

**Seismic visibility of a deep subduction channel**

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# Seismic visibility of a deep subduction channel: insights from numerical simulation of high-frequency seismic waves emitted from intermediate depth earthquakes

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## Abstract

Return flow in a deep subduction channel (DSC) has been proposed to explain rapid exhumation of high pressure-low temperature metamorphic rocks, entirely based on the fossil rock record. Supported by thermo-mechanical models, the DSC is envisioned as a thin layer on top of the subducted plate reaching down to minimum depths of about 150 km. We perform numerical simulations of high-frequency seismic wave propagation (1 to 6 Hz) to explore potential seismological evidence for the in-situ existence of a DSC. Motivated by field observations, for modeling purposes we assume a simple block-in-matrix structure with eclogitic blocks floating in a serpentinite matrix. Homogenization calculations for block-in-matrix structures demonstrate that effective seismic velocities in such composites are lower than in the surrounding oceanic crust and mantle, with nearly constant values along the entire length of the DSC. Synthetic seismograms for receivers at the surface computed for intermediate depth earthquakes in the subducted oceanic crust for models with and without DSC turn out to be markedly influenced by its presence or absence. In models with channel,  $P$  and  $S$  waveforms are dominated by delayed high-amplitude guided waves emanating from the waveguide formed by oceanic crust and DSC. Simulated patterns allow for definition of typical signatures and discrimination between models with and without DSC. These signatures stably recur in slightly modified form for earthquakes at different depths inside subducted oceanic crust. Comparison with available seismological data from intermediate depth earthquakes recorded in the forearc of the Hellenic subduction zone reveal similar multi-arrival patterns as observed in the synthetic seismograms for models with DSC. According to our results, observation of intermediate depth earthquakes along a profile across the forearc may allow to test the hypothesis of a DSC and to identify situations where such processes could be active today.

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## 1 Introduction

During the first decades of plate tectonics, most ideas on structure and properties of the plate interface along subduction zones were inspired by textbook cartoons, showing a giant thrust fault, with its position being marked by Benioff zone seismicity. The narrow fault or shear zone concept also underlies thermal models of subduction zones (e.g. Turcotte and Schubert, 2002; Van Den Beukel and Wortel, 1988; Peacock, 1996; Syracuse et al., 2010), with a downward single pass flow beneath a rigid mantle wedge in the forearc. This starting model became challenged by the finding that high  $P/T$  metamorphic rocks are very widespread within continental crust (e.g. Ernst and Liou, 1999; Tsujimori et al., 2006; Agard et al., 2009; Guillot et al., 2009; Ota and Kaneko, 2010), obviously having been exhumed from a subduction zone. While in many cases some cooling concomitant with decompression requires exhumation as relatively small bodies with heat transfer into a cooler environment (e.g. Schertl et al., 1991; Stöckhert et al., 1997; Reinecke, 1998; Groppo et al., 2007; Groppo and Castelli, 2010; Krebs et al., 2011; Angiboust et al., 2012), geochronological results pose narrow time brackets for typical time scales of exhumation, asking for displacement rates comparable to plate velocity (e.g. Gebauer et al., 1997; Rubatto and Hermann, 2001; Baldwin et al., 2004; Little et al., 2011). Rapid exhumation with concomitant cooling does neither reconcile with uplift and erosion nor with crustal extension (Platt, 1993; Ring and Brandon, 1999). Moreover, geochronological results suggest that in cases a large part of exhumation has taken place during ongoing subduction, prior to collision (e.g. Lardeaux et al., 2001; Rubatto et al., 2011). These observations have led to postulation of a deep subduction channel (DSC) with forced return flow as a possible mechanism for exhumation (Fig. 1).

The concept of a subduction channel was first applied to explain structure and  $P$ - $T$  paths of the high  $P/T$  metamorphic Franciscan mélange in California (Cloos, 1982), and elaborated by Shreve and Cloos (1986) and Cloos and Shreve (1988a, b). It was inferred to play a role in the frontal forearc beneath an accretionary wedge, competing to

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models based on critical wedge geometry (e.g. Platt, 1993). Identification of UHP meta-  
morphitic rocks starting in the 1980ies (e.g. Chopin, 1984; Schertl et al., 1991; Schreyer,  
1995; Harley and Carswell, 1995), and in particular the finding that these rocks un-  
dergo very rapid exhumation (e.g. Gebauer et al., 1997; Rubatto and Hermann, 2001;  
5 Baldwin et al., 2004; Parrish et al., 2006), then inspired tectonic models invoking a  
DSC reaching to greater depth. Forced return flow of material from depths exceeding  
100 km, as schematically shown in Fig. 1, seemed to provide a feasible alternative for  
generation and exhumation of smaller UHP metamorphic slices, distinct from coherent  
crustal or lithospheric sections of the downgoing plate during collision (e.g. Chemenda  
10 et al., 1995; Hacker et al., 2000; Kylander-Clark et al., 2012). Numerical simulations  
(e.g. Burov et al., 2001; Gerya and Stöckhert, 2002; Warren et al., 2008) generating  
bulk flow patterns and  $P$ - $T$ -paths for individual material points, grossly consistent with  
natural record and structures of orogenic belts (e.g. Engi et al., 2001; Stöckhert and  
Gerya, 2005), support the principal feasibility of the DSC concept.

15 Geometry and width of a DSC remains poorly constrained by natural observations  
(e.g. Warren, 2013). A lower bound to thickness is given by the size of high  $P/T$  meta-  
morphitic slices supposed to be carried by forced return flow in a low viscosity matrix,  
and an upper bound by the requirement of high rate of return flow (e.g. Gerya and  
Stöckhert, 2006). These bounds are assumed to be on the order of 1 and 10 km, re-  
spectively. The fact that high  $P/T$  metamorphic rocks can undergo cooling during ex-  
tremely rapid exhumation requires slices or blocks of limited size, allowing effective heat  
20 transfer into a cooler environment. Embedding into a cooler environment, by whatever  
mechanism and kinematics, requires large amounts and rates of displacement, which  
in turn imply high strain rates and a complex structural evolution. A DSC is envis-  
aged to obey these conditions, invoking turbulent flow in a heterogeneous rock assem-  
25 blage, and effective mixing of material of different provenience on different length scales  
(e.g. Gerya and Stöckhert, 2002, 2006). High  $P/T$  metamorphic tectonic mélanges are  
therefore likely candidates to represent material properties in a fossil subduction chan-  
nel.





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an unresolved question. While structural geology and metamorphic petrology deal with the product of long term processes taking millions of years, seismological observations may provide evidence for the presence of a currently active DSC in situ. Here, we investigate by numerical simulations whether a DSC can be detected using seismic waves recorded at the surface. The geometry of the simple seismic model is based on that of the Hellenic subduction zone, for which geological and seismological phenomena (Meier et al., 2007) are tentatively ascribed to anomalous material extruded from a DSC beneath Crete. Seismic velocities are calculated based on predictions on temperature and pressure field and assumptions on rock composition and mineral assemblage. For the subduction channel, a block-in-matrix structure is assumed composed of a serpentine matrix and eclogite blocks, for simplicity. In the simulations, we consider seismic waves recorded in the forearc and emitted from intermediate depth earthquakes in the subducted oceanic crust or the lithospheric mantle below. These waves, spending the major part of their travel path in subducted lithosphere and overlying mantle wedge, are expected to be affected by presence of an intervening DSC with distinct properties. For comparison, we also show examples of observed waveforms from intermediate depth earthquakes recorded in the forearc of the Hellenic subduction zone.

## 2 A seismic velocity model of a subduction zone

Seismic velocities of mantle rocks are controlled by the physical properties of their mineralic constituents which in turn depend on temperature and stress state. Due to phase transitions during subduction which may be delayed by kinetic constraints on the mineral reactions, physical rock properties may also depend on the dynamics of the subduction process. Since most of the controlling factors are only known with great uncertainties, seismic velocities calculated from mineral properties should be considered as a rough estimate only.

## 2.1 Temperature model

As a first step towards seismic velocities, a temperature model of the Hellenic subduction zone is set up. We consider a vertical cross section running in north-south direction from the Cyclades to south of Crete. The structure along this transect is quite well known from previous seismological studies (Meier et al., 2007; Endrun et al., 2004; Snopek et al., 2007). Basic building blocks are from south to north: a 90 km thick continental African lithosphere in the south with 32 km thick crust on top, an accretionary wedge underlain by subducting oceanic crust and oceanic mantle lithosphere dipping at an angle of 15 degrees down to a depth of 60 km and then bending to an angle of 30 degrees at greater depths, and 60 km thick Aegean lithosphere with 20 km thick crust in the north. The subducted oceanic crust is assumed to be 7 km thick.

Based on this structural model a temperature model was developed using analytic expressions for temperature in different regions of the subduction zone. Although it is not as accurate as a numerical fluid dynamical model it approaches such models very well as shown by Davies (1999).

To calculate the complete temperature field using analytical expressions, the subduction zone is divided into several regions:

- regular crust and lithosphere north and south of the trench: use of a parabolic temperature-depth relation based on static heat conduction with internal heating down to a depth of 24 km and a temperature at the base of the lithosphere of 1250 °C.
- the mantle below the subducting plate as well as the mantle wedge below the overriding Aegean lithosphere and above the slab: temperature increase following an adiabatic gradient of 0.4 K km<sup>-1</sup>;
- the forearc zone including the accretionary wedge and the upper part of the slab dipping at an angle of 15°: here we use analytic expressions derived by Royden (1993) for the calculation of temperature in eroding orogenic belts and acce-

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tionary prisms with prescribed erosion and accretion rates and a velocity of the ingoing lithosphere of 40 mm yr<sup>-1</sup>;

- the region inside the more steeply dipping slab including a boundary layer surrounding the slab to allow for diffusion of heat: here we assume time-dependent heat conduction perpendicular to the slab dip and advection of temperature parallel to slab dip. An analytical solution to this problem has been given by Davies (1999).
- a region between the forearc zone and the steeper part of the slab where none of the above expressions are valid: here we interpolate temperature using neighbouring values.

With typical values for thermal diffusivity of 10<sup>-6</sup> m<sup>2</sup> s<sup>-1</sup> and thermal conductivity of 2.5 W (K m)<sup>-1</sup>, we obtain the temperature field shown in Fig. 2.

