



Ground-penetrating radar signature of Quaternary faulting: a study from the Mt. Pollino region, southern Apennines, Italy

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Abstract. With the aim of unveiling evidence of Late Quaternary faulting, a series of ground-penetrating radar (GPR) profiles were acquired across the southern portion of the Fosso della Valle–Campotenesse normal fault (VCT), located at the Campotenesse continental basin (Mt. Pollino region) in the southern Apennines active extensional belt (Italy). A set of 49 GPR profiles, traced nearly perpendicular to this normal fault, was acquired using 300 and 500 MHz antennas and carefully processed through a customized workflow. The data interpretation allowed us to reconstruct a pseudo-3D model depicting the boundary between the Mesozoic bedrock and the sedimentary fill of the basin, which were in close proximity to the fault. Once the GPR signature of faulting was reviewed and defined, we interpret near-surface alluvial and colluvial sediments dislocated by a set of conjugate (W- and E-dipping) discontinuities that penetrate inside the underlying Triassic dolostones. Close to the contact between the continental deposits and the bedrock, some buried scarps which offset wedge-shaped deposits are interpreted as coseismic ruptures, subsequently sealed by later deposits. Our pseudo-3D GPR dataset represented a good trade-off between a dense 3D-GPR volume and conventional 2D data, which normally requires a higher degree of subjectivity during the interpretation. We have thus reconstructed a reliable subsurface fault pattern, discriminating master faults and a series of secondary splays. This contribution better characterizes active Quaternary faults in an area which falls within the Pollino seismic gap and is considered prone to severe surface faulting. Our results encourage further research at the

study site, whilst we also recommend our workflow for similar regions characterized by high seismic hazard and scarcity of near-surface geophysical data.

1 Introduction

A “seismic gap” is an area surrounded by regions struck by large earthquakes in historical or recent times. Such earthquake-free areas are characterized by the presence of seismogenic faults, whose past activity or possible quiescence is inferred on the basis of morpho-structural and/or paleoseismological data. The “seismic gaps” (McCann et al., 1979) show an apparent lack of historical seismicity but are candidate regions for the occurrence of large earthquakes in the near future (Mogi, 1979; Plafker and Galloway, 1989; Cinti et al., 1997; Galadini and Galli, 2003). A recent example of a seismic gap “filled” by strong earthquakes is the Mt. Vettore area (central Apennines) during the 2016–2017 seismic sequence (Chiaraluce et al., 2017; Barchi et al., 2021 and references therein). Following the extensive coseismic ruptures mainly generated by the $M_w = 6.5$ “Norcia” mainshock (Villani et al., 2018; Brozzetti et al., 2019; Testa et al., 2019), this area is currently an ideal laboratory for many conventional and innovative geoscience disciplines and applications (e.g., Xu et al., 2017; Porreca et al., 2018; Brozzetti et al., 2020; Cirillo, 2020; Ferrario et al., 2018; Ercoli et al., 2020; Michele et al., 2020; Porreca et al., 2020; Ferrarini et al., 2021; Pucci et al., 2021;

Sapia et al., 2021; Villani et al., 2021). In fact, although the area is characterized by a complex alignment of normal faults, no important earthquakes were reported over the past ~ 1500 years before this seismic crisis (Cinti et al., 2019; Galli et al., 2019, 2020). Former geological and geomorphological studies suggested the possible occurrence of Quaternary faulting (Calamita et al., 1992; Brozzetti and Lavecchia, 1994; Barchi et al., 2000), which was successively confirmed by paleoseismological (Galadini and Galli, 2003) and GPR surveying (Ercoli et al., 2013a, 2014). These studies revealed the occurrence of strong paleo-earthquakes and suggested that the Mt. Vettore master fault was “silent” but prone to causing future seismic events. However, invasive trenching due to complex logistics, environmental restrictions, high costs, and the need for authorizations cannot be applied systematically in many locations. Thus, Quaternary faults and associated basins characterized by an unsatisfactory definition of the seismotectonic framework have to be investigated with geophysical techniques. For all the above noted reasons, and since the Mt. Vettore case may represent an analogue of similar seismic gaps, the southernmost Apennines were studied through a dedicated research programme (Agreement INGV-DPC 2012–2013 and 2014–2015, Project S1 – Base-knowledge improvement for assessing the seismogenic potential of Italy, Brozzetti et al., 2015; Pauselli et al., 2015) aiming to improve the knowledge base of seismogenic structures. In the research, focused also on the Calabrian region (southern Italy) during the 2012–2015 period, structural geology, geophysical, and paleoseismological data were successfully acquired on the Mt. Pollino and Castrovillari fault systems (northern Calabria), providing evidence of Late Quaternary activity (Ercoli et al., 2013b; Cinti et al., 2015a; Ercoli et al., 2015; Brozzetti et al., 2017b). This area, which is considered one of the most important seismic gaps in southern Italy, extends from the Mercure basin to the north until Campotenese basin and Castrovillari plain to the south, all characterized by Late Quaternary continental syn-tectonic sedimentation (Fig. 1a–c).

The paleoseismological trenching and radiocarbon dating document in the region the occurrence of paleo-earthquakes with $6.5 < M_w < 7.0$ and a recurrence time interval of ~ 1200 years (Cinti et al., 1997, 2002, 2015a, b; Michetti et al., 1997, 2000). But this high magnitude interval contrasts with the historical seismicity records, reporting a single significant M_w 5.2 event that occurred in 1693 (Tertuliani and Cucci, 2014). In the last three decades instrumental seismicity recorded only two moderate seismic activities climaxed in the M_w 5.6 Mercure (9 September 1998) and M_w 5.2 Mormanno (25 October 2012) earthquakes. The latter occurred during a long-lasting seismic activity spanning the period 2010–2014, which included more than 6000 events of $M_w > 1$ and activated at least three individual seismogenic sources (Passarelli et al., 2015; Brozzetti et al., 2017a, Fig. 1b). The gap between the low energy release, observed during the instrumented seismic sequences, and the high seis-

mic potential estimated for the Quaternary faults raised the question of whether even stronger earthquakes had shaken and could shake the area in the future. A recent and detailed parameterization of the Fosso della Valle–Campotenese fault (VCT in Fig. 1c) based on geo-structural and geomorphological mapping (Brozzetti et al., 2017a) as well as on seismological evidence (Totaro et al., 2014, 2015; Cirillo et al., 2021), assesses a surface length of 15 km and a depth of at least ~ 10 km: the potential rupture area is estimated as likely to produce $M_w > 6.0$ earthquakes. As testified by earthquakes of the last century, such magnitudes in the Apennines extensional belt generally produce coseismic surface faulting (e.g., Oddone, 1915; Pantosti and Valensise, 1990; Boncio et al., 2010; Brozzetti et al., 2019). However, Quaternary faulting for the VCT structure is currently unclear, but geological and morpho-structural data suggest this fault has played an important role in determining the geometry and the recent sedimentary evolution of the basin.

The Campotenese basin and its VCT boundary fault is an example that summarizes the aforementioned issues: (1) lack of availability of paleoseismological data as the basin is entirely located within the Mt. Pollino National Park, thus requiring prior authorization from authorities; (2) lack of availability of publicly accessible geophysical data; (3) no fresh recent surface displacements within the Holocene deposits having been observed along its trace. For all these reasons, the VCT represents an ideal case study on which to test our working method.

We have conducted an explorative GPR field campaign across a VCT sector, suggested by discontinuous and smooth geomorphic scarps, as a screening tool for the definition of its possible Quaternary displacement history. The objectives of the paper are to (i) review and describe geophysical characteristics associated with a peculiar GPR signature of faulting, and propose a reference methodological workflow; (ii) specifically check the efficiency of GPR prospecting to locate the VCT fault and to depict its subsurface pattern and spatial continuity at shallow depth; (iii) provide new data to eventually relate the occurrence of $M_w > 6.0$ seismic events; (iv) pave the way for other local geophysical studies and identify interesting sites for future ground-truthing and/or paleoseismological trenching; (v) to be directly applicable to and have an impact on the planning of future mitigation strategies for the reduction of surface faulting risk in the nearby urbanized areas.

2 Tectonic setting and seismicity

The Campotenese continental basin is located in the northernmost Calabria region southwest of the Mt. Pollino calcareous massif (southern Italy, Fig. 1). The bedrock of the basin consists of shallow water dolostones and limestones, Late Triassic to Middle Miocene in age, belonging to the Verbicaro tectonic unit (Ogniben, 1969; Amodio Morelli et

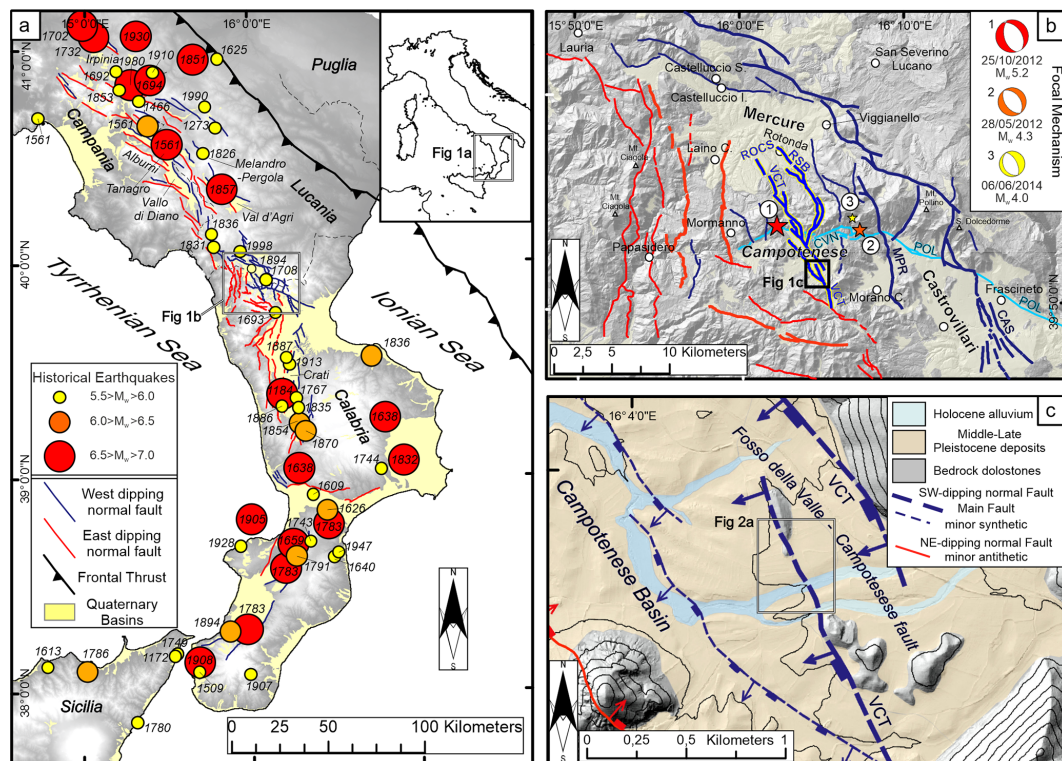


Figure 1. Location maps of the study site (DTM sources: TINITALY by Tarquini et al., 2012, and by Regione Calabria – <http://geoportale.regione.calabria.it/opendata>, last access: 11 June 2021, under license IODL 2.0. – <https://www.dati.gov.it/iodl/2.0/>, last access: 11 June 2021): (a) image illustrating the southern Italian peninsula with the regional faults pattern and the historical strong earthquakes (Rovida et al., 2020); (b) map showing the studied region with local faults (modified after Brozzetti et al., 2017a), and epicenters (stars) and focal mechanisms of the mainshocks of the 2012–2014 seismic activity (Scognamiglio et al., 2006); (c) location of the GPR survey area within the Campotenese Quaternary basin crossing the Fosso della Valle–Campotenese (VCT) fault.

