



The effectiveness of jute and coir blankets for erosion control in different field and laboratory conditions

Jana Kalibová¹, Lukáš Jačka², and Jan Petrá¹

¹Department of Land Use and Improvement, Faculty of Environmental Sciences, Czech University of Life Sciences Prague, Prague, Kamýčká 129, Praha 6 – Suchbátka, 165 21, Czech Republic

²Department of Water Resources and Environmental Modelling, Faculty of Environmental Sciences, Czech University of Life Sciences Prague, Prague, Kamýčká 129, Praha 6 – Suchbátka, 165 21, Czech Republic

Correspondence to: Jana Kalibová (kalibova@fzp.czu.cz)

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Abstract. Vegetation cover is found to be an ideal solution to most problems of erosion on steep slopes. Biodegradable geotextiles (GTXs) have been proved to provide sufficient protection against soil loss in the period before vegetation reaches maturity, so favouring soil formation processes. In this study, 500 g m⁻² jute (J500), 400 g m⁻² (C400), and 700 g m⁻² coir (C700) GTXs were first installed on a 9° slope under “no-infiltration” laboratory conditions, then on a 27° slope under natural field conditions. The impact of GTXs on run-off and soil loss was investigated to compare the performance of GTXs under different conditions. Laboratory run-off ratio (percentage portion of control plot) equalled 78, 83, and 91 %, while peak discharge ratio equalled 83, 91, and 97 % for J500, C700, and C400 respectively. In the field, a run-off ratio of 31, 62, and 79 %, and peak discharge ratio of 37, 74, and 87 % were recorded for C700, J500, and C400 respectively. All tested GTXs significantly decreased soil erosion. The greatest soil loss reduction in the field was observed for J500 (by 99.4 %), followed by C700 (by 97.9 %) and C400 (by 93.8 %). Irrespective of slope gradient or experimental condition, C400 performed with lower run-off and peak discharge reduction than J500 and C700. The performance ranking of J500 and C700 in the laboratory differed from the field, which may be explained by different slope gradients, and also by the role of soil, which was not included in the laboratory experiment.

1 Introduction

Land degradation causes high erosion rates as a consequence of agriculture, grazing, mining, forest fires or deforestation and this causes economic, social and environmental damage (Cerdà, 1998; Cerdà et al., 2010; Erkossa et al., 2015; Keesstra et al., 2014; Lieskovský and Kenderessy, 2014; Moreno-Ramón et al., 2014; Stanchi et al., 2015). However, the largest erosion rates and the most degraded soils are usually found in areas affected by development, infrastructure or urbanization (Cerdà, 2007; Pereira et al., 2015; Sadeghi et al., 2015; Seutloali and Beckedahl, 2015; Yuan et al., 2015).

Civil engineering projects often result in steep slopes with bare soil, which is highly vulnerable to soil erosion, caused by either impact energy from raindrops or by surface run-off (Weggel and Rustom, 1992). Well-established, low-growing, dense vegetation cover is able to control soil loss by 2 or 3 orders of magnitude compared to bare soil conditions (Keesstra et al., 2016; Ola et al., 2015; Rickson, 2006). The highest reduction of erosive run-off was recorded on permanently grassed plots (Álvarez-Mozos et al., 2014). However, the establishment of vegetation cover can be disrupted during early plant growth stages, leaving the slopes exposed to further erosion processes with negative consequences for slope stability (Rickson, 1988). Soils play a pivotal role in major global biogeochemical cycles (carbon, nutrients, and water), while hosting the largest diversity of organisms on land. Because of this, soils deliver fundamental ecosystem services, and management to change a soil process in support of one ecosystem service can either provide co-benefits to other ser-

vices or it can result in trade-offs. Therefore, the necessity of protecting the soil is non-negligible (Berendse et al., 2015; Brevik et al., 2015; Decock et al., 2015; Keesstra et al., 2012; Smith et al., 2015). This is why there is a trend in the research to protect soil with mulches, amendments, and other erosion control measures (Álvarez-Mozos et al., 2014; Hu et al., 2015; Hueso-González et al., 2014; Keesstra et al., 2016; Prosdocimi et al., 2016; Yazdanpanah et al., 2016).

Biological/biodegradable geotextiles (GTXs), made out of jute, coir, rice, straw etc., have often been proved to be effective, sustainable, and eco-friendly alternatives to synthetic erosion control materials used for preventing soil erosion and subsequent slope degradation processes in the period before vegetation reaches maturity, thus facilitating pedogenic processes (Fullen et al., 2007; Jordán et al., 2011; Khan and Binoy, 2012; Langford and Coleman, 1996; Morgan and Rickson, 1995; Ogbobe et al., 1998; Sutherland and Ziegler, 2007; etc.). The range of GTXs is wide. The choice of an individual product may be most convenient when based on the ratio of GTX cost to effectiveness.