**2.2 Predicting seismic velocities from mineral properties**

We follow an approach by Stixrude and Lithgow-Bertelloni (2005) (SLB2005). They use an expression of the mineral’s free energy consisting of two parts: a “cold” part which contains an expansion of free energy to fourth order in the finite strain tensor and does not depend on temperature, and a “thermal” part which specifies the free energy of the vibrations of the crystal lattice in the quasi-harmonic approximation. Besides its explicit temperature dependency the thermal part also varies with strain via the lattice vibrational frequencies. The formulation is completely anisotropic and allows for the calculation of the fully anisotropic tensor of elastic constants if corresponding mineral data are available. The first derivative of free energy with respect to a small change of finite strain due to the passage of seismic waves yields the stress tensor and a further derivative gives the tensor of elastic constants. By evaluating the expressions for the elastic constants at conditions where measurements are available (zero finite strain), the expansion coefficients of the free energy can be determined. For the current appli-

5 cation, we assume isotropic finite strains and calculate the equivalent isotropic elastic constants of the medium expressed as the bulk ( $K$ ) and shear modulus ( $G$ ). To get access to the thermal part SLB2005 assume a parabolic Debye density of vibrational states with a maximum frequency that determines the Debye temperature  $\Theta_D$ . This permits an explicit representation of the internal energy, entropy and specific heat of a mineral by integrals which can be numerically evaluated. Strain dependency of the thermal part comes in via the Grüneisen tensor which is the derivative of the lattice vibrational frequencies with respect to strain. For isotropic strains we get the well-known Grüneisen constant. A complete description also requires strain derivatives of the Grüneisen tensor which possesses the same symmetries as the elasticity tensor. In the isotropic case it can be represented by two constants (similar to  $K$  and  $G$ ) which we denote by  $q$  and  $\eta_S$ . In summary, the SLB2005 theory requires the specification of the following 9 parameters at ambient conditions: molar volume  $V$ , bulk modulus  $K$  and its pressure derivative  $dK/dP$ , shear modulus  $G$  and pressure derivative  $dG/dP$ , Debye temperature  $\Theta_D$ , Grüneisen constant  $\gamma$ , Grüneisen strain derivatives  $q$  and  $\eta_S$ .

### 2.3 Mineral data base

Mineral physics data are taken from the very comprehensive data base collected by Holland and Powell (1998) (HP98), which, however, does not directly list the nine parameters needed by the SLB2005 theory. Data associated with shear deformations are completely missing and instead of Debye temperature, Grüneisen constant and  $q$ , it provides the entropy at ambient conditions, the thermal expansivity  $\alpha$  and the specific heat  $c_P$  as a function of temperature at atmospheric pressure. Since there is a strong dependency of  $\alpha(T)$  and  $c_P(T)$  on the Grüneisen constant  $\gamma$  and its bulk strain derivative  $q$  we applied a grid search to find those values of  $\gamma$  and  $q$  that best reproduced thermal expansivity and specific heat given in the HP98-database. Similarly, Debye temperature was determined by a fit to the given entropy value in HP98. This procedure worked well for most minerals (with few exceptions) with errors of less than 5 percent. Finally, to obtain values for the parameter  $\eta_S$  associated with the shear part of

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the Grüneisen strain derivative tensor, we again performed a grid search for that value of  $\eta_S$  which best reproduces the quantity  $1/(-G\alpha)(\partial G/\partial T)$  given in tables by Hacker et al. (2003b). In this way, a database of mineral parameters was compiled from which physical properties of subduction zone minerals were calculated using the SLB2005 theory.

## 2.4 Phase diagrams

A major difficulty of estimating physical properties of mantle rocks is the uncertainty about which mineral assemblages (phases) are stable at given temperature and pressure. Usually, it is assumed that only thermodynamically stable phases are present. In that case, it is sufficient to determine phase diagrams for the relevant rock facies. However, even this step is plagued by uncertainties because the rock compositions are not known very well. Even worse, observations of ultra-high-pressure rocks at the surface clearly testify that metastable phases may persist in earth's mantle for a long time and that the hypothesis of thermodynamic stability is violated. This is particularly true for subduction zones where exceptionally low temperatures inside the slab may strongly hamper phase transformations as the material moves to greater depths. For simplicity, we chose to determine the stable phase using phase diagrams calculated on the assumption of thermodynamic equilibrium. Hacker et al. (2003b) presents phase diagrams including volume fractions of the minerals contained in the phase for a typical mid-ocean ridge basalt composition, which we apply to rocks in the subducted oceanic crust, and for a harzburgitic composition which we use for mantle rocks (Fig.3). We do not perform calculations for rocks in the shallow crust since usually density and seismic velocities are fairly well known there from seismic experiments.

It should be noted that the phase diagrams by Hacker et al. (2003b) assume MORB and harzburgite to be 100 percent water saturated. This leads to the appearance of many hydrated phases in the lower left part of the phase diagrams. To avoid these phases appearing in the subducting mantle part, we instead use dry harzburgite in

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this region of the model. Dry harzburgite only exhibits the phases F, G and K of the Harzburgite phase diagram shown in Fig. 3.

The geological record of exhumed high  $P/T$  metamorphic rocks (Stöckhert, 2002) indicates that a DSC could reach down to a depth of at least 130 km. However, since the existence of a DSC is linked to the release of water from the underlying oceanic crust, a consistent petrological model should allow the presence of some water-bearing minerals at these depths. The phase diagram by Hacker et al. (2003b) predicts the transition from the water-bearing zoesite eclogite to dry diamond eclogite at a pressure of about 3.3 GPa for temperatures between 500 and 700 °C. This pressure corresponds to a depth of about 105 km which is much less than required for a deep-reaching subduction channel. Assuming a kinetic delay of the transition owing to the low temperatures in the oceanic crust, we shifted the zoesite-diamond eclogite transition in the MORB phase diagram to a pressure of 4.7 GPa or equivalent depth of 150 km.

## 2.5 Evaluation of seismic wave velocities and density

Seismic velocities are determined on a dense grid that covers the cross section of the Hellenic subduction zone shown in Fig. 2. At the grid nodes, lithostatic pressure is calculated using the vertical density distribution of a standard earth model. Temperature at the grid nodes is calculated as described above (see Fig. 2). Depending on the bulk compositions at a given grid point (continental crust, MORB, harzburgite, dry harzburgite), we look up the stable phase and its modal composition in the corresponding phase diagram (Fig. 3) and calculate elastic moduli and density for each constituting mineral using the theory of SLB2005 and the corresponding parameters in the mineral data base. Effective elastic moduli of the phase are obtained by a volume fraction weighted average of the individual reciprocal elastic moduli (Reuss average). Density is calculated by averaging the individual density values according to the volume fractions. This procedure is certainly not satisfactory as it is known that the effective elastic moduli may have varying values depending on the spatial distribution of the modal constituents inside the phase. We have chosen to display here the Reuss averaged values

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to give an impression of the variations of seismic wave speeds inside a subduction zone. Hashin-Shtrikman bounds (Hashin and Shtrikman, 1963) can be readily calculated and provide an estimate of the variability of these values. Since, however, seismic wave speeds derived from tomographic imaging represent averages over rock volumes of kilometer size, a homogenization scheme is needed to obtain accurate estimates for the effective elastic moduli of such a rock volume. This is particularly true in subduction zones where large changes of temperature and also stress may occur within small distances. Clues of the spatial distribution of rocks inside a seismically “visible” rock volume may be taken from numerical models or geological outcrops.

In Fig. 4 we show the resulting distribution of compressional and shear wave speed as well as density and quality factor down to a depth of 150 km. Velocities vary from values below 6.0/3.0 km s<sup>-1</sup> mostly in the crust to values of 8.7/4.8 km s<sup>-1</sup> in the fastest parts of the slab, respectively. We can clearly recognize the gradual velocity increase in the oceanic crust due to release of water. In the wedge above the oceanic crust we obtain very low wave speeds caused by the presence of hydrated phases. They are partially slower than in the oceanic crust leading to a positive jump of velocity at the plate contact down to a depth of 40 km. For density, we obtain a picture that correlates very well with the seismic wave speeds. Hydrous phases now show up as regions of lower density. At about 80 km depth the oceanic crust becomes increasingly dense due to the appearance of various eclogite phases.

For some numerical calculations of wave propagation shown later, we also accounted for attenuation. Attenuation in the mantle primarily depends on temperature, pressure and water content and the activation energies and activation volumes of the dissipating mechanisms. We use the following formula to calculate the inverse quality factor for our model (Karato and Jung, 1998):

$$Q^{-1} = A_0 \left( \frac{f_0}{f} \right)^\alpha \left( A_D e^{-(E_D + pV_D)/(RT)} + A_W C_{OH}^r e^{-(E_W + pV_W)/(RT)} \right)^\alpha, \quad (1)$$



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where  $E_D$  and  $V_D$  are the activation energy and volume for dissipation of dry rock, respectively, and  $E_W$  and  $V_W$  are their counterparts for water-induced dissipation mechanisms.  $C_{OH}$  is the water content in ppm H/Si,  $r$  the water content exponent and  $A_D$  and  $A_W$ , respectively, are factors determining the contributions of the two terms to attenuation.  $\alpha$  the frequency exponent and  $A_0$  is a preexponential factor chosen in a way to produce seismologically reasonable values of the quality factor.  $R$  is the universal gas constant,  $T$  is temperature and  $p$  pressure. Values chosen for the various constants are listed below. The quality factor is generally high in the area of the subducted slab due to the low temperatures prevailing there (Fig. 4). For this reason, we do not expect strong effects of attenuation on the wave propagation characteristics in the slab.

List of constants used to compute temperature and pressure dependent values for the inverse quality factor according to Eq. 1.

