



Supplement of

Characterizing a decametre-scale granitic reservoir using ground-penetrating radar and seismic methods

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Supplementary material for Doetsch et al., "Characterizing a decameter-scale granitic reservoir using GPR and seismic methods"

S1. Anisotropy inversion

The basis is the Thomsen's anisotropy formula for weak anisotropy (Thomsen, 1986)

(1)
$$v_p \left(v_p^{\min}, \varepsilon, \delta, \theta^0 \right) = v_p^{\min} \left(1 + \delta \sin^2 \theta \cos^2 \theta + \varepsilon \sin^4 \theta \right),$$

where v_p^{\min} is the minimum P wave velocity, δ and ε are the Thomsen anisotropy parameters and $\theta = \theta^r - \theta^0$ is the angle between the seismic ray (θ^r) and the direction of minimum velocity (θ^0). For travel time inversions it is convenient to work with slowness s_p instead of velocity v_p . The corresponding equation is

(2)
$$s_p\left(s_p^{\min},\varepsilon,\delta,\theta^0\right) = s_p^{\min}\left(1+\delta\sin^2\theta\cos^2\theta+\varepsilon\sin^4\theta\right)^{-1}$$

In the following equations the subscript p is omitted. The travel time from source i to receiver j is

$$(3) t_{ij} = \sum_k s_k l_k ,$$

where s_k and l_k are the slownesses and ray lengths in the *k*th cell along the ray path connecting source *i* and receiver *j*. In the isotropic case, the partial derivatives contained in the Jacobian matrix are

(4)
$$\frac{\partial t_{ij}}{\partial s_k} = l_k \; .$$

In case of weak anisotropy, the corresponding derivatives are

(5)
$$\frac{\partial t_{ij}}{\partial s_k^{\min}} = l_k a^{-1} ,$$

(6)
$$\frac{\partial t_{ij}}{\partial \varepsilon_k} = -l_k s_k^{\min} a^{-2} \sin^4 \theta ,$$

(7)
$$\frac{\partial t_{ij}}{\partial \delta_k} = -l_k s_k^{\min} a^{-2} \sin^2 \theta \cos^2 \theta \text{ , and}$$

(8)
$$\frac{\partial t_{ij}}{\partial \theta_k^0} = l_k s_k^{\min} a^{-2} \left(4\varepsilon \sin^3 \theta \cos \theta + 2\delta \sin \theta \cos \theta \left[\cos^2 \theta - \sin^2 \theta \right] \right).$$

with $a = (1 + \delta \sin^2 \theta \cos^2 \theta + \varepsilon \sin^4 \theta).$

Supposed that the ray geometry is known (e.g., computed with an isotropic ray tracer), implementation of weak anisotropy is merely a matter of adding three more columns per inversion cell to the Jacobian matrix. The isotropic case can be considered as a special case of anisotropy, where the derivatives with respect to ε , δ and θ are set to zero.

S2. Extra GPR Figures

Figure 6 in the main manuscript shows the unmigrated GPR data recorded from the AU tunnel and Figure 7 the migrated data acquired from the VE tunnel. Here, we show the migrated data from the AU tunnel and the unmigrated data from the VE tunnel.



Figure S1: Fully processed and migrated GPR data acquired from the AU tunnel.



Figure S2: GPR reflection data measured from the VE tunnel in the N-S plane, looking East. These data are processed up to step 8 (Section 3.1.2) but not migrated.

References

Thomsen, L. (1986). Weak Elastic-Anisotropy. Geophysics 51(10): 1954-1966.