al., 1976). It is generally referred as to the western edge of the “Apenninic Platform”, a thick (>4 km) carbonate shelf that underwent compression during the Middle–Late Miocene times and was translated over an eastern basinal domain (Lagronegro–Molise basin; Patacca and Scandone, 2007; Vezzani et al., 2010, and references therein). From the bottom to the top, the bedrock succession includes late Triassic dolostones, Cretaceous limestones, and Paleocene–Lower Miocene calcarenites cross-cut by the pillow lava basalts belonging to Liguride units of the northern sector of the Calabrian arc (Quitow, 1935; Grandjaquet and Grandjaquet, 1962; Amodio Morelli et al., 1976; Ghisetti and Vezzani, 1983; Iannace et al., 2004, 2005 and 2007; Liberi et al., 2006; Filice et al., 2013, 2015; Tangari et al., 2018).

The origin of the Campotenese basin, however, is related to a set of NW–SE-striking extensional faults which, during the Middle–Late Pleistocene, displaced the contractional tectonic pile, favoring the deposition of alluvial and lacustrine sediments in a subsiding intra-mountain depression (Servizio Geologico d’Italia, 1970). This set of conjugate SW- and NE-dipping normal faults represents the local expression of the Quaternary extensional belt that develops all along the Ital-

ian peninsula, nearly parallel to the axial zone of the Apennines, from northern Tuscany to the Calabrian Arc (Brozzetti, 2011). North of Campotenese (Lucania and southern Campania), the Apennine extensional belt includes several continental basins and their boundary faults, such as the Irpinia, Vallo di Diano, Tanagro, Melandro–Pergola, and Val d’Agri (Ascione et al., 1992; Maschio et al., 2005; Amicucci et al., 2008; Villani and Pierdominici, 2010; Brozzetti, 2011; Filice and Seeber, 2019; Bello et al., 2021). To the south, it continues with the Crati graben that dissects the northern sector of the Calabrian Arc (Tortorici et al., 1995; Brozzetti et al., 2012, 2017b).

On the regional scale, the Quaternary normal fault array controls the release of major seismicity, as suggested by the distribution of supra-crustal instrumental earthquakes (INGV, 2020; ISIDE, 2007), and of the strongest historical events (Fig. 1a, Tertulliani and Cucci, 2014; Rovida et al., 2020). The recent seismic activity as well as paleoseismological investigations claim that most of the faults bounding the Quaternary basins are seismogenic and therefore enable, in some cases, major past earthquakes to be associated with specific structures (e.g., Pantosti and Valensise,

1990; Cello et al., 2003; Spina et al., 2009; Brozzetti et al., 2009; Villani and Pierdominici, 2010). These same studies highlight that the kinematics of the Quaternary faults and the focal mechanisms of the major earthquakes are mutually consistent and are mainly compatible with an SW–NE direction of extension (RCMT and TDMT databases by Pondrelli, 2006, and Scogliamiglio et al., 2006). Other authors have recognized oblique normal–lateral fault kinematics in the surrounding regions (e.g., Rossano and Sybaris faults, Galadini et al., 2001; Cinti et al., 2015b).

The fault investigated in this work has been pointed out in more detail by Brozzetti et al. (2017a) in the frame of a larger study focussed on the Quaternary and active faults at the Calabrian–Lucanian boundary (Fig. 1a). In the region, three main sets of normal faults, with prevailing dip-slip kinematics, have been mapped: a western one, consisting of E- to NNE-dipping faults (red lines in Fig. 1b), and two other main sets of W- to SW-dipping fault segments (dark-blue and blue lines in Fig. 1b). The Rotonda–Campotenese set (ROCS) is a right-stepping en échelon master fault developed for a total length of 15 km with an average N160E strike (blue, yellow rimmed lines in Fig. 1b). ROCS is composed of two fault segments: (i) the westernmost Fosso della Valle–Campotenese fault (VCT), which extends from the southern border of the Mercure basin to the SW boundary of the Campotenese basin, and (ii) the Rotonda–Sambucoso fault (RSB), which branches out from the VCT segment in the central part of the ROCS. In the northern sector, the two segments are averagely spaced ~ 2.5 km at the surface and linked at a depth of ~ 9 – 10 km (Cirillo et al., 2021), cross-cutting the middle-Pleistocene \sim E–W-striking Cozzo Vardo–Cozzo Nisco fault (CVN, light-blue line in Fig. 1b). Along the east side of the Campotenese basin, the VCT is generally buried by Holocene deposits, but its location can be inferred based on stratigraphic observations and geomorphic features, such as sharp ridge fronts, linear scarps, and slope breaks. The VCT controls the distribution and thickness of the clastic fill basin (Middle Pleistocene–Holocene in age, according to Schiattarella et al., 1994) that reaches the maximum thickness (~ 30 m) in the western sector (VCT hanging wall; see borehole stratigraphy at <http://sgi2.isprambiente.it/mapviewer/>, last access: 11 June 2021). The spatial relationships, at surface and depth, between the Quaternary fault segments and the hypocenters of the re-located 2010–2014 seismic events (Totaro et al., 2015; Brozzetti et al., 2017a; Napolitano et al., 2020, 2021; Pastori et al., 2021) suggest that the VCT is a good candidate as a seismogenic source for the M_w 5.2 (25 October 2012) Mormanno earthquake, as well as for strong paleo-events.

3 Methodology

Ground-penetrating radar (GPR) is a high-resolution geophysical method able to provide detailed images of the shal-

low sub-surface. This methodology is based on the recording of EM reflections, with operative frequencies for geoscience applications generally between 10 and 1000 MHz, depending on the transmitting and receiving antennae. The GPR reflections rise from dielectric permittivity contrasts between the subsurface targets and the surrounding media, which in geological and archeological applications typically correspond to geo-lithological changes or water content variations (Jol, 2009). In low-conductivity materials (“low-loss”), the maximum investigation depth is generally within a few tens of meters (Davis and Annan, 1989). The latter is, however, also controlled by the electrical conductivity, which for high values causes radar signal attenuation (Annan, 2001). The reflections are recorded as a function of the two-way-travel time (TWT) propagation and displayed as a 1D GPR trace. Several GPR traces displayed along a transect build up a radar profile or “radargram”, that is the 2D representation of the GPR reflections, more commonly identified as the conventional GPR output. A GPR dataset may also be provided as a 3D volume, which has been common for 25+ years in research applications and has recently become more widespread due to a wider diffusion of commercial GPR instruments equipped with arrays of antennae. The GPR is used in many research and applied fields, such as geological, sedimentological, geomorphic, and hydrogeological applications (Bristow and Jol, 2003; Jol, 2009), and also in archeological and engineering studies (Conyers, 2016; Daniels, 2004; Goodman and Piro, 2013; Utsi, 2017). In an active tectonic context, several 2D and 3D GPR studies have already imaged buried tectonic structures. These studies have shown geophysical images of faulting, supporting and/or extending observations on outcrops, boreholes, and trench data and contributed to base knowledge of seismogenic structures as well as to the seismic hazard assessment of several regions around the world. Among the pioneers, we can mention Benson (1995), Smith and Jol (1995), Busby and Merritt (1999), Cai et al. (1996), and Liner and Liner (1997), and in the successive 20 years, other 2D GPR studies were achieved across several faults worldwide (Audru et al., 2001; Demanet et al., 2001; Overgaard and Jakobsen, 2001; Bano et al., 2002; Liberty et al., 2003; Reiss et al., 2003; Slater and Niemi, 2003; Malik et al., 2007; Wallace et al., 2010; Yalciner et al., 2013; Imposa et al., 2015; Anchuela et al., 2016; Nobes et al., 2016; Matos et al., 2017; Pousse-Beltran et al., 2018; Zajc et al., 2018; Zhang et al., 2019 and Shaikh et al., 2020). In Italy, only a few GPR studies are currently available across normal faults (e.g., Salvi et al., 2003; Jewell and Bristow, 2006; Pauselli et al., 2010; Roberts et al., 2010; Ercoli et al., 2013a, 2014; Bubeck et al., 2015; Cinti et al., 2015). Over time, 2D GPR acquisitions were flanked by an increasing number of pseudo-3D or full-3D GPR studies (Grasmueck et al., 2005). Grasmueck (1996) traced the future path of three-dimensional GPR applications, providing a dense 3D GPR volume to image fractures in a Swiss quarry. The study opened the possibility of three-dimensional GPR

imaging of subsurface geological structures. Successive studies extended the approach to characterize active faults in different tectonic regimes combining 2D and pseudo-3D GPR surveys (e.g., Gross et al., 2002, 2003, 2004; Green et al., 2003; Tronicke et al., 2006; McClymont et al., 2008, 2009, 2010; Vanneste et al., 2008; Christie et al., 2009; Carpentier et al., 2012a, b; Malik et al., 2012; Brandes et al., 2018). A review of the near-surface GPR faulting studies suggests some reflection characteristics as possible indicators for the detection of subsurface fractures and faults (e.g., Smith and Jol, 1995; Liner and Liner, 1997; Reiss et al., 2003; Gross et al., 2004; McClymont et al., 2008, 2010 and Bubeck et al., 2015). Among these, sharp lateral reflectivity variations, interruptions of the reflections, and the presence of hyperbolic diffractions are considered convincing evidence, as shown also by numerical simulations (Ercoli et al., 2013a; Bricheva et al., 2021). In addition, we have accounted for additional GPR indicators identified for Quaternary faulting in similar environments (Ercoli et al., 2013a, b; 2014; 2015), which are linked to the geometry of stratigraphic deposits across fault zones: (i) reflections of abrupt truncating and offsetting along sub-vertical discontinuities (especially in the case of a normal fault); (ii) reflection packages thickening as they approach the fault strands; (iii) abrupt lateral dip variation of the reflections; (iv) peculiar reflection package geometries, with contorted reflection patterns resembling “colluvial wedges”, which McCaillin (2009) defines as deposit due to “subsidence and sedimentation of the hanging wall and erosion of the morphological scarp in the footwall”; (v) localized strong GPR signal attenuation due to the presence of conductive media within the main fault zone.