- $A_0$  preexponential factor – 12.5
- $f_0$  Reference frequency Hz – 0.1
- $\alpha$  frequency exponent – 0.25
- $A_D$  dry constant –  $1.25 \times 10^6$
- $A_W$  wet constant – 3.65
- $E_D$  dry activation energy  $\text{kJ Mol}^{-1}$  – 510
- $V_D$  dry activation volume  $\text{ccm Mol}^{-1}$  – 14
- $E_W$  wet activation energy  $\text{kJ Mol}^{-1}$  – 410
- $V_W$  wet activation volume  $\text{ccm Mol}^{-1}$  – 11
- $C_{OH}$  water content in ppm H/Si – 100
- $r$  water content exponent – 1.2

## 2.6 Effective seismic velocities in a subduction channel

Seismic velocities in the DSC require separate considerations. As mentioned in the introduction, we make the simplifying but reasonable assumption that the material inside the DSC is composed of eclogite blocks of various sizes floating in a low-viscosity serpentinite matrix (block in matrix structure). Since seismic waves recorded at the surface have wavelengths of a few kilometers and the typical size of the blocks is about one order of magnitude smaller, it is sufficient to consider effective seismic velocities of the composite material. They are computed using a theory of Sabina and Willis (1988) which is applicable up to frequencies where the effective wavelength approaches the size of the blocks. The theory delivers complex values for the isotropic elastic constants of an equivalent effective medium from which frequency-dependent values for wave velocities and scattering attenuation can be calculated. Controlling input parameters for the theory are the elastic constants and density of the constituting materials eclogite and serpentinite and the frequency-size distribution of the blocks. For eclogite, we used a  $P$  wave velocity of  $8.36 \text{ km s}^{-1}$ , an  $S$  wave velocity of  $4.67 \text{ km s}^{-1}$  and a density of  $3640 \text{ kg m}^{-3}$ .  $P$  and  $S$  velocities as well as density of serpentinite were taken from Hacker et al. (2003b) as  $6.0 \text{ km s}^{-1}$ ,  $2.73 \text{ km s}^{-1}$  and  $2680 \text{ kg m}^{-3}$  respectively. Recently, Bezacier et al. (2010) obtained isotropic Reuss average aggregate  $P$  and  $S$  velocities of antigorite using Brillouin-scattering of  $6.17 \text{ km s}^{-1}$  and  $3.32 \text{ km s}^{-1}$ . While the value for  $P$  velocity is consistent with Hacker's value,  $S$  velocity of Bezacier et al. (2010) is significantly higher. Moreover, antigorite and deformed serpentinite exhibit strong anisotropy (Bezacier et al., 2010) which is not accounted for in our simulations. Since samples taken from outcrops of exhumed fossil DSCs indicate a complex flow of the serpentinite matrix around eclogite blocks, we argue that the large-scale anisotropy of the block-in-matrix structure is much smaller than the one measured on pure samples in the laboratory. Nevertheless, remaining anisotropy may be a further important indicator of the existence of a DSC.

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We have done several calculations using different frequency-size distributions of the blocks that were determined by Grigull et al. (2012) from outcrops of exhumed fossil DSCs. The results show that the seismic velocities of a block-in-matrix compound lie between the end-member values for blocks and matrix and mainly depend on the relative amount of blocks and their size distribution. Since the velocity of serpentinite is relatively low and the fraction of eclogite blocks small, the effective velocity of the DSC is found to be less than the velocities of the surrounding mantle and oceanic crust. In addition, petrophysical calculations suggest that seismic velocities of serpentinite matrix are nearly constant over the entire length of the DSC because the effects of temperature and pressure approximately cancel each other. All these considerations lead to a DSC model with  $P$  wave speed of around  $6.6 \text{ km s}^{-1}$  and  $S$  wave speed of  $3.3 \text{ km s}^{-1}$  (Fig. 5).

### 3 Effects of a deep subduction channel on wave propagation

Can a subduction channel presumably less than 10 km thick be detected by seismic methods? Tomographic studies appear not to be suitable because their resolution is generally insufficient to image such a thin channel. Methods using scattered or converted teleseismic waves (Bostock, 2002; Suckale et al., 2009) have potential to reach a resolution on the order of 10 km, but it is questionable whether they could distinguish the subduction channel from the oceanic crust. An alternative approach could be to search for specific phases in the seismic records which may serve as indicators for the existence of a channel. Since the channel is a small scale feature, visible effects on the seismic wavefield can only be expected if the waves spend a considerable fraction of their propagation time inside the channel. For this reason, we consider here intermediate-depth earthquakes located in the subducted oceanic crust which directly radiate seismic energy into the subduction channel. Since both oceanic crust and channel are low-velocity regions for the major part of the propagation distance, we expect the formation of delayed high-amplitude guided waves. In the following, we will show by

numerical simulations that a thin low-velocity channel on top of the subducted oceanic crust can significantly alter the seismic wavefield observed at the surface.

### 3.1 Model setup

We use the 2-D Spectral Element Code by Komatitsch and Vilotte (1998) to simulate wave propagation in a 650 km wide and 300 km deep rectangular domain (Fig. 6). The domain is discretized into  $835 \times 96$  quadrilateral elements with 4 internal Gauss-Legendre-Lobatto points per element. Source time function is a Ricker wavelet with a dominant source frequency of 2 Hz implying a significant spectral bandwidth from 1 to 5 Hz. We computed 120 000 time steps with a sampling interval of 0.0011 s. Synthetic seismograms are calculated for a line of 130 receivers at the surface spanning the entire width of the domain with a spacing of 5 km. Receivers are numbered consecutively beginning by 1 from left (south) to right (north). Paraxial absorbing boundary conditions are applied at all boundaries except for the surface which is free. The computational domain has been chosen much deeper and wider than required to avoid disturbing reflections from the boundaries.

### 3.2 Guided $P$ waves

At first, we concentrate on the essential features of the compressional ( $P$ ) wavefield. An explosive point source is put inside the oceanic crust at a depth of 108 km. Although an explosive source can not represent a real earthquake, it proves useful here because it does not radiate shear waves which, owing to their large amplitudes, tend to obscure important features of the  $P$  wavefield in the snapshots. The general propagation situation is displayed in Fig. 6. A  $P$  wave with nearly spherical wavefront has expanded from the source. In the oceanic crust, a guided wave has formed which is already delayed compared to the wavefronts in the surrounding mantle. In addition, some PS-conversions have developed at the upper and lower boundary of the oceanic crust.

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4, attached to the oceanic crust, has developed a strong straight wavefront inside the wedge. Moreover, a secondary phase (5) has formed during travel through the serpentinized mantle wedge.

At 27.5 s after origin time, (Fig. 9b), the direct  $P$  wave (2) has just been overtaken by the slab refracted wave (1). In the model with channel (left panel), the guided phases 3 and 3' still produce the largest signals while in the model without channel (right panel) phase 4 becomes dominant and the secondary phase 5 starts to split off the main guided phase 4.

At 33 s after origin time (Fig. 9c), the slab-refracted wave (1) has left behind the slower waves and forms the first arrival. In the model without channel (right panel), the direct  $P$  wave (2) is still visible. However, phase 4 now forms the major onset closely followed by the slower phase 5. In the meantime, a  $PS$  conversion of phase 5 at the boundary between crust and serpentinized mantle wedge has also reached the surface as phase 7. In the model with channel (left panel), the guided phases 3 and 3' are still dominant but overlain by refractions from the weak guided phases 4 and 4' which are attached to the oceanic crust. The  $PS$ -conversion of phase 3 at the crust-wedge boundary (phase 7) is still very weak.

At 36.3 s after origin time (Fig. 9d), the wavefields start to unscramble. In the model without channel (right panel), phase 4 and 5 are now clearly separated. A converted  $PS$ -refraction from the slab starts to move towards the surface (phase 6). The direct phase 2 is submerged by the strong phase 4 and a reflection at the slab interface of the surface-reflected direct  $P$  wave develops (phase 8). In the model with channel (left panel), the waves 4 and 4' guided in oceanic crust start to overtake the guided phases 3 and 3'. However, they only form weak arrivals in the seismograms compared to the strong phase 4 in the model without channel.

At 42.9 s after origin time (Fig. 9e), all relevant arrivals at the surface can now be clearly recognized. The first arrival is still produced by the slab-refracted  $P$  phase (1) followed by the slab-refracted  $PS$ -conversion (6). In the model without channel (right panel), the major arrivals are now the phases 4 and 5 that took their origin as guided

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waves in the oceanic crust. They are followed by phase 8. In the model with channel, the phases 4 and 4' originating from the oceanic crust form weak arrivals preceding the dominating phases 3 and 3' that took their origin in the DSC.

With help of the snapshots, synthetic seismogram sections computed for the receivers at the surface (Fig. 10 and 11) can be readily interpreted. Remarkably, though the velocity models just differ by the presence or absence of the thin DSC, these record sections differ in the major arrivals. The pattern of onsets in the sections indeed define tell-tale signatures for the presence or absence of a DSC. The “no-channel” signature (Fig. 10) is characterized by the dominating phase 4 originating as guided wave from the oceanic crust and its follow-up phase 5 that emerged during propagation through the slow mantle wedge. An arrival between phase 2 and 3 is missing. On the other hand, the “channel”-signature is characterized by the phase pair 3 and 3' originating as guided waves from the DSC. Phase 4 is essentially missing and replaced by the weak phase pair 4 and 4'. It should also be noted that in the model with channel the combination of direct wave (1), slab refracted (2) and guided waves (3, 3') forms uninterrupted wavetrains of about 4 s length between receivers 60 and 70, a location corresponding to Crete in our subduction zone model.

To investigate whether the tell-tale signatures with respect to the presence or absence of a DSC are preserved when the source is moved up- or downwards inside the oceanic crust, we performed numerical simulations for varying source positions inside the oceanic crust (Fig. 12) for the model with DSC. If the source is too shallow, the phases 2, 3' and 3 merge and are no longer distinguishable. In our model, this occurs at source depths less than 70 km. For greater source depths, the “channel”-signature can be clearly recognized. The additional phase 3' is present in all cases. The deeper the position of the source, the longer are the guided wave trains. This behaviour is a consequence of the longer travel distance inside the waveguide formed by oceanic crust and DSC. For a source depth of 155 km the arrivals created by the guided waves become extremely long. Wavetrains of up to 10 s length can be generated without any need for small-scale scatterers inside the medium.

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The massive effect of the additional thin DSC on the seismic wavefield is again illustrated in Fig. 13 where the guided waves in the two different models are compared. Due to the low velocity in the DSC, multiple *P* reflections and *PS* conversions can build up in the waveguide and are able to conserve their amplitudes because of the velocity contrasts on both sides. Without DSC, there is no real difference between a deep or a shallow source with respect to the length of the guided wave. This behaviour is caused by the steady velocity increase inside the oceanic crust with depth due to progressive transformation of basalts into less water-bearing, denser and faster mineral phases. The oceanic crust alone starts to become an efficient waveguide only at rather shallow depths.

What happens if the source is not inside the oceanic crust but either in the mantle below or in the DSC above? We performed two additional simulations where we moved the source from its original place at 108 km depth to depths of 118 km in the slab mantle and 98 km depth in the DSC (Fig. 14). If the source is below the oceanic crust we observe a clear “no-channel”-signature despite the presence of the DSC in the model. If the source is inside the DSC, the record section is of “channel”-type. This finding may prove unfavourable for a detection of a DSC from seismic records. Earthquakes may well move into the mantle part of the slab because the temperature minimum also moves there during slab descent. On the other hand, if intermediate depth earthquakes are caused by dehydration reactions, it is highly probable that they occur in the oceanic crust which contains most of the subducted water and from where fluids are discharged into the overlying mantle wedge (Hacker et al., 2003a).