Many case studies evaluating the effect of jute and coir GTXs on slopes have been carried out across the world, but the reported effectiveness of GTXs varies (Giménez-Morera et al., 2010; see Table 1). Therefore, the results cannot be generalized (Cantón et al., 2011; Rickson, 2005). Furthermore, because of various site conditions, it is difficult to determine the extent to which soil loss reduction was caused by GTXs and not by other factors, e.g. vegetation cover (Fifield, 1992; Toy and Hardley, 1987).

This paper presents a study in which the effectiveness of three jute and coir fibre rolled erosion control systems (see Table 2), which are commercially available and widely applied worldwide, were tested under both laboratory and field conditions. No product with dense coverage (non-woven) was included, as these are not as effective in reducing run-off (Luo et al., 2013) and can produce even more run-off than bare soil (Davies et al., 2006; Mitchell et al., 2003).

Unlike previous laboratory studies, the impact of GTXs was examined on “no-soil” subgrade to omit one of the most variable factors affecting soil erosion – soil itself (Smets et al., 2011) – and to assess the effectiveness based on nothing but GTX properties. Due to the infiltration process, soil supports the erosion control effect of GTXs, providing less water for overland flow (Beven, 2011). Assuming that soil affects all GTXs equally in the field, the laboratory records of surface run-off volume (L) and peak discharge ($L s^{-1}$) reduction should proportionally match the data from field experiments. Concerning the shear stress of overland flow, the character of surface run-off volume and velocity reduction in the laboratory should reflect soil loss reduction in the field as well (Harmon and Doe, 2001; Morgan and Rickson, 1995; Thompson, 2001).

The objective of this experiment was to test the impact of biodegradable erosion control GTXs on surface run-off on a slope exposed to simulated rainfall under laboratory and field



Figure 1. A Norton Ladder Rainfall Simulator is positioned above test beds with mechanical toggle flow meters. A C400 erosion control net is spread over the test bed.

conditions, to rank the effectiveness of GTXs in run-off reduction, and to compare the run-off data trends under laboratory conditions (where soil subgrade and infiltration process were excluded) with data trends under different field conditions (including soil subgrade and different slope gradients).

2 Materials and methods

2.1 Laboratory experiment

Laboratory experiments were conducted in the rainfall simulation laboratory at the Czech University of Life Sciences Prague, using a Norton Ladder Rainfall Simulator. Rainfall simulations have been used since the 1930s by scientists to study soil erosion by water and soil hydrology. They are one of the most used and most successful tools used in disciplines such as agronomy, hydrology, and geomorphology (Cerdà, 1998; Martínez-Murillo et al., 2013; Rodrigo Comino et al., 2015, 2016; Iserloh et al., 2013a, b). In this study, the rainfall simulator uses four Veejet 80 100 nozzles, with a water pressure of 0.04 MPa, height of 1.9 m and target area of $4.9 \text{ m} \times 1.05 \text{ m}$. The main rainfall characteristics are as follows: mean rainfall intensity $I = 105 \text{ mm h}^{-1}$, time-specific kinetic energy $KE_R = 1269 \text{ J m}^{-2} \text{ h}^{-1}$, volume-specific kinetic energy $KE = 12 \text{ J m}^{-2} \text{ mm}^{-1}$, median vol-

Table 1. Overview of studies investigating the impact of J500 (jute) (500 g m^{-2}) and C400, C700 (coir) ($400; 700 \text{ g m}^{-2}$) GTXs on surface run-off and soil erosion by water since 2000¹.