Based on the research and criteria reviewed above, we carried out a near-surface interpretation of faulting based on the co-existence of most of these features along several adjacent analyzed GPR profiles. These conditions strengthen the interpretation of each profile and aid in highlighting the spatial continuity of the interpreted structures over linear distances of at least many tens, or hundreds, of meters.

3.1 GPR and GNSS survey

Three different geophysical field campaigns were carried out during 2014–2015, and a dataset of 49 GPR profiles was acquired in the southern sector of the ROCS across the VCT fault segment (Fig. 1b–c). This GPR dataset covered a buffer zone of ~ 400 m and ~ 200 m respectively along and across the fault strike (area of ~ 8 Ha), for a total linear length of the GPR profiles of about 4100 m collected using a common offset (CO) configuration (Fig. 2).

We used a Zond 12e GPR system equipped with 300 and 500 MHz antennae. The lower-frequency antennae was ultimately preferred and considered the best trade-off between maximum resolution and achievable signal penetration (in our case ~ 4 m) concerning the surveyed materials and wanted subsurface structures. The GPR was equipped

with an odometer wheel to measure the radar profiles' length and with a Topcon GR-5 Global Navigation Satellite System (GNSS) receiver to achieve accurate positioning of GPR traces and profile. Considering the scarcity of obstacles across the survey site and the good satellite coverage, we opted for network real-time kinematic positioning (NRTK, connected to the NETGEO network), measuring coordinates and elevations with centimeter accuracy and storing them directly within the SEG-Y GPR files.

Three datasets were acquired after preliminary fieldwork and collection of geological-structural data at the surface, which allowed us to infer the possible location of the fault trace. The average NE–SW direction of the GPR lines was initially planned with the primary purpose of intersecting the VCT fault roughly perpendicularly to its SW–NE strike, as reported in the literature and visible from surface evidence. This solution theoretically allows a more reliable interpretation of the investigated structure by reducing the effect of the apparent dip direction and dip angle of both stratifications and faults.

The acquisitions carried out in 2014, first resulted in 12 SW–NE GPR profiles collected in the southern sector of the basin (CMT light-blue lines in Fig. 2a), which was a flat land characterized by Quaternary alluvium. The second acquisition encompassed four additional radar profiles collected in the same area, and another nine radar profiles progressively moving to the north, which were collected in the central sector with slightly different and converging orientations (CMT green lines Fig. 2a). This solution was pursued for two main reasons: (1) to avoid directly surveying the outcropping dolostone, only partially crossed with two northernmost profiles, and thus focussing only on the sedimentary cover, representing our target for possible Quaternary faulting; (2) to optimize, through a preliminary GPR data interpretation, the future acquisition schemes by figuring out the dip direction of the buried geologic structures of interest. In fact, similarly to the interpretation of reflection seismic profiles, the “apparent dip” of reflections in bidimensional radar profiles should be considered to achieve a reliable 3D conceptual model.

In order to intercept several possible buried faults and fault-related structures as well as to fully image the local structural setting, the successive 2015 acquisition crossed part of the Triassic dolostones ridge with longer GPR profiles. The GPR profiles collected during the second 2014 campaign (close to h1 and h2) already revealed a considerable difference in GPR reflectivity between the unconsolidated deposits and layered and fractured Mesozoic lithotypes (Gafarov et al., 2018). Therefore, two new datasets of 24 parallel GPR radar profiles (CMT dark-blue sets of lines in Fig. 2a, north “n” and south “s”) were extended in NNE–SSW and NE–SW directions, respectively, crossing h1 for several tens of meters (max profile length ~ 220 m) throughout the basin. The GPR profiles were recorded using a trace step of 0.05 m and a profile inter-distance of 25 m for dataset “n” and 10 m for dataset “s”, respectively. A detailed sum-

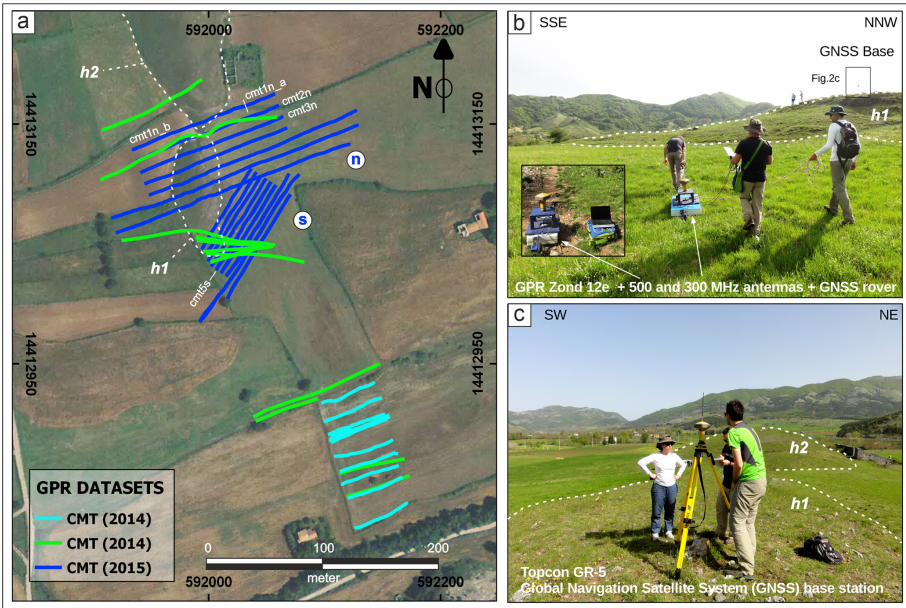


Figure 2. GPR acquisition campaigns: (a) GPR profiles collected at the study site Campotenese (“cmt”, where “n” and “s” stand for north and south, “h1” and “h2” indicate the two dolostone hills outcropping in the basin) during the three field visits (aerial image source: Regione Calabria – <http://geoportale.regione.calabria.it/opendata>, last access: 11 June 2021, under license IODL 2.0. – <https://www.dati.gov.it/iodl/2.0/>, last access: 11 June 2021); (b) acquisition phase using the 300 and 500 MHz antennae (in the insert) and GNSS receivers used for accurate data positioning; (c) GNSS base station set up during the fieldwork.

Table 1. Main information and GPR parameters used during the data collection (* the time window was adapted depending on the surveyed area).

GPR survey information and parameters		
Antenna frequency (MHz)	300 (preferred)	500
Number of acquired profiles	45	4
Total profile length (m)	3789.5 of 4153	363.5 of 4153
Profile distance (m)	10 and 25 (in g1 and g2)	not regular
Traces distance (m)	0.05	0.02
Number of samples	1024	512
Time window (ns)	300–200*	200–100*

mary of the acquisition parameters used for the GPR surveys is reported in Table 1. For these two datasets, the profile spacing and positioning are more regular and accurate, thanks to preparatory transects planning using a GIS project. Thus, we later staked out their initial and final positions during the fieldwork through the differential Global Navigation Satellite System (GNSS). The results of the accurate GPR trace positioning achieved during the GNSS campaigns were also used for GPR data processing, visualization, and interpretation.

3.2 GPR data processing and results

The processing sequence was customized after testing several workflows and parameters. We aimed to remove random and coherent (e.g., ringing) noise and enhance the data quality to better visualize the geometry of the buried reflections

and their discontinuity in signal amplitude and phase. The first step was an accurate quality control (QC) of the profile coordinates and topographic profiles. Despite the generally favorable environmental conditions (e.g., good satellite coverage, no forested areas) of the site for a GNSS survey, some measurements occasionally suffered a degradation of positional accuracy (e.g., temporary scarce satellite coverage or poor communication via Network Transport of RTCM via Internet Protocol – Ntrip). For some traces therefore the coordinates and elevation field records that were outliers (Fig. 3a) were corrected using various strategies (e.g., replacement, interpolation, or smoothing, Fig. 3b).

We have also compared our measurements with topographic transects extracted from 10 m and 5 m resolution digital terrain models (DTMs) by Tarquini et al. (2012) and by Regione Calabria. Later on, we finally used a 1 m resolution DTM (Geoportale Nazionale, 2018; lidar data provided by Italian Ministero dell’Ambiente e della Tutela del Territorio e del Mare – MATTM) to double-check whether, despite the different scales of observation, the topographic profiles were comparable. Although the meter resolution of the DTM is unable to represent centimeter topographic variations, the comparison confirmed an excellent match of the topographic profiles at a meter scale, so that the DTM data were integrated to correct the GNSS-measured topography when the accuracy of GNSS recordings was excessively degraded. With the topographic profiles corrected, the raw GPR data (Fig. 3c, illustrating the profile cmt5s) were initially processed with