For efficiency reasons, the numerical simulations were carried out neglecting attenuation of seismic waves. To ensure the validity of the conclusions derived from the purely elastic simulations, we performed one simulation for a model with DSC assuming a spatial distribution of the quality factor as depicted in Fig. 4. The resulting record section for a source at 108 km depth does not significantly differ from the one shown in Fig. 11. In particular, the “channel”-signature is fully preserved with attenuation.



### 3.3 Guided shear waves

Are shear waves of help in distinguishing a subduction zone with DSC from one without? We performed further simulations for a double-couple source with a rupture plane striking perpendicular to the subduction direction (profile direction) and dipping 15 degrees downwards. Since the deeper part of the slab dips at 30 degrees, the angle of 15 degrees was chosen to achieve both sufficient  $P$  and  $S$  wave radiation into the oceanic crust. The source depth is again 108 km as in our reference case for  $P$  waves. The synthetic record sections are slightly more complicated because  $SP$  conversions arrive now before the guided shear waves. As for the  $P$  waves, again tell-tale signatures can be observed in the record sections which allow a discrimination between models with and without channel by one quick glance (Fig. 15). The guided shear wave signals appear within the rectangular boxes inserted into the record sections. Beyond receiver number 65, three distinct phases (3a, 3b, 3c) can be recognized for the model with subduction channel whereas there is only one for the model without. At receivers 40 to about 65, the situation reverses: the model without channel now exhibits a package of three phases while there is only one in the model with channel. The phases preceding those in the rectangular box appear for both models and are not suitable for discrimination purposes. They are the direct  $S$  wave (1), a slab-refracted  $S$  wave (2), a slab-refracted  $SP$  surface conversion (4) and a slab-reflected  $SP$  conversion (5). The snapshots in Fig. 16 provide some additional understanding of guided shear wave propagation: in the model with channel, an extended M-shaped guided wave package develops in the steeper part of the slab from which phases 3a-c develop later. As for  $P$  waves, the guided wave train in the model without channel is rather compact (Fig. 16a). Once these waves move into the serpentinized mantle wedge, they develop strong wavefronts (Fig. 16b) which keep their identity while passing through the wedge and arrive as strong individual phases at the surface (Fig. 16c).

### 3.4 Observations of guided $P$ waves in the Aegean

$P$  phases of typical seismograms from intermediate-depth earthquakes recorded in the forearc of the Hellenic subduction zone are shown in Fig. 17. The data were acquired between October 2005 and March 2007 during the EGELADOS experiment (Friederich and Meier, 2008) in the southern Aegean. The seismograms are band-passed filtered in the frequency range from 2 to 5 Hz in order to mimic the effect of the Ricker wavelet used in the numerical modelling. We selected seismograms from stations located on Crete for the most part, complemented by some low-noise ocean-bottom hydrophone records. The data records are sorted according to epicentral distance. The  $P$  signals are characterized by multiple high-amplitude wavetrains of several seconds length that are also found in the synthetic seismograms where they are produced by guided waves in oceanic crust and DSC. Long wavetrains could alternatively be generated by the scatterers of a size on the order of a wavelength. However, numerical simulations done by the authors (unpublished) indicate that the length and amplitude of the observed  $P$  wave trains can only be reproduced by placing strong, kilometer-sized velocity anomalies of 20 to 40 percent contrast into the oceanic crust. The beauty of our model is that the long, high amplitude wavetrains can be effectively generated by a simple, thin, homogeneous low-velocity channel on top of the oceanic crust.

## 4 Discussion

The fundamental question is to which extent the results of our numerical simulations can be applied to natural situations. More specifically, can seismic records that display the “channel signature” be taken to indicate the presence of a subduction channel, or, vice versa, can the absence of this signature in seismic records be taken to discard the hypothesis? At this point, it must be emphasized that the structural model of a DSC underlying our simulations is extremely simplistic, although it incorporates presumably realistic structural elements, phase assemblages and elastic properties based on min-

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eral physics. These properties are poorly constrained, mainly due to uncertainties with respect to bulk composition and mineral assemblage, widespread disequilibrium and metastability, heterogeneity on all length scales, probably steep temperature gradients and possibly complex internal structures which can only tentatively be inferred from geological observations in exhumed high  $P/T$  metamorphic terranes, leaving ample space for interpretation.

Limited by the wavelength of recordable seismic signals and the resolution of seismic experiments, our model of a subduction channel necessarily integrates over a large volume. Most importantly, it substitutes highly heterogeneous material in a real subduction channel by a homogenized, effective material which neglects heterogeneities below the kilometer-scale and temperature gradients within the subduction channel. The temperature field is expected to be controlled by the overall flow pattern which may change in space and time with a potentially strong feedback. In addition, our model adopts a simple crustal structure and is only two-dimensional. In contrast, the Hellenic Subduction Zone (HSZ) to which it is applied exhibits considerable curvature and a possibly corrugated slab shape (Knapmeyer, 1999; Papazachos et al., 2000). Finally, anisotropy inside the subduction channel is neglected, as many exposed high  $P/T$  metamorphic rock assemblages show structural patterns which cannot necessarily be expected to produce anisotropy on the length scale resolved by seismic experiments. The same holds for block-in-matrix structures taken to represent a subduction channel here.

Available data from the HSZ are not suitable to search for “channel signatures” by tracking seismic phases over epicentral distance, because the seismic stations in the forearc of the HSZ are not located on a straight profile but exhibit varying azimuths with respect to the intermediate-depth hypocenters (map in Fig. 17f). A passive seismic experiment with stations aligned parallel to the dip direction of the subducted slab, reaching from the outer rise to the backarc, could remedy the situation. In such an experiment, stations should be linearly aligned with a spacing of less than 5 km. Even though intermediate-depth earthquake data generally exhibit more complicated waveforms than those obtained from corresponding simulations, the characteristic guided

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*P* -wavetrains of several seconds length are well discernible. These strong signals, tracked and correlated over epicentral distance, would allow identification of tell-tale signatures for the presence or absence of a subduction channel. In the Aegean, as probably in most subduction zones worldwide, ocean bottom seismometers would be required besides land stations to provide the required data.

The HSZ is considered an attractive target region for this type of experiment, as an active DSC has been proposed based on independent evidence (Meier et al., 2007). These authors found that the outline of a region lacking microseismicity at a depth of about 20 to 40 km coincides with the coast line of Crete. Significant uplift of Crete since 4 Ma in an overall extensional environment is therefore suspected to be correlated with anomalous material at depth. Based on position within the HSZ, the properties are tentatively proposed to reflect extrusion of material from a DSC, which became fully established at about 4 Ma after Miocene microcontinent collision (Meier et al., 2007). The fact that only discrete parts of the forearc, forming the islands, undergo uplift may be explained by disintegration of the DSC into distinct fingers, as the radius of the curved plate interface increases towards the surface. If signatures of a DSC could be observed in a seismic experiment at the HSZ, they could be taken to add another piece of evidence in favour of the above hypothesis.

Limiting factor for any such passive seismic experiment is the occurrence of suitable intermediate depth earthquakes. For example, observations of seismicity in the Aegean (Hatzfeld and Martin, 1992) indicate that intermediate depth earthquakes cluster in a small region close to the islands Nisyros and Astypalea in the southeastern corner of the Aegean. Using these earthquakes would imply a profile across Karpathos, for which the layout requires a large share of ocean bottom seismometers. For a more convenient seismic profile across Crete, intermediate depth earthquakes further to the west along the strike of the subduction zone would be prerequisite, which are rarely observed. As a compromise, a profile oriented towards the Nisyros earthquake cluster could be feasible (green line in Fig. 17f), albeit being oblique to the dip of the slab. In

that case, one would have to cope with three-dimensional propagation effects owing to slab curvature.

## 5 Conclusions

We performed numerical simulations of seismic wave propagation in a generic subduction zone model to explore potential seismological evidence for an active deep subduction channel. The distribution of seismic velocities in our best-guess model is based on geometric and structural information, predicted temperature field, phase diagrams for MORB and harzburgite, and properties of minerals at high pressures and temperatures predicted using equations of state. The deep subduction channel itself is modelled as a thin layer located on top of the subducted oceanic crust. This layer is composed of eclogitic blocks floating in a serpentinite matrix. Homogenization calculations show that such a block-in-matrix structure exhibits frequency-dependent seismic velocities with values intermediate between those of block material and pure matrix. Since seismic velocities of serpentinite are low compared to those of typical mantle rock, and the volume fraction of eclogitic blocks is small (between 5 and 50 percent), the subduction channel is predicted to represent a low-velocity zone acting as wave guide. Petrophysical calculations suggest that seismic velocities of serpentinite matrix are nearly constant over the entire length of the subduction channel, the effects of temperature and pressure approximately cancelling each other.

Our numerical simulations focus on high-frequency seismic waves emitted from intermediate depth earthquakes. Analysis of synthetic seismograms for receivers located in the forearc indicate significant differences of  $P$  and  $S$  waveforms for models with and without deep subduction channel. Although only a very small volume of the model is covered by the subduction channel, the presence or absence of a channel is found to affect major seismic arrivals. Record sections along profiles crossing the forearc parallel to slab dip exhibit tell-tale patterns which allow to discriminate between models with and without deep subduction channel. The “channel” and “no-channel” signatures

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are found to represent stable features which remain preserved when the earthquake is shifted up or down within the oceanic crust. The signature also remains visible when the source mechanism is changed. Only in case the earthquake occurs below the oceanic crust, the “channel” signature is lost and a “no-channel” signature appears. Our results suggest that the hypothesis of deep subduction channel, explaining rapid exhumation of high  $P/T$  metamorphic rocks, might be tested by an appropriately designed seismic experiment.