Author	GTX type	Soil type (sand–silt–clay; %)	Slope [°]	Simulated rainfall intensity [mm h^{-1}]	Control sample cover type	Run-off reduction [% of control]	Soil loss [% of control]	Lab./field [L/F]
Álvarez-Mozos et al. (2014)	J500	silty clay loam (13.8–53.9–32.3)	45°	max. 31.2	hydroseeded soil	266	31	F
	J500	silty clay loam (13.8–53.9–32.3)	60°	max. 31.3	hydroseeded soil	238	40	F
Shao et al. (2014)	J500	mixed substrate	40°	50	bare substrate	37.9	0.3	L
Khan and Binoy (2012)	J500	sandy	33°	122	bare soil	83	10	L
Jakab et al. (2012)	J500	silty loam (23–70–7)	8.5°	max. 38.7	bare soil	47, 74, 119	20	F
Kertész et al. (2007)	J500	silty loam	11°	max. 83	bare soil	30–250	7–306	F
Sutherland and Ziegler (2007)	C700	clay (24–34–42)	5.5°	35	bare soil	84	0.4	F
	C400	clay (24–34–42)	5.5°	35	bare soil	90	8	F
Rickson (2006)	J500	sandy loam	10°	72	bare soil	102	15	L
	C700	sandy loam	10°	72	bare soil	106	51	L
Sutherland and Ziegler (2006)	J500, C700	clay-dominated oxisol	5.5°	35, 114	bare soil	91–104	17	F
Lekha (2004)	C700	sandy loam	26°	NA ²	seeded bare soil	NA ²	0.4–21.9	F
Mitchel et al. (2003)	J500	loamy sand	15°	NA ²	bare soil	35	1	F
Rickson (2000)	J500	sandy loam	10°	35	bare soil	90	14	L
	C700	sandy loam	10°	35	bare soil	97	25	L
	J500	sandy loam (68.1–22.1–9.8)	10°	95	bare soil	90	23	L
	C700	sandy loam (68.1–22.1–9.8)	10°	95	bare soil	102	23	L

¹ For studies carried out before the year 2000, see papers by Bhattacharyya et al. (2010) or Ingold and Thompson (1986). ² NA = not available.**Table 2.** Main characteristics of three tested biological GTXs.

Treatment	1 – Jute net	2 – Coir net	3 – Coir net
Marking	J500	C400	C700
Material	100 % jute fibre	100 % coir fibre	100 % coir fibre
Description	open weave biodegradable jute geotextile in a grid structure	open weave biodegradable coir geotextile in a grid structure	open weave biodegradable jute geotextile in a grid structure
Mass per area (g m^{-2})	500	400	700
Mesh size (mm × mm)	15 × 15	35 × 35	20 × 20
Thickness (mm)	2	7	8
Open area (%)	60	65	50
Working life (years)	1–2	3–4	3–7
Average price (EUR m^{-2})*	0.61–0.96	0.89–1.29	1.29–2.09

* Data obtained from several GTX suppliers.

umetric drop diameter $d_{50} = 0.44 \text{ mm}$, Christiansen uniformity $\text{CU} = 79 \%$. A slope gradient of 9° was used for the experiment. An impermeable plastic film spread over the test bed was used as a control. The tested GTXs were then laid onto the plastic film to simulate no-infiltration conditions (see Fig. 1). All treatments were exposed to rainfall of 1.75 mm min^{-1} intensity and 15 min duration. Ten rainfall simulations were carried out on each treatment (control, J500, C400, C700). To provide constant starting conditions, a 15 min rainfall of 1.75 mm min^{-1} intensity was applied before each simulation. During a rainfall event, run-off initiation time t_i [s] was recorded, run-off was collected by a mechanical toggle flow meter, and the time for each toggle was electronically recorded. Total run-off volume at time = 15 min R_{15} [L] and peak discharge Q [L s^{-1}] were measured. An outline of the laboratory experiments is given in Table 3.

2.2 Field experiment

The field simulations were carried out on the south slope of the Rokycany–Pilsen rail corridor near the village of Klabava ($49^\circ 44' 56.938'' \text{ N}$, $13^\circ 32' 17.887'' \text{ E}$) in the Pilsen Region, Czech Republic. According to Quitt's classification, Klabava falls into a moderately warm region with mean annual air temperature of 8° C and mean annual precipitation of 550 mm (Tolasz, 2007). The experimental slope was formed by a 1 : 2 (27°) cut. The stabilized unmade ground was covered by a gravelly loam soil layer of 0.3 m thickness, 1.40 g cm^{-3} bulk density, and 47% porosity. A particle size analysis was performed using a hydrometer method (SIST-TS CEN ISO/TS, 17892-4:2004, 2004). The soil texture was classified using the system of the United States Department of Agriculture. The tested soil was classified as gravelly loam (24% clay, 40% silt, 36% sand). The percentage of gravel

Table 3. An outline of laboratory and field experiments testing the impact of biological GTXs on surface run-off and soil loss.