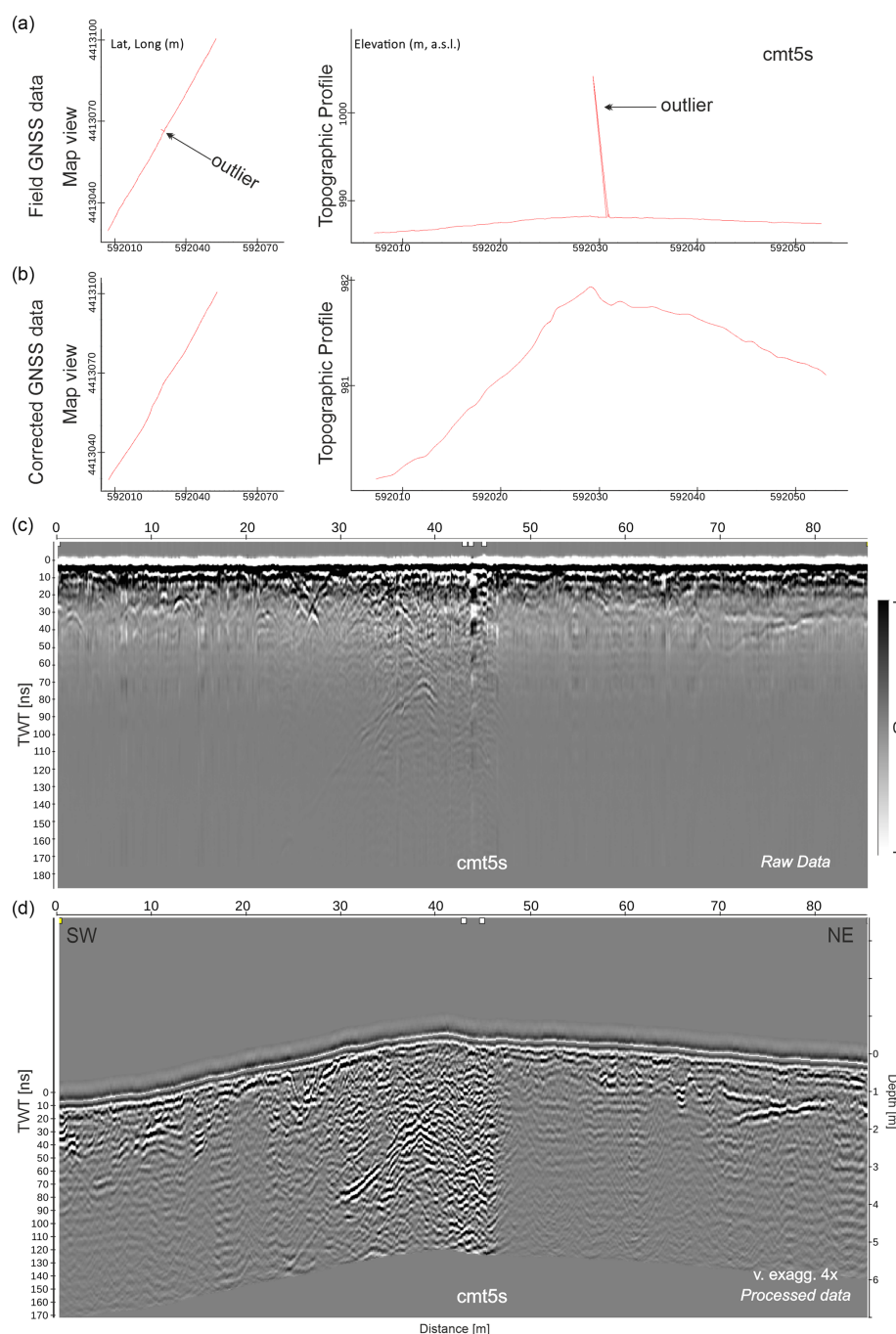


Figure 3. Topographic correction of GPR profiles: **(a)** example of accuracy degradation of GNSS data, displaying an outlier both in map view and in topographic profile, in which the positioning error is considerable; **(b)** GNSS coordinates and topographic profile after the correction; **(c)** raw GPR section displaying high reflectivity in the central sector; **(d)** example of full processed profile with topography displaying various reflection patterns encompassing dipping reflections and diffractions. Vertical exaggeration is 4.

the Prism software (Radar System, Inc., <http://www.radsys.lv/en/index/>, last access: 11 June 2021) using a basic processing sequence, to analyze the main characteristics of data and optimize a customized processing flow. The processing sequence was later improved through ReflexW software (<https://www.sandmeier-geo.de/reflexw.html>, last ac-

cess: 11 June 2021; see Table 2 for details on the processing algorithms and parameters). The workflow included a time-zero correction, dewow, amplitude recovery, velocity analysis, background removal, bandpass filtering, F-K filtering, 2D time migration, topographic correction, and time-to-depth conversion. The amplitude recovery was operated through a

“gain function” including a linear and an exponential coefficient ($g(t) = (1 + a \cdot t) \cdot e^{(b \cdot t)}$) to enhance the amplitude (reflectivity) contrasts as well as preserving the horizontal and vertical amplitude variations already visible in the raw data (Fig. 3a). This amplitude recovery function was used across all the profiles with slight customization depending on the datasets (details in Table 2). The entire processing flow was applied to all the available radar profiles, again with occasional filtering adaptations aiming to remove local pervasive signal ringing (e.g., due to low antennae–ground coupling). Particular care was dedicated to the migration process, whose algorithm was decided after extensive tests on several radar profiles to select the best migration strategy.

In fact, a very different reflectivity and maximum depth of penetration are visible in the data: it is more than 150 ns in the central sector, decreasing to 70–80 ns in the rest of the radar profiles (Fig. 3c): this fact suggests sharp lateral variations of subsurface media (Figs. 3d) and, possibly, of the velocity field. Thus, we have first tested a 1D time migration algorithm (Kirchhoff) by performing a migration velocity scan (MVS) analysis (Forte and Pipan, 2017) and inspecting the success of diffraction hyperbola collapse after migration. We have varied constant values of EM velocity, from a minimum of 0.06 up to 0.12 m ns^{−1}, with steps of 0.01 m ns^{−1}, to evaluate considerable variation in dielectric properties of surveyed media. The MVS is characterized by a higher velocity for the central sector of the GPR profiles which displays high reflectivity: Fig. 4 illustrates an example of the migration results obtained on the profile cmt1n_a, by using three constant values of average velocity. The profile in Fig. 4a shows the unmigrated version characterized by numerous hyperbolic and half-hyperbolic diffractions originated by single scatter points and wavy reflections (white arrows). In Fig. 4b we display the first test using $v = 0.07$ m ns^{−1}, showing overall good results, with slight under-migration at a few points mainly located within the shallower sediments (light-blue arrows). The hyperbolic diffractions are also nicely collapsed using higher velocity ($v = 0.09$ m ns^{−1}) as shown in Fig. 4c (dark-blue arrows), even if some imaging problems affect deeper reflections. The last migration scan test ($v = 0.11$ m ns^{−1}) displays a good result only in few profile sectors (dark-blue arrows), particularly localized within the sectors with high reflectivity, displaying an improved lateral reflection continuity. The rest of the radar profiles show generally poor imaging, particularly in the area characterized by strong attenuation, where the wavy reflection is over-migrated (red arrows indicating migration smiles, Fig. 4d).

The workflow therefore suggests a challenging imaging task due to velocity variation happening not only at depth but also laterally across the different media. This sharp change of reflectivity and velocity at a distance of about 13–14 m (Fig. 4d) represents a complex problem for the efficiency of 1D migration algorithms conventionally used for GPR imaging. Such considerations have lead to testing a 2D migration

algorithm, by creating and using a 2D velocity model obtained for each radar profile through a hyperbolic diffraction fitting tool (Fig. 5a). Single velocity points have been fitted for each area displaying hyperbolic diffractions, while in the remaining parts of the radar profiles we have arbitrarily included presumed velocity adaptation only to obtain a regular grid of points to spatially interpolate the 2D models. The 2D migrated radar profiles, in comparison to the 1D approach, resulted in improved imaging of GPR profiles, displaying a more accurate collapse of the hyperbolic diffractions into point sources and an improved relocation of dipping reflections, with a refinement of their geometry and an increase in their continuity. A good-quality imaging result is visible on the central sectors of radar profiles displaying strong reflectivity and reflections with improved continuity, but also many phase breaks and displacements. Despite steep topographic gradients, sharp lateral velocity variation and the reflection heterogeneity might cause imaging issues that need to be treated using more specific workflows (Lehmann and Green, 2000; Heincke et al., 2006; Goodman et al., 2007; Dujardin and Bano, 2013). We believe we have reached a good compromise for our purposes. In our case, a considerable improvement can be seen along the hill slope and flatter areas (profile cmt1n_a, Fig. 5b) which are of greatest interest for the study aimed at detecting possible earthquake ruptures within the Quaternary deposits. The improved imaging of reflection geometries is therefore fundamental for the interpretation and detection of geophysical signatures of faults.

A successive import of the processed SEG-Y data was performed in the seismic interpretation software Opend-Tect Pro v.6.4 (academic license courtesy of dGB Earth Science, <https://www.dgbes.com>, last access: 11 June 2021), which was used first for global QC of processing operations (correctness of topographic correction and datum plane, coordinate accuracy and matching, profile orientation and intersection) and for three-dimensional (3D) visualization of all the profiles (Fig. 6a). The three-dimensional GPR project was subsequently integrated with geological and structural maps, DTMs, and literature schemes (using a common coordinate reference system: WGS84 UTM Zone 33N, EPSG: 32633) in the Move suite software v. 2019.1 (academic license courtesy of Petroleum Experts, <https://www.petex.com/products/move-suite/>, last access: 11 June 2021) for GPR interpretation and model building. All the E- and W-dipping fault surfaces were created by interpolating the fault sticks picked on displaced reflections and correlated across adjacent radar profiles. In particular, we used the “surface geometry” tool to extract the properties of each single mesh building up the surfaces, and obtaining the “dip” and “dip azimuth” data. Subsequently, such values have been automatically saved in an attribute table, which can then be queried to reconstruct the “synthetic” stereonet.

Table 2. Customized flow and details of the parameters used during the processing of the GPR dataset.

Processing flow	Parameters (300 MHz)	Parameters (500 MHz)
Trace editing, coordinate editing, and corrections	–	–
Time-zero correction	–	–
Dewow (ns)	10	5
Amplitude recovery function: $g(t) = (1 + a \cdot t) \cdot e(b \cdot t)$	linear: 0.5 (2014) & 1.2 (2015) exponent: 0.15 (2014) & 0.6 (2015)	linear: 0.5 (2014) & 1.2 (2015) exponent: 0.15 (2014) & 0.6 (2015)
Velocity analysis	Diffraction hyperbola fitting	Diffraction hyperbola fitting
Background removal (ns)	Applied from 5 ns to end (computed on all the traces)	Applied from 5 ns to end (computed on all the traces)
Bandpass filter (MHz)	32/96/650/700	64/112/750/800
F-K filter	Customized	Customized
Time migration (2D Kirchhoff)	2D velocity models	2D velocity models
Topographic correction	GNSS/GIS elevations	GNSS/GIS elevations
Time–depth conversion (Quaternary deposits)	$v = 0.07 \text{ m ns}^{-1}$	$v = 0.07 \text{ m ns}^{-1}$

