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The dynamics of laterally variable subductions: laboratory models applied to the Hellenides

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Abstract

We design three-dimensional dynamically self-consistent laboratory models of subduction to analyze the relationships between overriding plate deformation and subduction dynamics in the upper mantle. We investigate the effects of the subduction of a lithosphere of laterally variable buoyancy on the temporal evolution of trench kinematics and shape, horizontal flow at the top of the asthenosphere, dynamic topography and deformation of the overriding plate. The interface between the two units, analogue to a trench-perpendicular tear fault between a negatively buoyant oceanic plate and positively buoyant continental one, is either fully-coupled or shear-stress free. Differential rates of trench retreat, in excess of 6 cm yr^{-1} between the two units, trigger a more vigorous mantle flow above the oceanic slab unit than above the continental slab unit. The resulting asymmetrical sublithospheric flow shears the overriding plate in front of the tear fault, and deformation gradually switches from extension to transtension through time. The consistency between our models results and geological observations suggests that the Late Cenozoic deformation of the Aegean domain, including the formation of the North Aegean Trough and Central Hellenic Shear zone, results from the spatial variations in the buoyancy of the subducting lithosphere. In particular, the lateral changes of the subduction regime caused by the Early Pliocene subduction of the old oceanic Ionian plate redesigned mantle flow and excited an increasingly vigorous dextral shear underneath the overriding plate. The models suggest that it is the inception of the Kefalonia Fault that caused the transition between an extension dominated tectonic regime to transtension, in the North Aegean, Mainland Greece and Peloponnese. The subduction of the tear fault may also have helped the propagation of the North Anatolian Fault into the Aegean domain.

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1 Introduction

At convergent margins, the negative buoyancy of the subducting lithosphere plays a first-order role in driving subduction (Forsyth and Uyeda, 1975; Chapple and Tullis, 1977). Variations in slab buoyancy occur both in time and space, for example during the subduction of oceanic plateaux that tend to decrease the average density of the subducting lithosphere (e.g. Cloos, 1993). Not surprisingly, analogue (Bellahsen et al., 2005; Martinod et al., 2005; Espurt et al., 2008), semi-analytical (Royden and Husson, 2009), and numerical (van Hunen et al., 2002; De Franco et al., 2008; Magni et al., 2012) models show that temporal variations of slab buoyancy exert a primary control on slab dip and migration of the subduction hinge relative to the upper plate. The downdip descent of positively buoyant material into the subduction zone initiates a transient mode during which the slab steepens and the subduction rate decreases. Similarly, mantle flows at lower rates about the slab, and the magnitude of dynamic deflections adjusts within the same characteristic time frame. Less clear is the role of the lateral variations in slab buoyancy on trench migration rates, arc curvature, mantle flow circulation, overriding plate deformation and topography along the subduction zone. Yet, they are common features on Earth, where seamounts, aseismic ridges, continental fragments, stretched continental margins often correspond to lateral variations in the buoyancy of slabs. Their descent into the mantle is expected to transiently affect slab geometry and mantle flow and subsequently, dynamic topography, upper plate strain and trench deformation.

Clearcut examples of such settings are the subduction of continental units adjacent to oceanic plates. The Australian continent in the Banda trench subducts underneath the Banda Sea; it is dragged along with the Indian oceanic plate that subducts in its western counterpart Sunda trench (e.g. Carter et al., 1976; Hamilton, 1979; Bowin et al., 1980). Similarly, the Adriatic plate subducts underneath the Apennines; to the south, in the Ionian Sea, the subducting plate is oceanic, possibly the oldest worldwide (Speranza et al., 2012). To the north, the bathymetry is much shallower, which

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2 Models

Our simplified subduction system is designed to reproduce the force balance in natural subduction zones, which means that the slab drives the mantle flow and its motion is resisted by viscous dissipation in the mantle, in the slab and in the overriding plate.

5 We performed a total of 11 models, following the experimental procedure proposed by Funiciello et al. (2003) and Bellahsen et al. (2005) (Table 1). The set of models aims at exploring how the lateral variation in slab buoyancy affects the kinematics of the trench, mantle flow, dynamic topography and upper plate deformation. The modeled subducting lithosphere has been divided into a positively buoyant portion and a nega-
10 tively buoyant portion (Fig. 2). Such approach has already been used to study how the subduction of positively buoyant ridges and oceanic plateaux impact the subduction dynamics (Martinod et al., 2005; Espurt et al., 2008; Martinod et al., 2013). To compare the experimental results to the kinematics of the Hellenic subduction, we restrict the length of the subduction zone within the range 1200–2400 km and we fix the sub-
15 ducting plate at its trailing edge, in analogy with the Hellenic subduction zone that is embedded into the massive, slowly moving African plate.

2.1 Setup

We use silicone putty (Rhodrosil Gomme, PDMS + iron fillers) and glucose syrup to model the lithosphere and the upper mantle, respectively. Silicone putty is a viscoelastic material. However, it can be considered as a quasi-newtonian fluid since the elastic
20 component is negligible for the applied low experimental strain rates (Weijermars and Schmeling, 1986). Glucose syrup is a transparent newtonian low-viscosity fluid. These materials have been selected to achieve the standard scaling procedure for stresses scaled down for length, density and viscosity in a natural gravity field as described by
25 Weijermars and Schmeling (1986) and Davy and Cobbold (1991).