	Laboratory experiments	Field experiments
Substrate type	impermeable plastic film	gravelly loam
Slope (°)	9	27
Rainfall intensity (mm h ⁻¹)	105	80
Experiment duration (min)	15	15
Cover type	J500, C400, C700	J500, C400, C700
Control cover	impermeable plastic film	bare gravelly loam
Replications	10	3
Total number of experiments	40	12

(> 2 mm) was 26 %. The estimated organic matter content of the soil was 3.5 %. The loss-on-ignition method (heated destruction of all organic matter) was used for the calculation of the organic matter content in the soil (ASTM, 2000; Schumacher, 2002; Nelson and Sommers, 1982).

Four rectangular plots (one control and three for the GTX treatments), each covering an area of 1.8 m × 8.5 m, were outlined by iron barriers on each side and a triangular collecting trough at the bottom (see Fig. 2). Afterwards erosion control nets were installed. A bare soil plot was used as a control.

The rainfall was simulated by four FullJet nozzles, with water pressure of 0.03 MPa and height 2.4 m above the plots. Rainfall application did not differ significantly among treatments ($\alpha = 0.05$). Three replications of each treatment were carried out at an overall mean intensity of $1.33 \pm 2 \text{ mm min}^{-1}$ (a 10-year return period at the study site). To provide constant starting conditions, a 15 min rainfall of 1.33 mm min^{-1} intensity was applied before each simulation. For an outline of the field experiment see Table 3.

For operational reasons, it was necessary to spread the simulations over a period of two days. The measurements were therefore carried out under slightly different moisture conditions. The control treatment was measured on the first day with initial volumetric soil moisture content at 20.7 %. The GTX treatments were measured the following day with initial volumetric soil moisture content at 13.1 % (an average value of nine records – three for each plot; the individual values did not differ significantly). The volumetric soil moisture content was determined using the gravimetric method (e.g. Kutílek and Nielsen, 1994) from undisturbed soil samples (100 cm³) that were collected in the top soil. During the rainfall event, run-off initiation time t_i [s] was recorded, run-off was collected by a mechanical toggle flow meter with electronic recording of time for each toggle, and the total run-off volume [L] and discharge [L s^{-1}] were measured. After the rainfall event, sediment concentration [g L^{-1}] of the run-off



Figure 2. Experimental slope in the field (Rokycany, Czech Republic). Rainfall simulation on bare soil (control sample) in progress. Note: the iron collecting trough at the bottom of the plot is hidden below the eroded material, as the image was taken during the rainfall simulation.

was determined by oven-drying five collected run-off samples at 105 °C for 48 h, and subsequent weighing of the samples and sediment load (soil loss SL) [g] was calculated by multiplying the mean sediment concentration by total run-off volume.

2.3 Data analysis

All analyses were performed using Excel 2010 and R statistical software. One-way analysis of means was used to test whether the differences in laboratory values of time to run-off initiation t_i [s], run-off at time $t = 15 \text{ min}$ R_{15} [L] and peak discharge Q [L s^{-1}] are caused by sampling variation, at significance level 0.05. A Welch two-sample t test, not assuming equal variances, was used to compare mean values of t_i , R_{15} and Q for each treatment. The null hypothesis was defined as follows: the true difference in means is equal to zero.

In order to compare run-off (and soil loss) rates from field and laboratory plots, run-off ratios RR_{15} (Eq. 1), peak discharge ratios QR (Eq. 2), and soil loss ratios SLR (Eq. 3) were calculated and expressed as a portion of control [%]:

$$RR_{15} = \frac{R_{15 \text{ geotextile}}}{R_{15 \text{ control}}} \times 100 \quad (1)$$

$$QR = \frac{Q_{\text{geotextile}}}{Q_{\text{control}}} \times 100 \quad (2)$$

$$SLR = \frac{SL_{\text{geotextile}}}{SL_{\text{control}}} \times 100. \quad (3)$$

Ratios were calculated from mean values of variables.

Table 4. Statistical description of peak discharge for 500 g m⁻² jute net (J500), 400 g m⁻² coir net (C400), and 700 g m⁻² coir net (C700) in laboratory experiments.

Parameters	Units	Control	J500	C400	C700
Arithmetic mean	L s ⁻¹	0.151	0.126	0.146	0.137
Standard deviation	L s ⁻¹	0.0005	0.0076	0.0025	0.0015
Median	L s ⁻¹	0.151	0.126	0.145	0.138
Minimum	L s ⁻¹	0.150	0.117	0.143	0.135
Maximum	L s ⁻¹	0.150	0.140	0.150	0.139
Range	L s ⁻¹	0.001	0.023	0.007	0.004
Coefficient of variation	%	0.004	0.058	0.017	0.011
CI mean 0.95*	L s ⁻¹	0.0004	0.0056	0.0019	0.0011

* The confidence interval of the mean calculated at the 0.95 significance level.