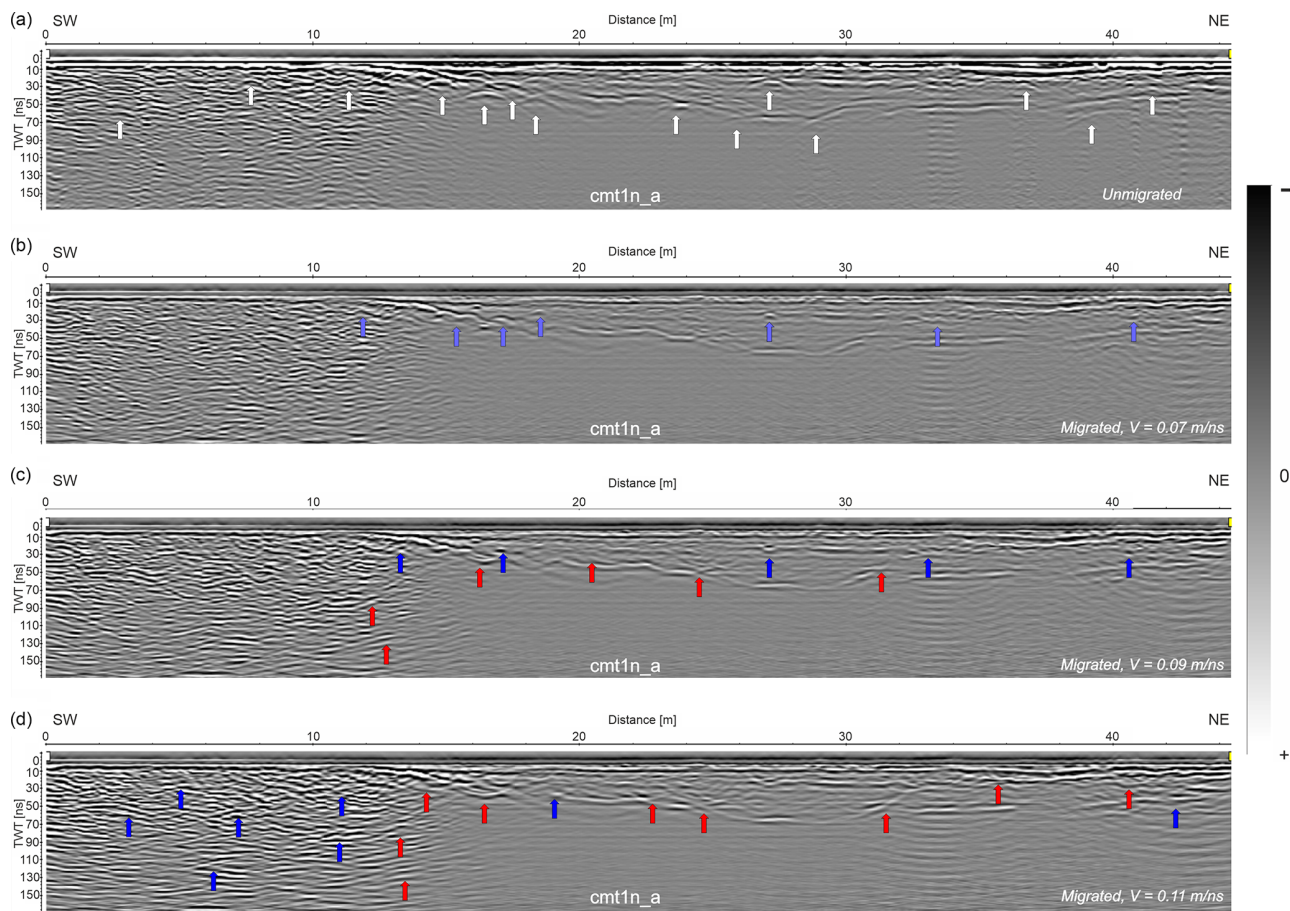


Figure 4. Migration tests performed during the GPR data processing: (a) unmigrated 2D GPR profile, 300 MHz antennae, displaying hyperbolic diffractions (white arrows); (b) migrated profile using a constant velocity $v = 0.07 \text{ m ns}^{-1}$, light-blue arrows indicate good diffractions collapse; (c) migration output obtained with a constant velocity $v = 0.09 \text{ m ns}^{-1}$, with dark-blue arrows suggesting good migration results (migration artifacts are shown by red arrows); (d) migration results using a constant velocity $v = 0.11 \text{ m ns}^{-1}$, with dark-blue arrows highlighting good hyperbolas collapse, particularly within the high reflective unit; red arrows highlight clear migration smiles.

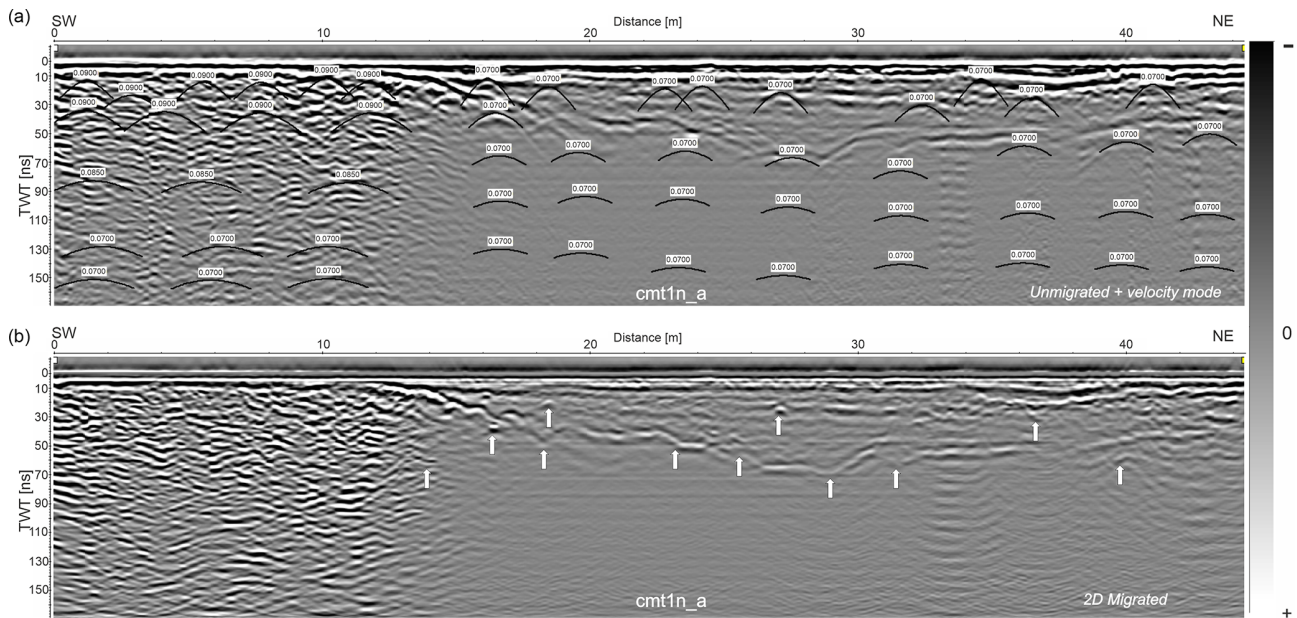


Figure 5. Example of 2D time-migration of radar profiles: **(a)** example of hyperbolic diffractions fitting used for 2D velocity model building; a constant velocity value (0.07 m ns^{-1}) was assumed in deeper no-diffraction areas for interpolation purposes; **(b)** 2D time-migration results, highlighting the good performance of the process, which collapsed the hyperbolic diffractions (white arrows) and restored reliable reflection geometry.

4 GPR data description and interpretation

The 3D MOVE project allowed us to extract 2D and 3D data visualizations to better figure out the relationships between the main reflections identified on the different GPR profiles (Fig. 6a). The workflow aimed to reconstruct and model the three-dimensional surfaces including both horizons and high-angle discontinuities.

A common feature on all the radar profiles is the strong reflectivity visible within their central sectors (e.g., profile cmt3n in Fig. 6b), which are characterized by an irregular and steep slope, particularly within the northern portion of the surveyed area. These sectors show deep GPR signal penetration due to the Triassic dolostones, which outcrop in the central and northern portions of the study area (Figs. 1c and 2a). The quality of the radar reflections and the remarkable depth reached ($\sim 6 \text{ m}$, Fig. 6b) suggest this rock type is an excellent dielectric medium (corresponding to higher-frequency content zone in the 2D spectrum of Fig. 6c). However, its reflection pattern is not spatially homogenous, being characterized by oblique and sub-parallel reflections. The latter are interpretable as dolostone beds of moderate ($25\text{--}30^\circ$) W and E “apparent” dips on the respective sides of the surveyed dolostone hills. In addition, these reflections are frequently cut and slightly displaced by apparent high-angle ($60\text{--}65^\circ$) phase discontinuities, highlighted by a dense hyperbolic diffraction pattern (radar profile cmt2n, Fig. 7a), suggesting intense fracturing and little faults displacing the dolostone (Fig. 7b). This radar signature was recorded not only in correspondence of

the outcropping carbonate but also in the transition slope areas covered just by a thin soil layer (Fig. 7b, c). In the southern side of h1, an outcrop with thin microbialitic laminae allows one to measure the attitude of the bedding (NNW dip, $\sim 30\text{--}35^\circ$ dip angle) as well as two sets of major and minor joints (SW and SE dip and dip angle of $\sim 40\text{--}45^\circ$, respectively) fitting with GPR reflections.

Apart from its internal heterogeneities, the GPR signature of the Triassic dolostones can be considered as a well-defined depositional facies (fc1) (Sangree and Widmier, 1979; Huggenberger, 1993; Beres et al., 1999; Bristow and Jol, 2003). A different radar signature fc2 is defined for the profile sectors on the sides of fc1. This second facies is characterized by prominent laterally continuous and sub-parallel reflections in the very shallow depth range ($<1 \text{ m}$, just beneath the direct arrivals), stratigraphically sealing underlying reflections 1–3 m deep: the latter are more discontinuous, wavy, and contorted, with moderate to low reflectivity and encompassing sparse diffraction hyperbolas (in unmigrated data, Fig. 7a). This reflection pattern onlaps onto a generally prominent wavy reflection (Fig. 7a, b), which typically marks the transition to strong signal attenuation deeper in the section.