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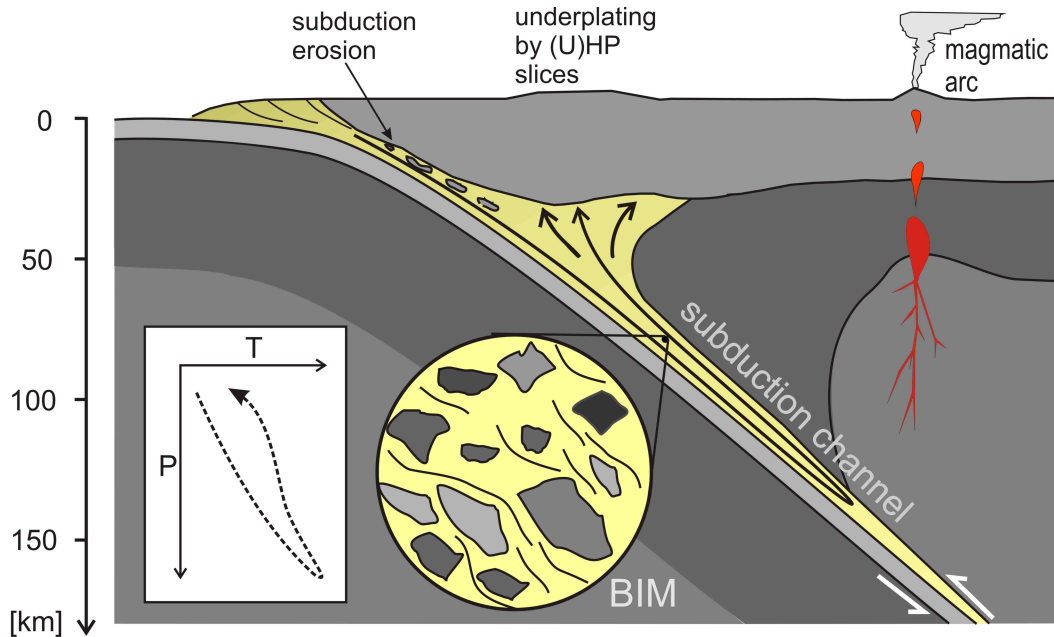
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**Fig. 1.** Envisaged geometry of deep subduction channel (DSC), including subduction erosion and underplating (after Stöckhert, 2002). Insets show scale-invariant block in matrix (BIM) structure and typical pressure-temperature ( $P$ - $T$ ) path derived for rapidly exhumed high  $P/T$  metamorphic slices.

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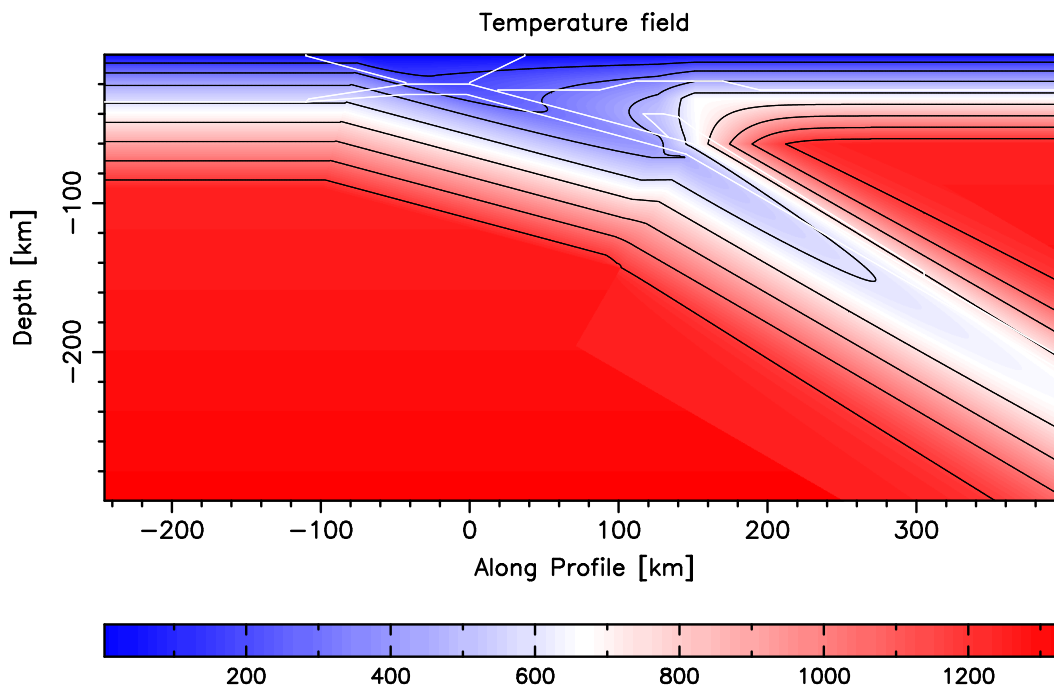
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**Fig. 2.** Temperature distribution on a vertical section through a generic subduction zone model. White lines indicate the structural regions derived from seismological studies. Temperature at the base of the lithosphere has been assumed as 1250 °C. Units: degrees Celsius

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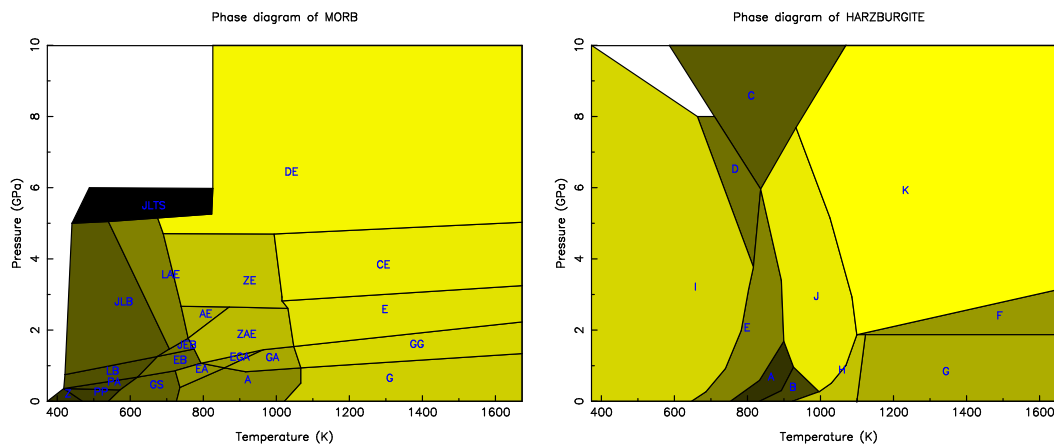
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**Fig. 3.** Phase diagrams for a typical MORB composition (left) and a harzburgite composition (right) according to Hacker (2003). Phase regions have been extrapolated to higher pressures and temperatures. Abbreviations: Left: Z: zeolite; PP: prehnite-pumpellyite; PA: prehnite-actinolite; GS: greenschist; EA: epidote amphibolite; GA: garnet amphibolite; EGA: eclogite-garnet amphibolite; A: amphibolite; G: granulite; GG: garnet granulite; LB: lawsonite blueschist; JLB: jadeite-lawsonite blueschist; CJLB: coesite-jadeite-lawsonite blueschist; JLTS: jadeite-lawsonite-talc blueschist; EB: epidote blueschist; JEB: jadeite-epidote blueschist; ZAE: zisite-amphibole eclogite; AE: amphibole eclogite; ZE: zisite eclogite; LAE: lawsonite amphibole eclogite; E: eclogite; CE: coesite eclogite; DE: diamond eclogite. Right: A: talc-chlorite-dunite; B: anthophyllite chlorite-dunite; C: phaseA-chlorite-peridotite; D: serpentine-chlorite-phaseA; E: serpentine chlorite dunite; F: garnet-harzburgite-1; G: spinel harzburgite-1; H: spinel harzburgite-2; I: serpentine-chlorite-brucite; J: chlorite harzburgite; K: garnet harzburgite-2.

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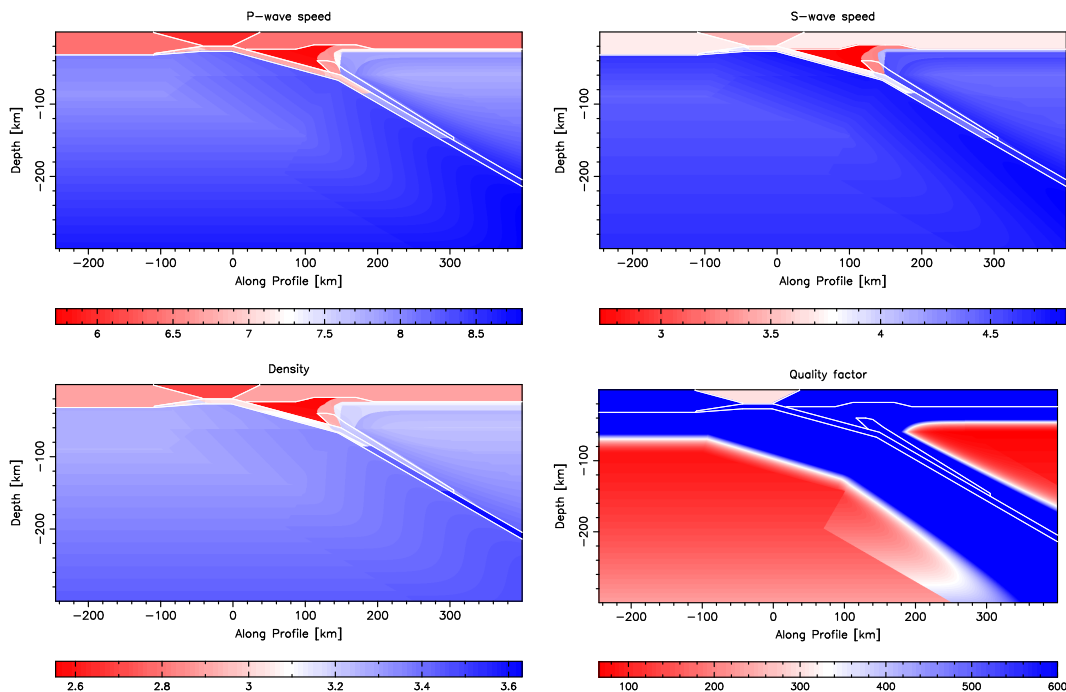
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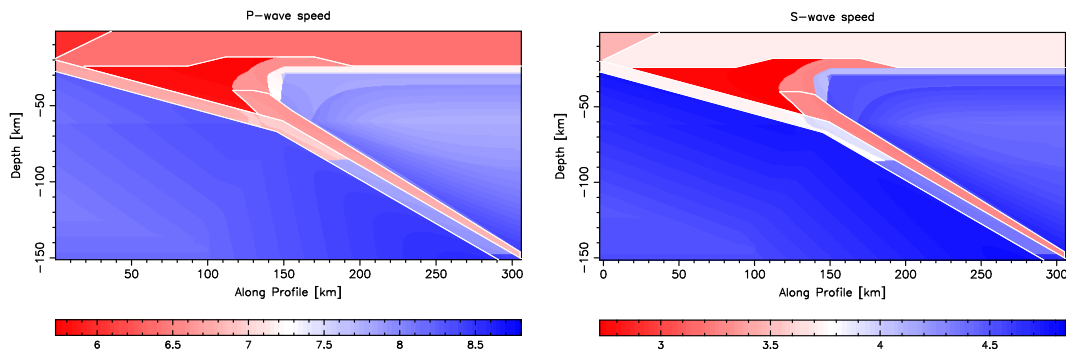


**Fig. 4.** Distribution of  $P$  wave velocities (top left) and  $S$  velocities (top right) in  $\text{km s}^{-1}$ , density in  $\text{g cm}^{-3}$  (bottom left) and quality factor  $Q$  (bottom right), calculated from the temperature model using SLB2005 theory, the phase diagrams of Hacker (2003) and our mineral data base which was derived from those of Holland and Powell (1998) and Hacker (2003).