3 Results

A statistical description of the results of peak discharge Q (L s⁻¹) is shown in Table 4. Run-off R_{15} data were analysed analogically.

The mean time to run-off initiation of the simulated rainfall in the laboratory was 16.3 s (standard deviation $\sigma = 0.46$ s) for control, 21.3 s ($\sigma = 0.46$ s) for J500, 21.1 s ($\sigma = 1.30$ s) for C400 and 25.8 s ($\sigma = 1.54$ s) for C700. The results of a one-way analysis of mean values of run-off t_i ($F = 28.484$, num $df = 2.000$, denom $df = 14.076$, p value = 1.127×10^{-5} , equal variance of data sets are not assumed) indicate that the differences in mean values of measured GTX samples are not caused by sampling variation at significance level 0.05. The null hypothesis (“The true difference in means of time to run-off initiation is equal to zero”) was rejected (by the Welch two-sample t test, not assuming equal variances) for all comparisons except C700 vs. C400 at significance level 0.05 (see Table 6).

Mean run-off R_{15} in the laboratory was 130.9 L ($\sigma = 0.30$ L) for control, 102.2 L ($\sigma = 5.21$ L) for J500, 118.6 L ($\sigma = 1.43$ L) for C400 and 109.0 L ($\sigma = 1.79$ L) for C700. The results of a one-way analysis of mean values of run-off R_{15} ($F = 100.414$, num $df = 2.000$, denom $df = 16.201$, p value = 7.432×10^{-10} , equal variance of data sets are not assumed) indicate that the differences in mean values of measured GTX samples are not caused by sampling variation at significance level 0.05. The null hypothesis (“The true difference in means of run-off is equal to zero”) was rejected for all comparisons (see Table 6).

The results of a one-way analysis of mean values of peak discharge Q ($F = 52.051$, num $df = 2.000$, denom $df = 13.494$, p value = 4.53×10^{-7} , equal variance of data sets are not assumed) indicate that the differences in mean values of measured GTX samples are not caused by sampling variation at significance level 0.05. The null hypothesis (“The true difference in means of peak discharge is equal to zero”) was rejected for all comparisons (see Table 6).

In short, all GTX samples significantly delayed the run-off initiation in comparison with the control. Jute J500 proved

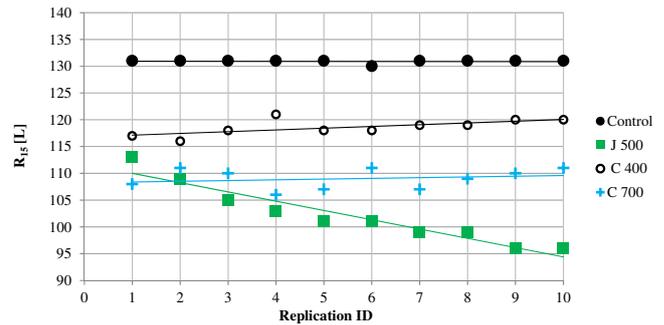


Figure 3. Surface run-off volume at time = 15 min, R_{15} (L); linear trend lines included; laboratory conditions.

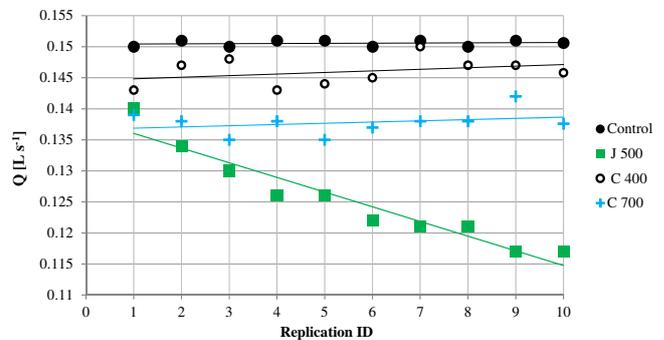


Figure 4. Peak discharge at outlet section, Q (L s⁻¹); linear trend-lines included; laboratory conditions.

to be significantly more effective than both coir GTXs. No statistically significant difference in time to run-off initiation was found between coir GTXs C400 and C700. Mean values of run-off and discharge are significantly different for all tested GTXs. All GTXs significantly reduced run-off and peak discharge, with jute net J500 being the most effective under laboratory conditions. The results of the rainfall simulation experiments in the laboratory are shown in Figs. 3 and 4.