The reflection package belonging to fc2 corresponds to the alluvial and colluvial deposits (Fig. 7b–d), outcropping on the sectors with flat topography, which represent the GPR profile sectors we have carefully inspected to find geophysical evidence of Quaternary faulting. A key layer for this research is the described prominent, wavy reflection, as it can

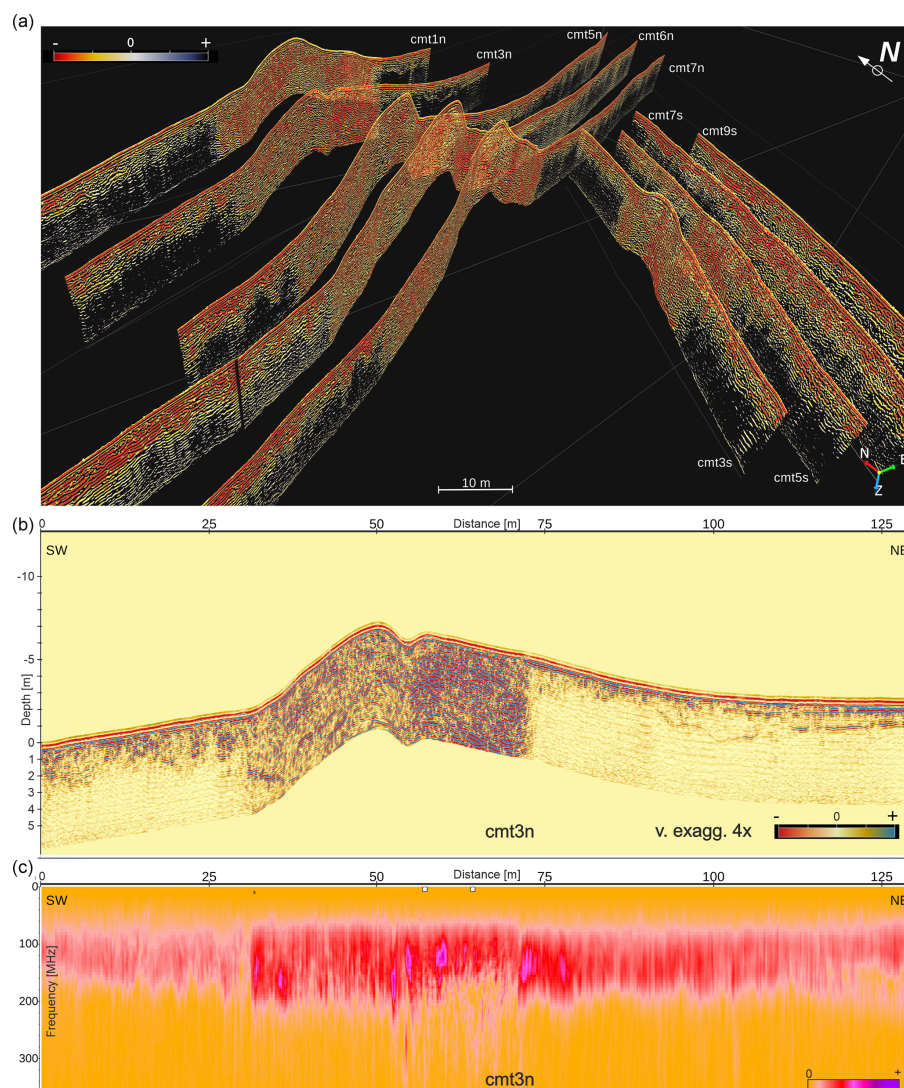


Figure 6. GPR data visualization: **(a)** fence diagram showing the three-dimensional location of some representative GPR profiles in the northern sector of the study site; **(b)** bidimensional GPR profile (cmt3n; see Fig. 2a for location) displaying the central high reflective sector and dipping reflections across the hill; **(c)** spatial variation of a 2D amplitude-frequency spectrum linked to variable physical properties of media along the profile cmt3n. Vertical exaggeration is 4.

be recognized in many radar profiles. The related interpretation is not straightforward in the absence of direct data (e.g., boreholes and/or paleoseismological trenches) or at least without additional geophysical data. A strong GPR reflection suggests significant variation of the dielectric constant between the two media so that most of the incident energy is reflected back to the receiver at the surface. This wave behavior is potentially explained by several geological models, such as (i) a high dielectric contrast that may be a result of a sharp soil moisture variation (Ercoli et al., 2018); (ii) a sharp erosional, stratigraphic, or tectonic boundary within heterogeneous deposits (Ercoli et al., 2015); or (iii) a contact between two considerably different lithologies, such as unconsolidated deposits laying above a bedrock substrate reflecting

back all (or almost all) the incident signal (e.g., Frigeri and Ercoli, 2020). In addition, the possible role of conductive deposits (e.g., high clay content) should not be discounted to explain the occurrence of strong attenuation. Several considerations are at the basis of the GPR data interpretation: (1) the available well logs show the Pleistocene–Holocene alluvium and colluvium layered above the carbonate bedrock at ~ 20 – 30 m depth (Brozzetti et al., 2017a), a greater depth than the strong GPR reflection. However, it should be observed that the area drilled is located ~ 2.5 km away on the northwesternmost sector, over the depcenter of the Campotene basin, whereas the studied GPR site is placed just on its eastern border, in proximity to emerged dolostone hills; (2) only terraced Middle Pleistocene silts and sands (Schi-

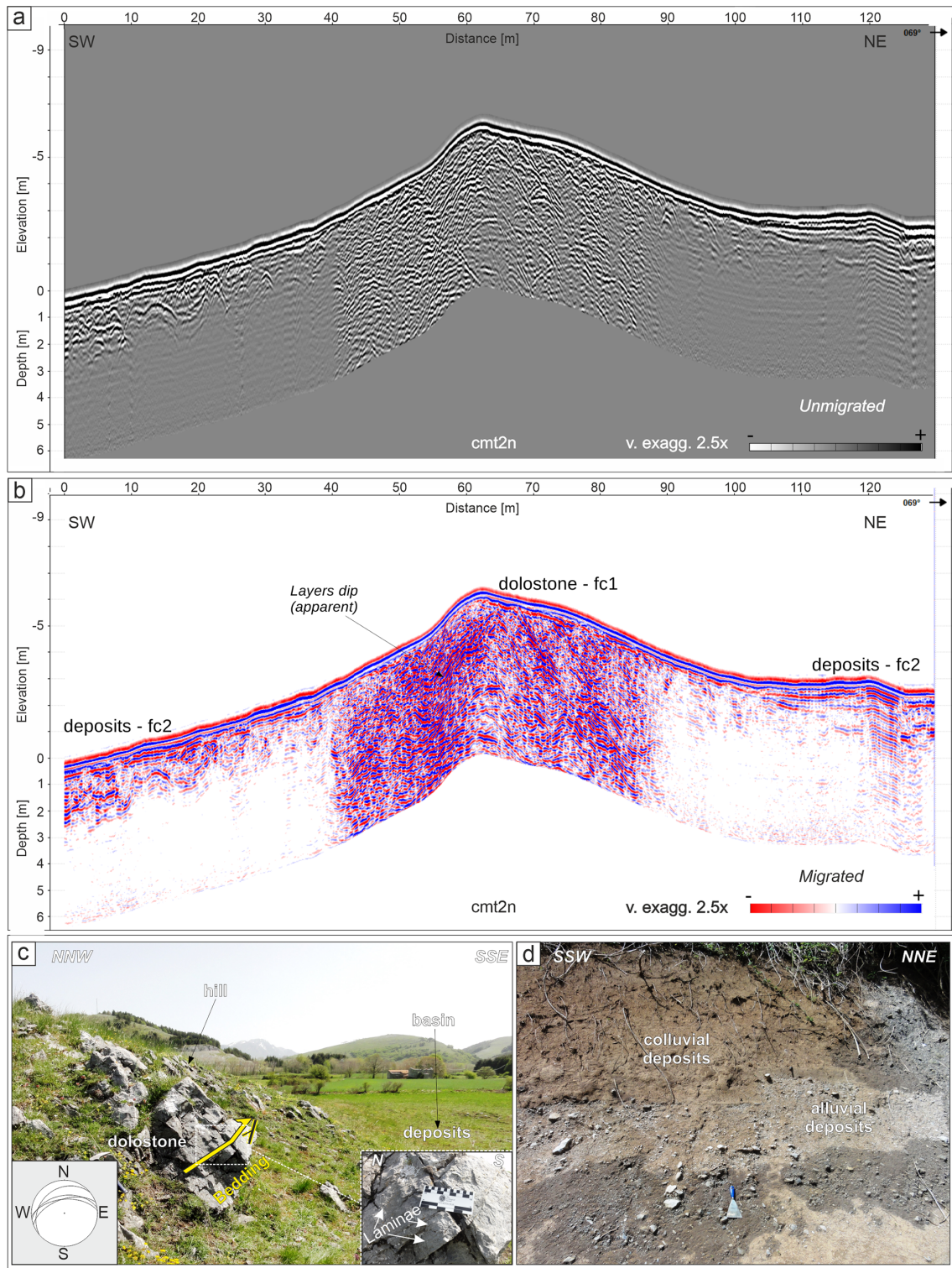


Figure 7. Correlation between GPR profiles and outcropping geology at the study site: **(a)** unmigrated 300 MHz profile (cmt2n; see Fig. 2b for location) displaying numerous hyperbolic diffractions; **(b)** migrated profile displaying the apparent dip associated with fractured dolostone formation (facies fc1) and Quaternary deposits in the attenuated sectors (GPR facies fc2); **(c)** Quaternary deposits of the basin (on the background) surrounding the Triassic dolostone formation outcropping on the hill h1. The yellow arrows indicate the bedding, such as the stereonet (left-side inset); the right-side inset shows details of the laminae visible on the site and nearby; **(d)** an example of Quaternary colluvial and alluvial deposits outcropping nearby the survey site. Vertical exaggeration is 2.5.

attarella et al., 1994) and slight coatings of Late Pleistocene colluvium (generally <2 m thick) are documented outcropping in the eastern sector of the basin (footwall of VCT fault) (see Fig. 7 in Brozzetti et al., 2017a); (3) the subsurface geometries highlighted by the prominent GPR reflection and underlying reflection pattern suggest a relatively thin layer of sedimentary deposits resting on a fractured substratum. Its top surface is progressively deepening towards the W, thus providing increased space for settling sediments and thus a gradual thickening of deposits is observed from E to W.

In light of the above considerations, we interpret the prominent, wavy GPR reflection as a buried top layer of carbonate (e.g., as observed by Bubeck et al., 2015), in our case represented by the Triassic dolostone formation. The latter is lying at a shallower depth (1–3 m) beneath shallow and poorly consolidated Quaternary deposits, across both sides of the surveyed hills. Thus, after picking such a prominent reflection event on all the radar profiles, the top of the bedrock surface was reconstructed as shown in Fig. 8a (colored surface). In this figure, we also display an overlay of a recent structural map of the basin (modified after Brozzetti et al., 2017a) reporting the area dissected by a set of en échelon fault splays to the west associated with the VTC segment. Thus, analyzing the geophysical characteristics of the prominent, wavy reflection in terms of a structural interpretation, the main peculiar characteristic is the clear “stepped” geometry of some sectors (Figs. 5b, 6b, 7b, 8b), namely breaks in its continuity associated with lateral sharp variations of depth (linked to sediment growth and onlaps). We also notice other geophysical features, which can be observed in the stratigraphy of overlying deposits (fc2): some reflections are semi-continuous to discontinuous (sharp variation in signal amplitude and phase) and display evident lateral variation of the dip angle.