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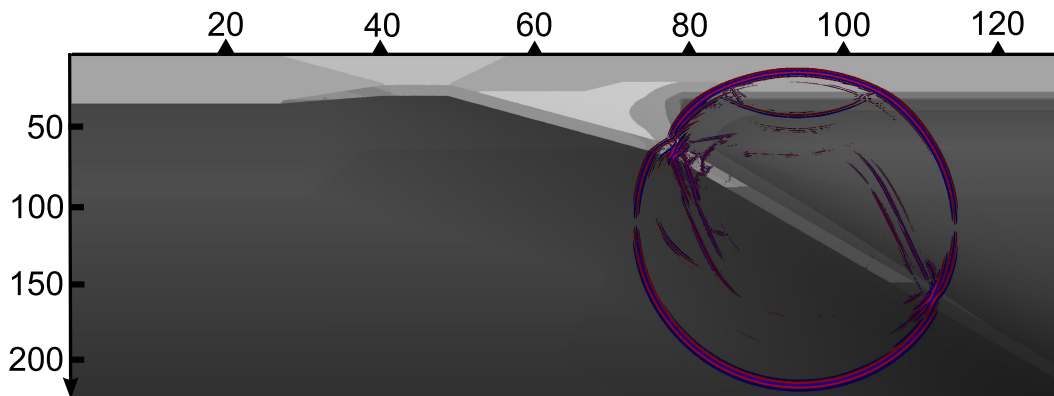
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**Fig. 5.** Distribution of  $P$  wave velocity and  $S$  wave velocity for the subduction zone model including a DSC

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**Fig. 6.** General setup of the numerical model. An explosive source radiates  $P$  waves travelling up the slab. Inside the oceanic crust, the  $P$  wave is already slightly delayed but the wavefront is still attached to the waves propagating in the surrounding mantle. At the upper and lower interface, PS conversions have developed. They can be identified by their smaller wavelength. Vertical axis annotation gives depth in km. Horizontal axis specifies index of receivers.

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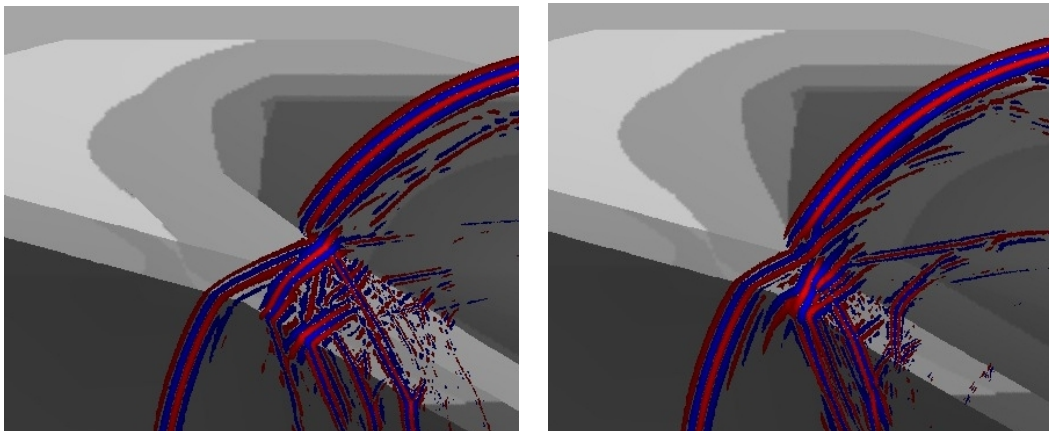
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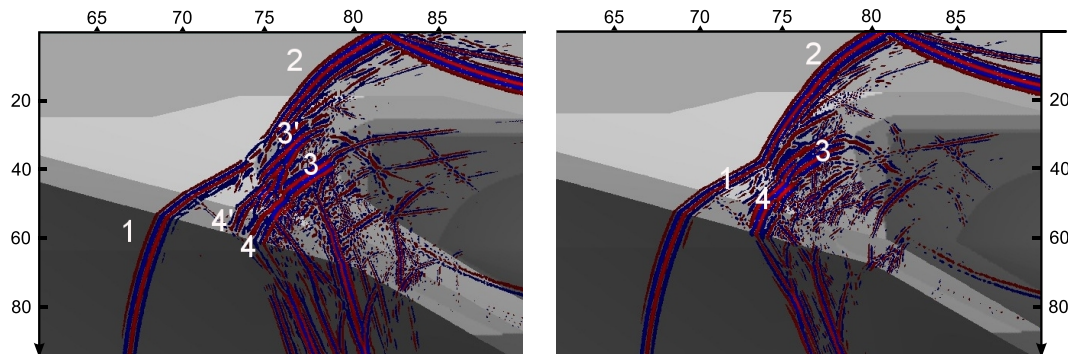
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**Fig. 7.** Snapshot of displacement field when guided waves are about to reach the bend in the slab. The wavefronts of the guided waves assume the shape of a slightly inclined letter N. Left: model with DSC. Right: model without DSC.

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**Fig. 8.** Snapshot of  $P$  wave propagation for a model with DSC (left) and without DSC (right). Propagation time is 18.15 s. Phase 1 is the slab refracted wave, phase 2 the direct  $P$  phase and 3 and 4 are guided waves. Note that in the model with DSC there are two guided waves (3, 3' and 4, 4'). Phases 4 and 4' in the model with DSC are much weaker and phases 3 and 3' are much stronger than their counterparts in the model without DSC. Numbering of phases is the same as in Fig. 10.

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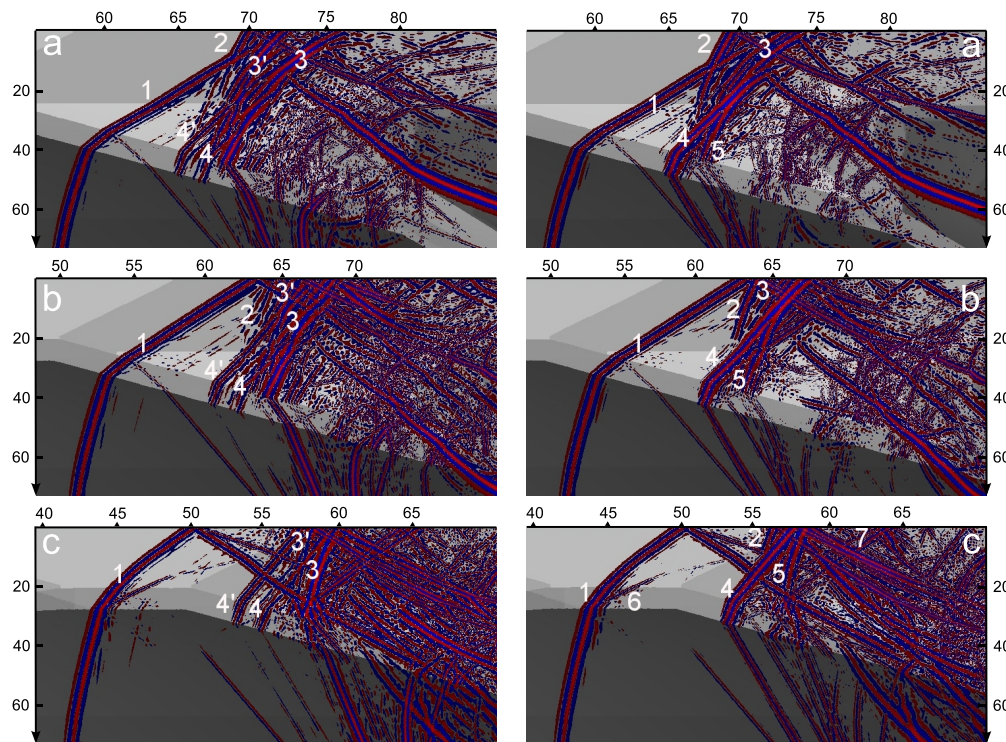
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**Fig. 9.** Sequence of snapshots illustrating the evolution of the wavefield. Left column: model with DSC. Right column: model without DSC. Vertical axis annotation gives depth in km. Horizontal axis specifies index of receivers. **(a)**  $t = 24.2$  s, guided phases 3 have reached the surface. The direct phase still forms the first onset. **(b)**  $t = 27.5$  s, slab-refracted wave 1 overtakes direct wave 2; phase 4 forms dominant signal in model without DSC and a secondary guided phase 5 develops in the slow serpentinized wedge; on the contrary, in the model with DSC phases 3 form distributed signals at the surface, phases 4 stay weak. **(c)** In the model with DSC, phases 4 overtake phases 3 and form weak precursory signals; an  $S$  conversion of phase 5 reaches the surface for the first time (phase 7) in the model without DSC.

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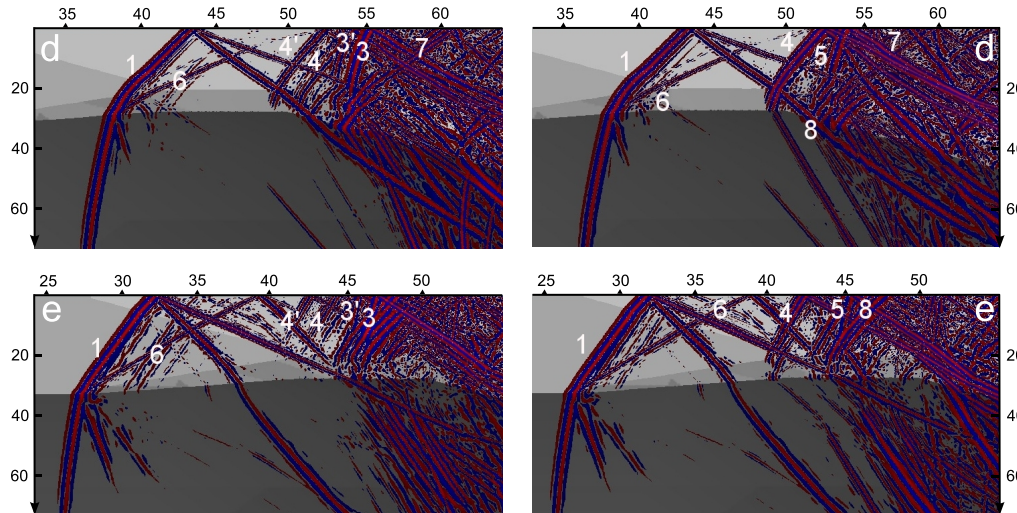
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**Fig. 9.** **(d)** The slab refracted  $S$  conversion (phase 6) becomes visible and a reflection from the slab interface of the  $P$  surface reflection emerges. **(e)** Phases 1, 6, 4 and 3 are now well separated. Strongest signal in model with DSC is phase 3. Phase 4 is strongest signal in model without DSC. Numbering of phases is the same as in Fig. 10.