The mean time to run-off initiation of the simulated rainfall in the field was 295 s (792, 50, and 44 s for the first, second, and third rainfall events) for the control, 120 s (no runoff observed, 120, 120 s) for J500, 268 s (no runoff observed, 280, 255 s) for C400 and 325 s (no runoff observed, 405, 245 s) for C700. For J500, C400, and C700, no run-off was produced during the first rainfall event.

In general, control plots tended to produce the highest run-off volume (L) and discharge (L s⁻¹). Concerning the time to run-off initiation, run-off was most quickly produced at the control plot, followed by coir C400, jute J500 and coir C700 in the laboratory. In the field, J500-treated plots produced run-off faster than C700-treated plots.

The order control – C400 – J500 – C700 matches the impact of GTXs on run-off volume and discharge for the first rainfall event in the laboratory. For the next replications,

Table 5. Mean run-off ratios RR_{15} [%], peak discharge ratios QR [%] and soil loss SLR [%] ratios of jute 500 g m^{-2} (J500), coir 400 g m^{-2} (C400) and coir 700 g m^{-2} (C700) GTXs, compared to control treatments under field and laboratory conditions.

	Mean run-off ratio RR_{15} [%]				Mean peak discharge ratio QR [%]				Mean soil loss ratio SLR [%]			
	control	J500	C400	C700	control	J500	C400	C700	control	J500	C400	C700
Lab.	100	78	91	83	100	83	97	91	100	–	–	–
Field	100	62	79	31	100	74	87	37	100	0.6	6.2	2.1

Table 6. Parameters (t value, degree of freedom df and p value) of the Welch two-sample t test; significance level 0.05.

	run-off t_i			run-off R_{15}			peak discharge Q		
	t value	df	p value	t value	df	p value	t value	df	p value
control \times J500	–16.53	10.42	8.18×10^{-9}	16.49	9.06	4.57×10^{-8}	9.98	8.08	8.00×10^{-6}
control \times C400	–10.45	11.20	4.07×10^{-7}	25.28	9.79	3.02×10^{-10}	5.85	8.74	2.72×10^{-4}
control \times C700	–23.15	18.00	7.63×10^{-15}	36.22	9.51	1.65×10^{-11}	26.10	10.07	1.40×10^{-10}
J500 \times C700	7.64	10.42	1.38×10^{-5}	–3.70	11.09	0.0034	–4.37	8.64	0.002
J500 \times C400	6.49	17.17	5.31×10^{-6}	–9.11	10.34	2.93×10^{-6}	–7.57	9.80	2.15×10^{-5}
C700 \times C400	–0.44	11.20	0.672	–7.57	9.80	2.15×10^{-5}	9.01	13.01	5.90×10^{-7}

an obviously decreasing trend of R_{15} and Q for J500 was recorded, showing jute GTXs to be the most effective. Other GTXs seemed to provide slightly increasing trends (Figs. 3, 4).

Table 5 shows a comparison of run-off (RR_{15}) and peak discharge (QR) ratios for both laboratory and field conditions. In the laboratory, the greatest decrease in RR_{15} was recorded by the J500 jute net ($RR_{15} = 78\%$) in comparison with control (100%). The order of effectiveness of each treatment in the laboratory was identical for both run-off volume and peak discharge: (1) J500, (2) C700, and (3) C400.

A different effectiveness ranking was observed in the field. The highest reductions of run-off volume and peak discharge were observed for coir C700 ($RR_{15} = 31$, $QR = 37\%$), followed by jute J500 ($RR_{15} = 62$, $QR = 74\%$).

Results of soil loss ratio from the field experiment are also given in Table 5. All GTXs provided a great reduction of soil loss with jute J500 being the most effective, followed by coir C700 and C400.

4 Discussion

4.1 Time to run-off initiation

In general, control plots (bare soil/impermeable plastic film without GTXs) have a significantly faster response to rainfall than GTX-treated plots (also reported by Cerdà et al., 2009). The performance of GTXs seems to be highly influenced by the infiltration rate, as the surface run-off was initiated after less than 30 s on impermeable subgrade (laboratory experiment) and after 2–6 min on soil (field experiment). The very short time to run-off initiation means that any thunder-

storm will contribute to run-off and soil loss on sloping bare soil (Cerdà et al., 2009). The high bulk density of the soil (1.40 g cm^{-3} , frequently a feature of slopes created during civil engineering projects) can explain the fast run-off initiation, and the large run-off volumes and available sediment are due to raindrop impact on bare soils (Cerdà and Jurgensen, 2008).