These broken reflection packages present truncations (e.g., Smith and Jol, 1995), displacements, and hyperbolic diffraction events (insets of Fig. 8b1, b2). Such a peculiar GPR signature is therefore compatible with coseismic displacement due to Late Quaternary surface faulting events (Fig. 8b). Contorted reflections across the main discontinuities frequently show localized strong attenuation of the GPR signal (Fig. 8b). The attenuation might be linked to their high dip angle, causing a minor amount of energy to be reflected back to the antenna, but, more likely, due to the presence of conductive fine soils nearby faulted zones (e.g., circle 1 in Fig. 8b). These conditions can be linked to different depositional facies across fault zones (McClymont et al., 2010), e.g., including colluvial wedges (Reiss et al., 2003; Bubeck et al., 2015) or deposits deriving from degradation of fault scarps (detailed interpretation within the caption of Fig. 8b). Using all such stratigraphic evidence and geophysical markers of faulting, we have therefore interpreted and classified synthetic (W-dipping, blue) and antithetic (E-dipping, red) normal faulting events (Fig. 8b). During the interpretation process, the faults were picked using solid lines (fault sticks);

when the presence of geophysical markers of faulting were uncertain, a dashed fault segment was initially added, and then their possible connection among nearby GPR profiles was revised a second time.

The interpreted faults present a dip angle between 65–75° and variable amount of displacement (D), estimated by correlating the position of the top of the carbonate substratum in the footwall and hanging wall blocks (e.g., scheme summarized in the inset of Fig. 8b3). Considering the GPR profile of Fig. 8 as representative for the studied VCT sector, D is not exceeding ~ 1 m for the W-dipping splays within the Quaternary sediments (~ 0.5 m for the E-dipping splay). A displacement D of ~ 1.5 m was derived across the sharp boundary between the Triassic dolostone and the Quaternary deposits (easternmost fault in Fig. 8b), being interpreted as the main fault. This clear contact is characterized in all profiles by hyperbolic diffractions (in unmigrated data), variable dip angle, abrupt truncations, and sharp lateral variation of the reflectivity suggesting a wide fault zone (Figs. 3 to 9), controlling the above-mentioned Quaternary splays. By interpolating all the fault sticks placed in adjacent profiles, we have created the fault surfaces, which show a good degree of continuity from north to south (Fig. 9). For the studied sector of the VCT, we have reconstructed the tridimensional fault network and the geometry of the associated synsedimentary deposits at a metric scale of observation (Fig. 9).

5 Discussion

5.1 Inferences from subsurface 3D model

The perspective view of Fig. 9a shows a 3D structural scheme of the main tectonic lineaments at the basin scale displaying a NW–SE fault strike (modified after Brozzetti et al., 2017a) in relation to the GPR investigated area (white rectangle). Our GPR interpretation enriches many of the details of such a former structural scheme across the southern VCT segment. We highlight an en échelon system of two main SW and NE-dipping faults as well as an articulated set of extensional meso-faults within the Quaternary sediments. The high-angle GPR discontinuities identified in the study (e.g., Fig. 9b) show a considerable continuity in the NW–SE direction (accurate 3D structural reconstruction in Fig. 9c), dissecting not only Quaternary alluvial and colluvial deposits (except for the very shallow fc2 layers), but also deeper stratigraphic layers.

The reconstructed faults mark a horst–graben structure, mostly buried within the Campotenese basin, which locally emerges from the Quaternary deposits. In the investigated area it corresponds to a NNW–SSE elongated topographic high (h1 and h2 in Fig. 2a) made by the Triassic dolostone. This horst is bordered toward the W and towards the E by SW- and NE-dipping normal faults, respectively (Fig. 9b, c). In Fig. 9c, the fault set d1, together with its antithetic

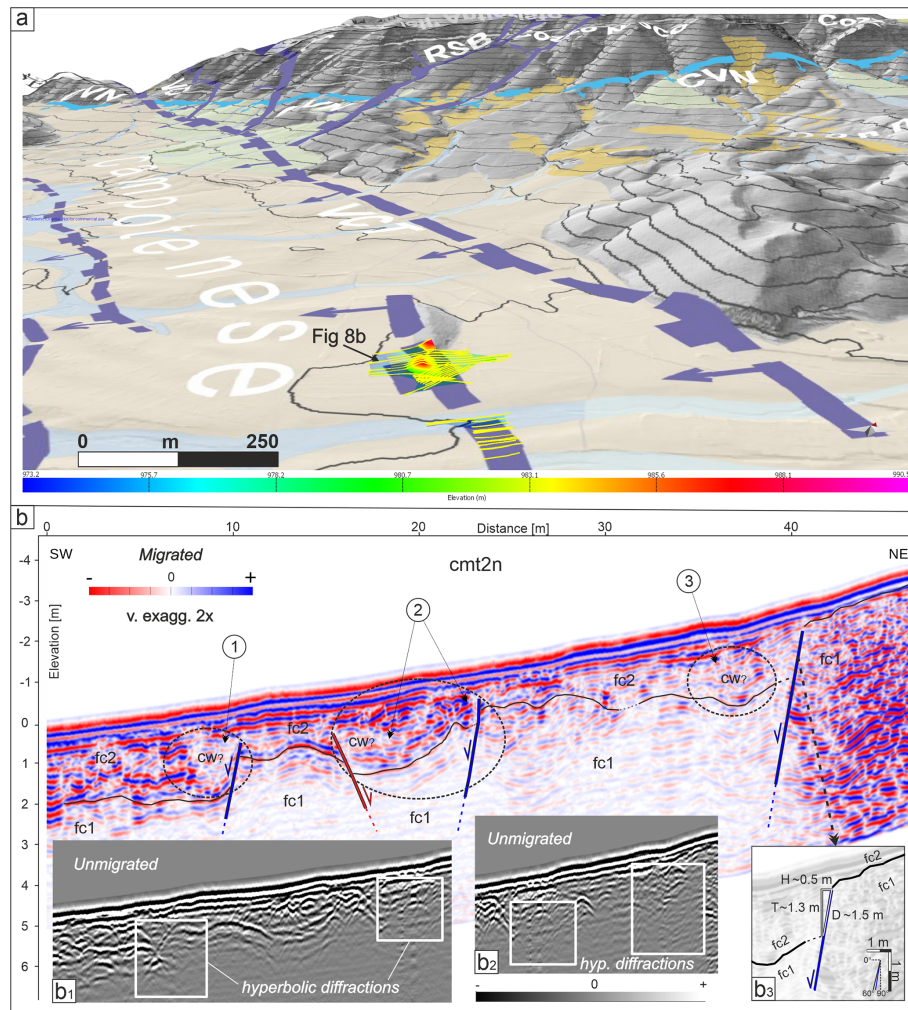


Figure 8. GPR data interpretation: **(a)** three-dimensional image of the surveyed area (see Fig. 1c for location), displaying the dolostone outcrops (grey color). Blue dashed lines are the VCT and RSB faults (Fig. 1b), whilst the light blue is CVN fault. In yellow lines the GPR profiles; the colored surface is the interpreted dolostone top reflection (DTM source: Regione Calabria – <http://geoportale.regione.calabria.it/opendata>, last access: 11 June 2021, under license IODL 2.0. – <https://www.dati.gov.it/iodl/2.0/>, last access: 11 June 2021); **(b)** migrated radar profile with the main interpreted normal faults (blue and red are W- and E-dipping structures, respectively) as well as related sedimentary structures within the Quaternary deposits (unmigrated data in b1 and b2); the inset b3 is a schematic representation illustrating the methodology used for extraction of the GPR fault displacement (D : displacement; T : throw; H : heave). GPR facies fc2 shows semi-continuous and sub-horizontal reflections (Quaternary deposits) onlapping fc1 (Triassic dolostones, black line is the “top”). Circle 1 shows that reflection package thickening and truncation with localized attenuation are likely interpretable as “colluvial-wedge-like” (cw?) features, or deposits from degradation of earthquake fault free-face near the hanging wall ($D \sim 0.6$ m). In circle 2 fc2 is shown to be more discontinuous, from subparallel to wavy reflections package downlapping the lower top dolostone; the asymmetric, truncated reflection thickening is bounded by two conjugate normal fault strands (east dip $D \sim 0.5$ m, west-dip $D = 0.4$ m) displacing both fc1 and fc2. Circle 3 shows a contorted reflection package with limited continuity, displaying thickening, truncation, and distributed attenuation, suggesting colluvial wedge deposits close to the main fault zone ($D \sim 1.5$ m, inset b3). Vertical exaggeration is 2.

set d2, shows the maximum displacement and the most evident deformation of the adjacent sub-surface deposits. The variations of thickness of such Quaternary deposits are consistent with the horst and graben configuration. Thinning is observed in correspondence with the raised buried blocks, whereas thickening, wedge-shaped, and chaotic geometries correspond to the lowered blocks. The main fault of set d1

can be considered a conjugate fault of the VCT (Fig. 8b), separated by a right step-over of about 0.5 km from the segment that borders the eastern basin (Figs. 2c, 8a). Thus, the fault-set d3 and d4 located on the eastern part of h1 and h2 can also be hierarchically classified as a network of minor splays embedded in the southern junction zone between the two VCT segments (Fig. 9c).