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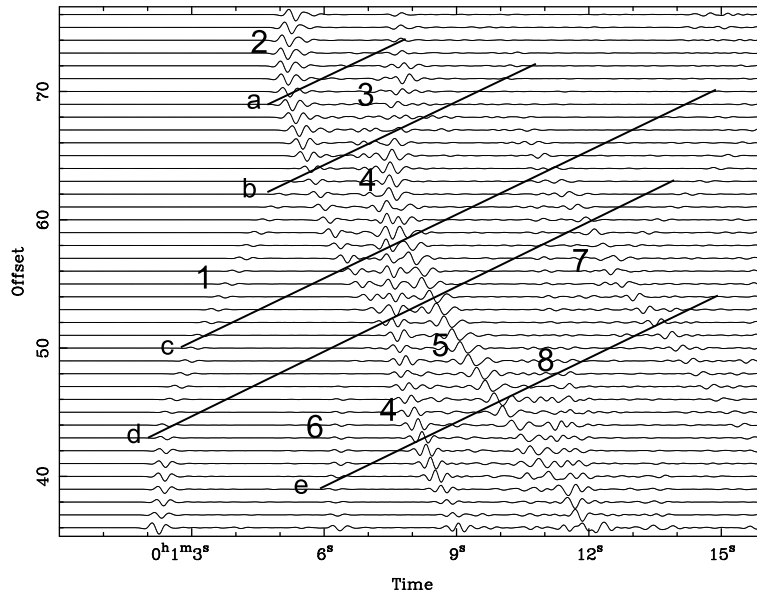
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**Fig. 10.** Model **without** DSC: time-reduced record section of synthetic horizontal component seismograms computed at receivers at the surface. Numbers from 1 to 8 mark major seismic phases. (1) *P* wave refracted at the interface between subducted oceanic crust and lithospheric mantle, (2) direct *P* phase, (3) first guided *P* phase emerging from the deep oceanic crust, (4) second guided *P* phase emerging from the deep oceanic crust, (5) third guided *P* phase developing in the serpentinized mantle wedge, (6) refracted *S* phase converted from direct *P* phase at interface between subducted oceanic crust and lithospheric mantle, (7) *S* conversion of up-going guided phase 5 at serpentinized wedge-crust interface, (8) surface reflection of direct *P* phase reflected back at slab interface. Solid lines crossing seismograms indicate lines of constant time for comparison with snapshots a–e of Fig. 9 on the right. Associated times from top to bottom are:  $t = 24.2, 27.5, 33, 36.3$  and  $42.9$  s. Source is explosive and at 108 km depth.

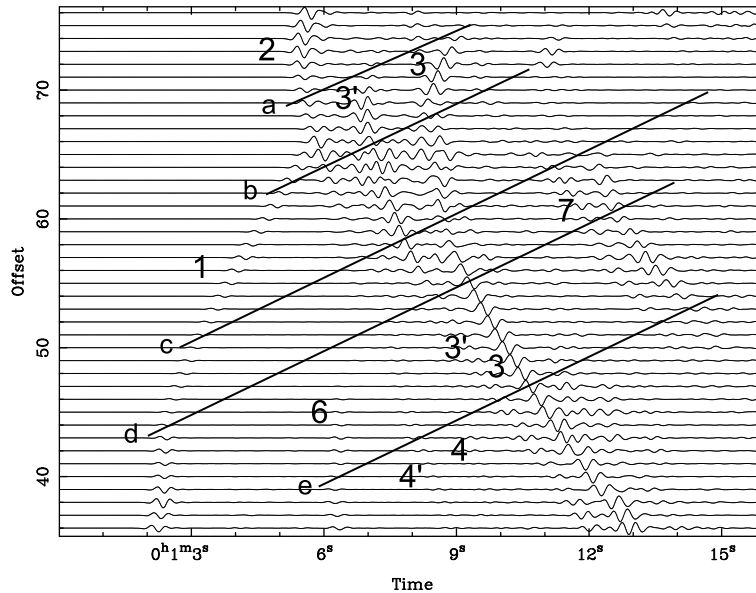
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**Fig. 11.** Model **with** DSC: time-reduced record section of synthetic horizontal component seismograms computed at receivers at the surface. Numbers from 1 to 7 mark major seismic phases. (1) *P* wave refracted at the interface between subducted oceanic crust and lithospheric mantle, (2) direct *P* phase, (3) and (3') two guided *P* phases emerging from the deep oceanic crust and radiated into the serpentized mantle wedge, (4) and (4') guided *P* phases emerging from the deep oceanic crust staying attached to the oceanic crust, (6) refracted *S* phase converted from direct *P* phase at interface between subducted oceanic crust and lithospheric mantle, (7) *S* conversion of upgoing guided phases 3 at serpentized wedge-crust interface. Solid lines crossing seismograms indicate lines of constant time for comparison with snapshots a–e of Fig. 9 on the left. Associated times from top to bottom are:  $t = 24.2, 27.5, 33, 36.3$  and  $42.9$  s. Source is explosive at 108 km depth.

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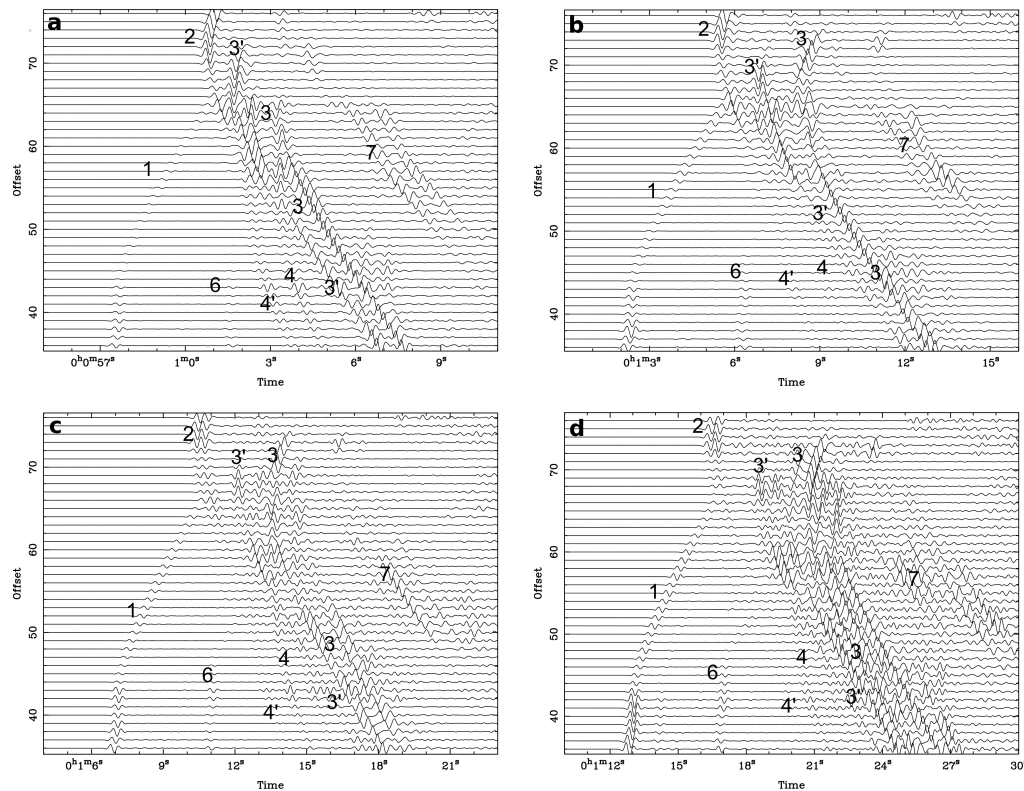
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**Fig. 12.** Time-reduced synthetic record section for the model with DSC for different source depths inside the oceanic crust. Depths: **(a)** 88 km, **(b)** 108 km, **(c)** 128 km, **(d)** 155 km. The additional phase 3' is present for all depths. Note the increasing length of the guided wave train with increasing source depth.

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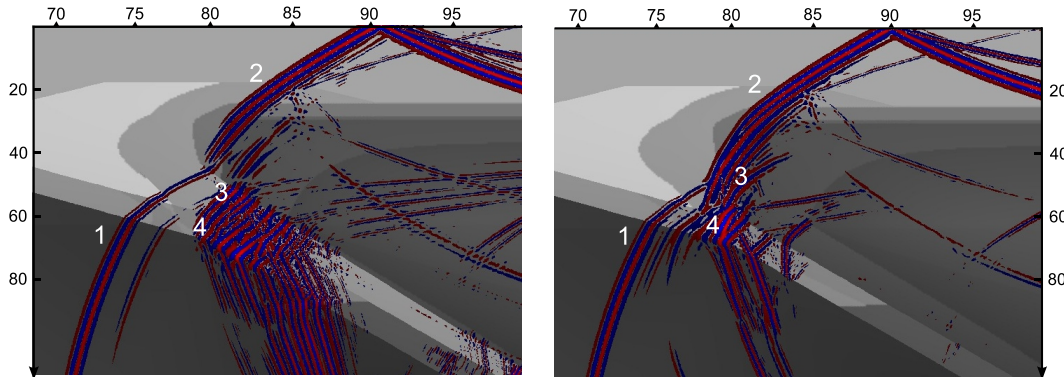
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**Fig. 13.** Snapshots for a source at 155 km depth. Left panel: with DSC. Right panel: without DSC. Vertical axis annotation gives depth in km. Horizontal axis specifies index of receivers. An extremely long guided wave package has developed in the model with DSC which produces the extended wavetrains in figure 12d (phases 3).