The results of laboratory-based rainfall simulations indicated that GTXs significantly delayed the time to run-off initiation. Similar results were obtained by Shao et al. (2014) and Sutherland and Ziegler (2007). According to mean values, C700 performed better than J500. When studying the results of individual replications, J500 reached the peak discharge earlier than C700, but the discharge values remained lower. Time to run-off initiation was longer for C700, but higher peak discharge values were observed. The better performance of jute J500 compared to both coir GTXs was probably caused by lower water-absorbing capacity and lower flexibility of coir GTXs, due to which the GTXs did not lay directly on the subgrade, allowing water to flow over a smoother surface under the GTXs. The same observation was previously reported by Rickson (2006). In the literature, significant differences between GTX-covered and control (bare soil) plots were confirmed by Sutherland and Ziegler (2007). In other studies, such differences were not proven (Rickson, 2000). A possible explanation could be the different infiltration capacity of used soil subgrade. Rickson (2000) used more permeable sandy loam, while Sutherland and Ziegler (2007) used clay (see Table 1); therefore it seems that the smoother and less permeable the subgrade, the higher the delay of the GTX effect, as the low infiltration ca-

capacity of the subgrade provides a higher volume of surface run-off.

4.2 Run-off volume reduction

The results of the laboratory simulations showed a significant decrease in run-off volume [L] from the GTX-treated plots. Similar results were reached by Khan and Binoy (2012), Shao et al. (2014) and Sutherland and Ziegler (2007; see Table 1). On the contrary, some studies (both field and laboratory) concluded that GTXs increase the run-off volume (Álvarez Mozos et al., 2014; Giménez-Morera et al., 2010; Kertézs et al., 2007). The increase might be caused by a dense cover of GTXs (Mitchel et al., 2003) or high slope gradient, where water can flow through the GTX fibres without infiltration into the soil (Álvarez-Mozos et al., 2014). In this study, the run-off control effect of GTXs was supported by the infiltration process, leading to a higher run-off reduction in the field in comparison to the laboratory, despite a higher slope gradient (27°).

The authors presumed that due to the infiltration process, soil would support the erosion control effect of GTXs, providing less water for overland flow (Beven, 2011). Assuming that soil affects all GTXs equally in the field, the laboratory records of surface run-off volume (L) and peak discharge (Ls^{-1}) reduction should proportionally match data from field experiments. However, the GTX effectiveness ranking in the laboratory significantly differed from the field data. In the laboratory the run-off ratios of 78, 83, and 91 % were recorded for jute J500, coir C700 and coir C400 respectively. In the field, the run-off ratios were the following: 62, 31, and 79 % for the same order of GTXs (see Table 5). Coir GTX C700 performed with significantly higher run-off reduction than jute J500 in the field. The same results were reported by Álvarez-Mozos et al. (2014) from a 60° slope, while on 45° slope jute performed better than coir. If more replications were carried out in the field, a different trend possibly might be found, because a decreasing trend of run-off volume is clear for jute J500 under laboratory “no-soil” conditions, while coir C700 shows an increasing trend (see Fig. 3). Similar behaviour was observed in the field, where the run-off ratio of 66 and 59 % (first and second replication) was observed for J500, and 24 and 38 % was observed for C700. More replications in the field would indicate whether the decreasing trend for jute and increasing trend for coir will continue.

Higher run-off reduction by C700 might also be explained by its slightly higher loop size in comparison with J500 (see Table 2). In theory, C700 might provide more space for rainwater to fall directly to the soil surface and then infiltrate, which would lead to lower surface run-off volume. However, on the jute-treated plot the rainwater was initially absorbed by the fibres and then brought down through them due to gravity.

4.3 Soil loss reduction

According to the laboratory test, jute J500 seemed to have the highest impact on peak discharge and run-off velocity. Therefore, lower shear stress might be assumed for jute J500 (Thompson, 2001) than for coir GTXs, leading to lower erosion rate in the field. This was confirmed both in the field experiment of this study and in the work of Rickson (2000, 2006). All GTXs significantly reduced soil loss (see Table 5). Despite much higher run-off volume from the jute-treated plot, SLR equalled to 0.6 % for jute J500, followed by coir C700 with SLR = 2.1 %. The performance of jute and coir C700 may be considered to be comparable, as the small difference might have been caused by a soil loss measurement error.