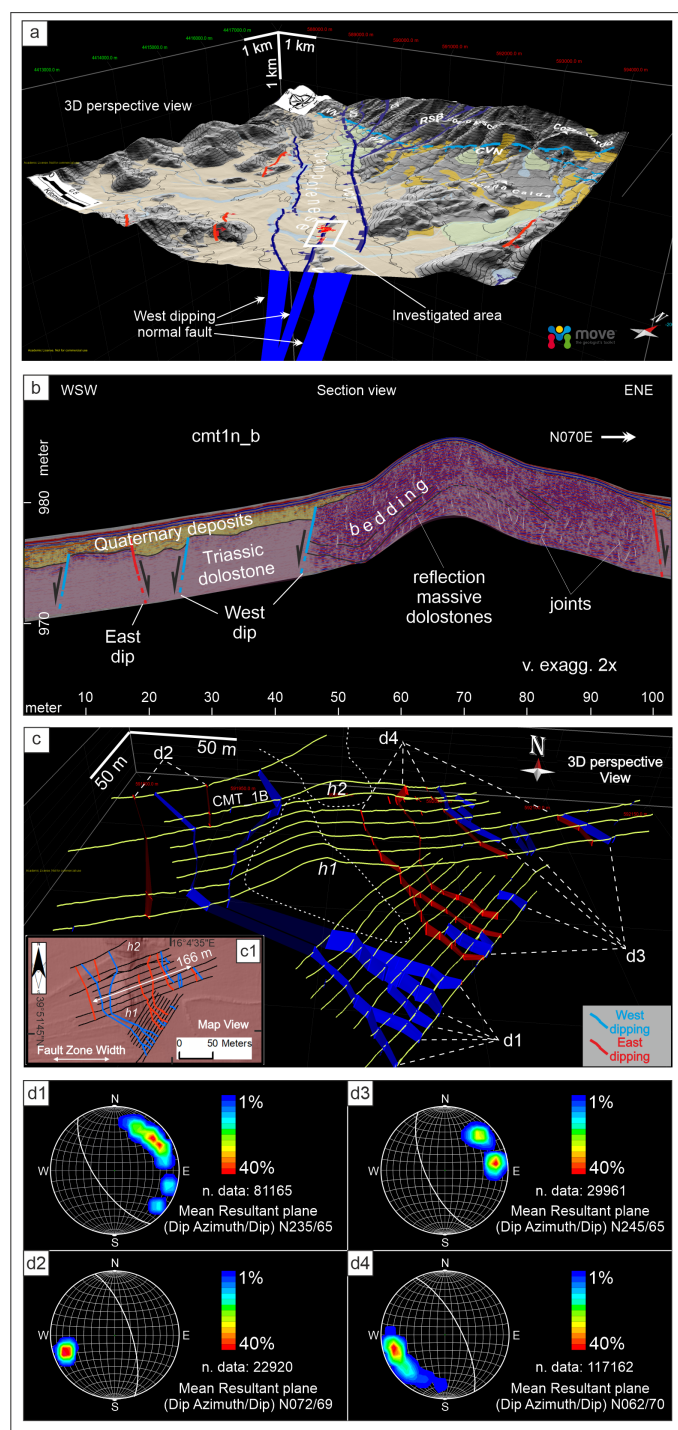


Figure 9. Results of the three-dimensional analysis and interpretation performed on the entire GPR dataset: **(a)** 3D structural model of the Campotenese basin updated after Brozzetti et al. (2017a) (DTM sources: TINITALY by Tarquini et al., 2012, and by Regione Calabria – <http://geoportale.regione.calabria.it/opendata>, last access: 11 June 2021, under license IODL 2.0. – <https://www.dati.gov.it/iodl/2.0/>, last access: 11 June 2021); **(b)** GPR section view (cmt1n-b) with interpretation including synthetic and antithetic fault splays (blue = W to SW dip; red = E to NE dip, respectively); **(c)** detailed structural scratch of faults obtained by the analysis and correlation of interpreted fault splays across the entire GPR dataset; the inset c1 is a conventional structural map oriented to the north and reporting the same fault sets to highlight the maximum width derived for the fault zone **(d)** synthetic stereonet plots of the fault planes in (c), reporting the mean dip azimuth and dip angle extracted for the identified four main sets of discontinuities, with a dip azimuth ranging between 235–245 and 062–072° N for the W-dipping and E-dipping normal faults, respectively. Vertical exaggeration is 2.

The three-dimensional model (Fig. 9a, c) highlights that these faults, despite having a typical Apenninic NW–SE trend, are characterized by a complex polymodal pattern of strikes, with alternating N–S to NW–SE direction. Therefore, such a polymodal character which was observed along all the extensional structures of the area (Brozzetti et al., 2017a) is also confirmed at the GPR scale along this VCT sector. A dedicated statistical analysis of the reconstructed fault planes is reported in the stereo plots of Fig. 9d (d1–d3 = W-dipping faults; d2–d4 = E-dipping faults).

5.2 Seismic hazard implications

The combination of geological and seismological data may suggest outcropping Quaternary faults are capable of releasing earthquakes, but the determination of the expected magnitude along these faults might not always be well constrained. An estimate can be made using well-known scale relationships (Wells and Coppersmith, 1994; Wesnousky et al., 2008; Leonard, 2010; Stirling et al., 2013) with knowledge of the geometric parameters (e.g., fault length, area, and depth), which are often difficult to assess. These scale relations can also be applied to Quaternary scarps caused by cumulative coseismic faulting produced by medium–strong earthquakes (generally $M > 6$). Nevertheless, only through paleoseismological analysis, by sampling and dating the stratigraphy at different levels, is it possible to date and distinguish the amount of slip of each seismic event. But in cases like the VCT, the GPR data assume a key value since the key fault parameters were provided when no direct information on the nature of the surveyed deposits and no accurate dating are available. Our GPR interpretation by itself does not allow one to extract any date for a single earthquake, identify a succession of past seismic events, or establish recurrence times (Galli, 2020). However, it suggests a segmentation of the VCT and the presence of buried splays, which appear to have exerted a strong control on the deposition of Late Quaternary sediments. The location of Quaternary ruptures at a shallow depth in the flat land of an intra-mountain basin presently undergoing alluvial and colluvial sedimentation suggests their occurrence might be attributed to the Holocene. Thus, pointing out normal faulting of Holocene deposits would be, in itself, a very important and novel result for the Campotenese area. A Middle–Late Pleistocene age of activity was proposed for the Mercure and Campotenese boundary faults by Schiattarella et al. (1994) and Brozzetti et al. (2017a), with Holocene activity indirectly inferred on the basis of morpho-structural observations. More recently, an earthquake-structure association with the recent 2010–2014 Pollino seismic activity has been reconstructed through cross sections and relocated seismicity in Cirillo et al. (2021).

Our data are promising because the GPR facies interpretation highlights the possible presence of small-scale grabens or half-grabens (maximum estimated fault zone width of ~ 160 – 170 m, inset c1 of Fig. 9c) and the likely fault-related

deposits (e.g., as observed by Reiss et al., 2003), and Bubeck et al., 2015) at shallow depth. This inference would testify to not only the persistence of extensional deformations up to the Late Quaternary but would even imply the occurrence of episodes of surface faulting. In other words, the Campotenese basin may have been affected in the relatively recent past by medium–strong earthquakes, larger than the 2010–2014 mainshocks. It should be in fact considered that historical events with $6 < M_w < 7$ surrounded the area, being documented a further ~ 50 km north (1857 – $M_w 7.1$) and ~ 60 km south (1184 – $M_w 6.7$, Fig. 1a) (Rovida et al., 2020). Some paleoseismological earthquakes with inferred magnitude $6.5 < M_w < 7$ are attributed to the Castrovillari fault, located ~ 20 km SE and also falling within the Pollino seismic gap (Cinti et al., 1997; Michetti et al., 1997; Cinti et al., 2002, 2015a).

The estimates of the VCT fault length provide an overall value of 15 km (Brozzetti et al., 2017a; Cirillo et al., 2021) which is compatible, in the case of a complete rupture, with the expected magnitudes of $M_w = 6.5$ (Wells and Coppersmith, 1994) and $M_w = 6.8$ (Stirling et al., 2013); these estimates are therefore suggesting this fault is well capable of producing surface breaks. Being the source of the most recent earthquakes (2012 – $M_w 5.2$; 1894 – $M_w 5.1$; 1708 – $M_w 5.8$; and perhaps 1693 – $M_w 5.2$) affecting the study area estimated at ~ 8 km depth (Totaro et al., 2015; Brozzetti et al., 2017a; Napolitano et al., 2020, 2021; Sketsiou et al., 2021), the level of seismic energy released by such historical seismic events would likely be not enough to generate the VCT ruptures at surface. Therefore, it sounds reasonable that the hypothesis of past earthquake occurrence, nucleated from the VCT, with a magnitude sufficiently high to cause the buried coseismic ruptures highlighted by our GPR interpretation, which were subsequently erased at surface by footwall erosion and sedimentation at the hanging wall. In addition, because historical catalogs do not show events with $M_w > 6$ (Rovida et al., 2020), a very energetic earthquake could have likely occurred before the period covered by the available seismological catalogs, proving new perspectives on the actual seismic hazard of the area.

6 Conclusions

Our novel GPR data and dedicated workflow allowed us to obtain a detailed 3D model of the southern sector of the Fosso della Valle–Campotenese fault (VCT) in the continental Campotenese basin, a seismic gap in the Mt. Pollino region (southern Italy). The processing, analysis, assemblage, and interpretation of the 49 GPR profiles was pursued using expertise, techniques, and tools borrowed from seismic reflection industry applications. The non-destructive GPR survey did not require special authorizations and was relatively fast and low cost. The pseudo-3D configuration was an efficient compromise between spatial coverage and duration of

the data acquisition (four days of fieldwork). On the other hand, the data processing was non-trivial, requiring about 6 months overall to set up an optimized workflow, due to challenging data characteristics, such as the steep and rugged topography and the sharp lateral variations of dielectrical properties of media (Triassic dolostones vs. Quaternary deposits).

Our structural reconstruction derived by GPR data interpretation shows several sets of sub-vertical discontinuities within the near surface ($\sim 1\text{--}4\text{ m}$ depth), which we interpreted as a pattern of extensional surface faulting. Such faults are bounding small local “graben or semi-graben-like” structures, which cut an hypothesized Holocene age clastic cover and underlying Triassic dolostones. We have also identified some chaotic and laterally discontinuous GPR-stratigraphic facies, interpreted as near-fault post-earthquake deposits (i.e., possible colluvial wedges). These shallow structures suggest the possibility that surface faulting due to past strong earthquakes ($6 < M_w < 7$) occurred in relatively recent times in the study area. Its traces at the surface were possibly later leveled by the concurrent natural processes of erosion, aggradation, and anthropogenic activities. As our results confirm the presence of seismic potential and thus the possible occurrence of a large earthquake in the future, we wish the primary effect of our study to be one of raising the level of attention regarding the seismic hazard in the Campotenese area, as well as prompting further research. Based on ground truthing, our work may represent a preparatory study for further geophysical surveys (3D GPR and other methods), as well as direct analysis including trenching, drilling, sampling campaigns, and dating (e.g., luminescence, radiocarbon). Although a further multidisciplinary approach would be necessary to achieve a quantitative (i.e., slip rates and recurrence times) assessment of the seismogenic potential of the study area, we firmly promote, particularly where near-surface data are lacking, a widespread use of the presented GPR workflow on other seismic gaps worldwide.

Data availability. The entire GPR dataset presented in this study is available on request from the corresponding author.

Author contributions. ME and DC contributed equally to this work as first authors. ME, DC, CP, and FB led the fieldwork. ME analyzed and processed the GPR and GNSS data. ME, DC, CP, HMJ, and FB contributed to the paper conceptualization and writing. ME and DC managed all data in the GIS environment and within 3D interpretation programs (OpenTect, Move). DC realized the final 3D structural–geological model through Move software. DC and ME created and prepared all the figures. All authors reviewed and edited all the drafts.

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