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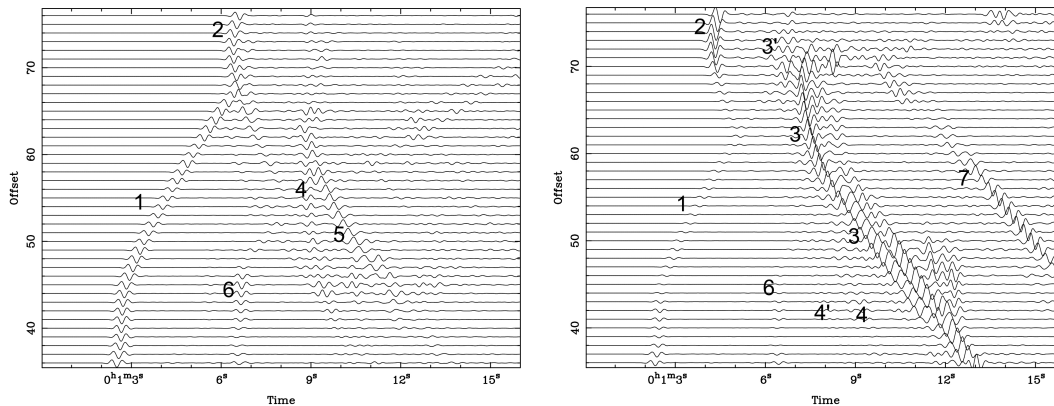
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**Fig. 14.** Time-reduced synthetic horizontal component record sections for the model with DSC and explosive sources located below the oceanic crust (left panel) and inside the DSC (right panel). In the former case, the record section exhibits a “no channel”-signature (compare to Fig. 10), in the latter case, it exhibits a clear “channel” signature (compare to Fig. 11). Phases are numbered consistent with Fig. 10 and 11.

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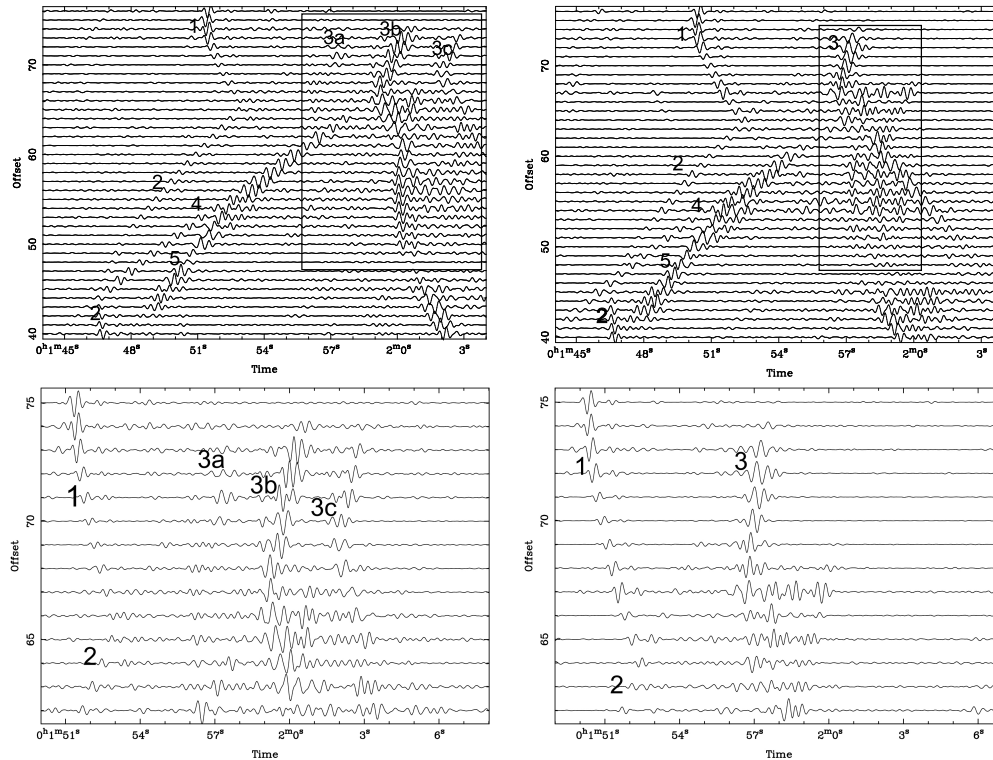
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**Fig. 15.** Time-reduced synthetic record sections for a double-couple source at 108 km depth showing *S* waves. Left panel: model with DSC. Right panel: model without DSC. Marked phases: (1) direct *S* wave, (2) *S* wave refracted at slab interface, (3) guided wave, (3a-3c) multiple guided waves in model with DSC, (4) *SP* surface conversion refracted at slab interface, (5) *SP* surface conversion reflected at slab interface. Phases 1,2,4 and 5 appear in models with and without DSC. Note the three distinct guided waves in the model with DSC. Box encloses signals related to guided waves. Lower panels: zoom into the receiver range 62 to 75 where the three guided arrivals are best visible.

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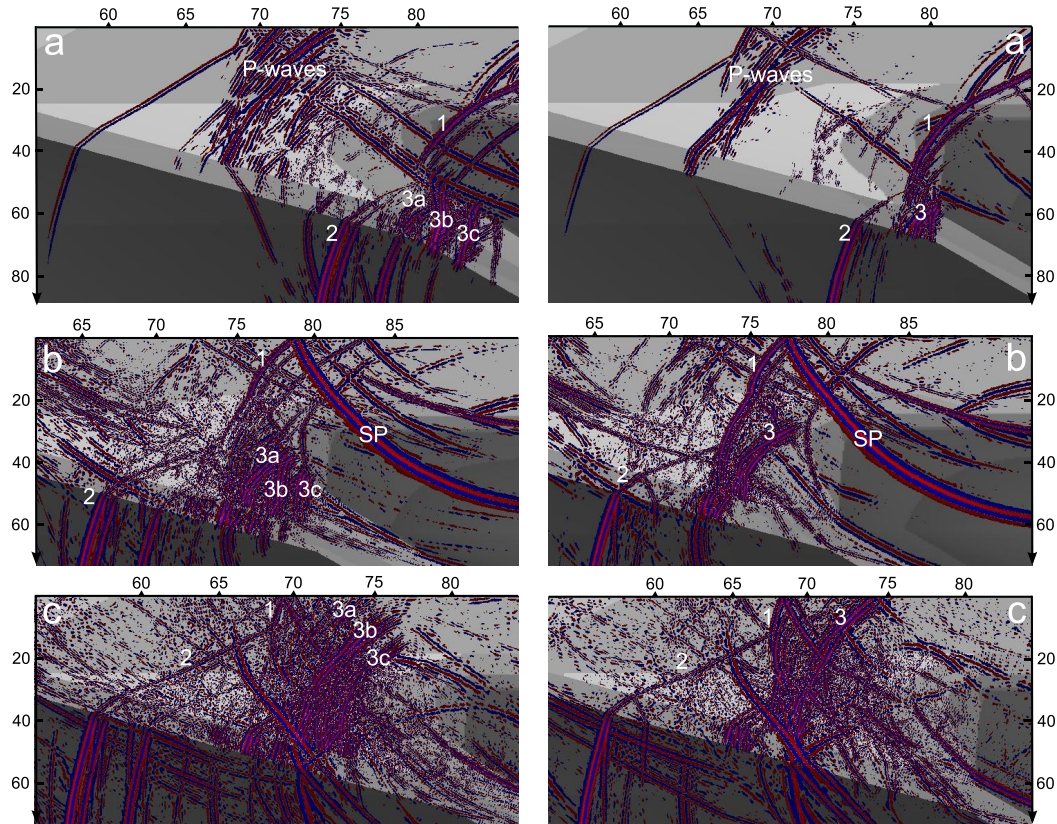
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**Fig. 16.** Sequence of snapshots for double couple source. Left panels: model with DSC. Right panels: model without DSC. Vertical axis annotation gives depth in km. Horizontal axis specifies index of receivers. Phase identification is given in Fig. 15. **(a)** Guided S waves about to enter the serpentinized mantle wedge; several wave packets have developed in model with DSC (phases 3a, 3b, 3c). **(b)** Guided wave already in serpentinized area, direct S wave already at surface, note strong SP surface conversion. **(c)** Guided waves about to reach the surface.

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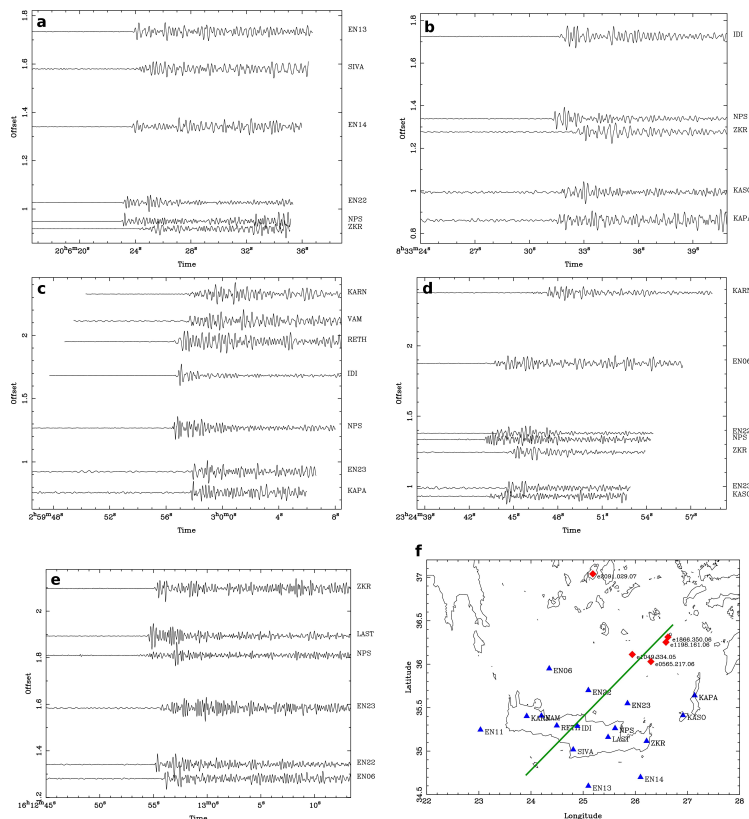
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**Fig. 17.** Examples of time-reduced seismograms for intermediate depth events recorded at stations located in the forearc of the Hellenic subduction zone as shown in the event and station map in (f). (a) Event e0565.217.06, depth 87 km, (b) event e1049.334.05, depth 99 km, (c) event e1198.161.06, depth 127 km, (d) event e1866.350.06, depth 110 km, (e) event e2091.029.07, depth 180 km. Note the multi-onset character of the *P* phases and the generally long complex wavetrains. Red diamonds in (f) show event epicenters and green line indicates possible profile for a seismic experiment.