Álvarez-Mozos et al. (2014) reported similar behaviour from jute and coir GTXs. In their study, jute performed better for run-off reduction but resulted in higher soil loss than coir on a 45° slope. On a 60° slope the situation was reversed: jute showed more run-off reduction but better erosion control than coir. The authors explain this with the theory that on gentle or moderate slopes, biological GTXs might absorb rainwater and slow run-off generation, whereas on steep slopes water can slip through the GTX fibres and create superficial flow paths without infiltrating into the soil. This factor seems to be more relevant for jute than coir due to its higher water absorbing capacity (Gosh, 2014). In this study, the run-off control effect of GTXs varied under different slope gradients even when lower values (9 and 27°) were used. It is interesting that differences in performance were recorded for slope ranges which do not overlap (9° vs. 27° and 45° vs. 60°). A threshold value of slope gradient, at which GTX behaviour changes, needs to be established. Potentially, if the field and laboratory experiments were both carried out on a slope gradient either below or above this threshold, the match between data sets would be reached.

The rigidity of GTX fibres may play an important role too, as the smoother structure of jute GTX fibres probably provides better conditions for the flow of water compared to the tougher coir fibres.

Furthermore, the contact between GTXs and soil plays a very important role (Midha and Suresh Kumar, 2013). It seems to decrease as the slope gradient and GTX material rigidity increases (Chen et al., 2011; Midha and Suresh Kumar, 2013). This may apply to this study – jute probably absorbed more rainwater into its fibres and due to gravity this water was brought down through the fibres, causing almost no erosion. Despite being provided by the same supplier, coir C700 was visually observed to have slightly higher cover in the field (manufacturing variability). This might have led to higher retention of rainwater, but because of lower contact with the soil due to its rigidity, the erosion rate of plots with coir was higher than for those with jute. Another explanation might be that due to the structure of fibres, water flows more slowly through coir than through jute. Additionally, coir fi-

bles create higher obstacles for overland flow due to their larger diameter and also the clogging of spaces among fibres. Therefore, at the coir C700 plot the water run-off was lower but the sediment content was higher. Further investigation of the interaction between eroded soil particles and GTX fibres during rainfall events would be valuable for testing this theory. According to this experiment, it seems that slope gradient is not the only factor determining GTX performance. Soil characteristics and GTX–soil interface need to be considered along with the slope gradient.

The field experiment was carried out on a steeper slope (27°) than the laboratory experiment (9°). Authors proceeded to compare these two data sets because, according to some studies, GTX effectiveness increases with the slope gradient (Morgan, 2005). This fact was partly confirmed by Álvarez-Mozos et al. (2014), who examined the impact of GTXs on run-off volume and soil loss on 45 and 60° slopes. On the 45° slope the soil loss was reduced by 69 and 90 % by jute and coir respectively. On the 60° slope, the reduction was 60 % for jute and 56 % for coir. Again, different behaviours (performance ranking) were recorded with changing slope, which makes it necessary to find slope gradient threshold values beyond which the performance of GTXs changes. In this study it is not possible to determine whether the soil erosion control performance increased in the field, as “no-soil” conditions were used in the laboratory. Furthermore, without any other field records of lower slope gradients and same soil conditions for comparison, it would be highly complicated to separate erosion control effects of GTXs from the impact of soil infiltration on soil loss in the field. Also, lower rainfall intensity applied to the field for operational reasons might slightly modify the results. But for a pilot research on whether the performance ranking of GTXs is the same in the field as in the laboratory, this deviation might be acceptable. For further research more consistent conditions would definitely be required, but the data presented here shed more light on the behaviour of GTXs under different site conditions.

5 Conclusions

Jute and coir GTXs tested in this study can significantly delay the initiation of surface run-off under the simulated rainfall, when compared to control plots (bare soil in the field, impermeable plastic film in the laboratory) without GTXs. Control plots tended to produce significantly higher run-off volume [L], discharge [L s^{-1}], and soil loss [g] than GTX-treated plots.

In the laboratory, jute J500 showed an increasing trend of run-off control, unlike coir GTXs, the performance of which gradually decreased. Further investigation is needed to prove whether this behaviour also appears in the field.

Regardless of the conditions (slope, laboratory vs. field), coir C400 seemed to be less effective than jute J500 and coir C700. The run-off control performance of jute J500 and

coir C700 significantly differed between the “no-soil” laboratory and field conditions, but all GTXs provided a great reduction of soil loss with jute J500 being the most effective, followed by coir C700 and C400. The theory that soil would influence the performance of all GTXs equally (same effectiveness ranking in the laboratory as in the field) was not confirmed, which makes it necessary to find slope gradient threshold values beyond which the performance of GTX changes. The influence of the slope gradient and GTX–soil contact on run-off and soil loss reduction still needs to be investigated in detail. Another experimental testing of GTX effectiveness using different slope gradient and soil subgrade is suggested by authors.

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