The scale factor for length is 1.67×10^{-7} (1 cm in the model corresponds to 60 km in nature). Densities and viscosities are assumed to be constant over the thickness of

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the individual layers and are considered to be averages of the actual values. Scaling for time t is given by

where $\Delta\rho$ is the density contrast between the subducting plate and upper mantle, h is the slab thickness, and η the mantle viscosity. The density contrast $\Delta\rho$ between oceanic lithosphere and mantle ranges from 71 to 83 kgm⁻³ (corresponding to a 40 Myr-old oceanic lithosphere with a 80 % eclogitized crust; see Cloos, 1993) and that of the continental lithosphere between -35 and -43 kgm⁻³ (corresponding to a continental lithosphere with a crust thickness of ~ 16 km) (Table 1). When present, the overriding lithosphere is positively buoyant with $\Delta\rho = -35$ kgm⁻³. The viscosities of the lithospheres and upper mantle are measured with a rheometer (Physica MCR 301, Anton Paar). At room temperature and for strain rates ranging between 10⁻⁴ s⁻¹ and 10⁻³ s⁻¹, the viscosity of the silicone putty used for the oceanic lithosphere is 3.2 $\times 10^4$ Pas and the viscosity of the continental lithosphere is either 2.9 $\times 10^4$ Pas for model 1 or 6.8 $\times 10^4$ Pas for the other ones. Viscosity of the overriding lithosphere, when present, is 2.9 $\times 10^4$ Pas and the viscosity of the mantle ranges between 30 and 40 Pas. The obtained viscosity ratio between the slab and the upper mantle varies between 7.75 $\times 10^2$ and 25 $\times 10^2$ (Table 1), which is in the high range of proposed values (e.g. Billen et al., 2003; Faccenna et al., 2007; Funiciello et al., 2008; Wu et al., 2008; Loiselet et al., 2009, 2010). In the following, we directly express the quantities with their corresponding scaled values for a better relevance to real Earth.

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boundary between the two plates: (i) no lithospheric tear fault: we assume that differential buoyancy forces and rheological properties do not meet the conditions required to trigger the rupture of the lithosphere. The evolution of the oceanic and continental portions of the subducting lithosphere stay interdependent during the time of the experiment; (ii) preexisting tear fault: we assume that the rupture is instantaneous and localized at the transition between oceanic and continental lithospheres. In practice, this second case is obtained by forming a pre-existing structure precutting the subducting lithosphere at the transition between negatively- and positively-buoyant lithospheres and filling in the created gap with vaseline that prevents the two plates of silicone to stick together again during the experiment. Mechanically, it implies that shear stresses (but not the normal stresses) are negligible between the two plates.

2.2 Experimental procedure

The silicone plates are initially floating above the glucose syrup and their trailing edges are attached to the box in order to preclude any trenchward motion of the subducting plate (*fixed edge* subduction *sensu* Kincaid and Olson, 1987), in which absolute motion of the subducting lithosphere is null with respect to the lower mantle (Fig. 2). Assuming negligible horizontal strain of the subducting lithosphere, the rate of trench motion equals the rate of subduction. Spontaneous sinking of the negatively buoyant oceanic lithosphere, that initially floats over the syrup, is avoided by surface tension exerted by the syrup onto the silicone plate. The experimental subduction is always initiated by forcing the leading edge of the silicone plate into the glucose syrup to a depth of ~ 2 cm (corresponding to about 120 km in nature). We ensure that the subduction is at steady state (see Funicello et al., 2003) before the lateral transition between oceanic and continental lithospheres enters the trench. In order to meet this condition and only identify the effects of the lateral variations in slab buoyancy, the leading part of the subducting plate is made of 20 cm-long oceanic lithosphere. For descriptive convenience, we geographically orient our models, such that West is on the foreland side of the plate (the unsubducted part of the plate).

When present, the overriding plate is decoupled from the subducting plate by a thin layer of glucose syrup (see Heuret et al., 2007; Espurt et al., 2008; Guillaume et al., 2009), which reduces the shear stresses to negligible values (because stresses scale with viscosity) and prevents plates sticking to one another. It is somehow equivalent to introducing a *weak zone* in numerical models that is used to mimic the effect of a fault subduction zone (e.g. Zhong and Gurnis, 1994; G  rault et al., 2012).

The glucose syrup in some of the models is initially seeded with highly reflecting air micro-bubbles. These bubbles are used as passive tracers to map the upper mantle circulation pattern and to quantify the related velocity field using the image analysis technique denoted as Particle Image Velocimetry using the MatPIV 1.6.1 toolbox (Sveen, 2004). Tracers only slightly influence the density and viscosity of the mantle fluid. For models 8–11, when steady state is reached, the surface is spray-painted (in order to overcome optical issues due to the translucency of the glucose syrup) and scanned with a 3-D scanner (EScan 3-D Imaging System), which acquires the topography with a maximum horizontal resolution of 0.13 mm (~ 800 m in nature). The precision of topographic data is 0.05 mm (300 m in nature).

3 Modeling results

Lateral variations of slab buoyancy are accounted for by locally changing the density contrast between the slab and surrounding mantle. At this transition, the two units are either decoupled from one another by a preexisting lithospheric tear fault or not.

3.1 Trench kinematics

3.1.1 Large subduction zone with tear faulting (model 5)

The trench in model 5 is 2400 km large. W–E trench migration rate (v_t) is computed for 90 s (~ 1.2 Myr) time steps and 1 cm (60 km) steps along the trench (Fig. 3a, b). Trench kinematics follow a 4 stage evolution:

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- i. For the first 6 Myr, the oceanic plate is sinking into the upper mantle, slab pull force progressively increases and trench retreat velocity reaches values as high as $6\text{--}8\text{ cm yr}^{-1}$ (Fig. 3a, b).
- 5 ii. Once the slab reaches the bottom of the box, oceanward trench motion slows down and stabilizes at $\sim 4.5\text{--}5\text{ cm yr}^{-1}$. v_t is slightly higher in the center of the subduction zone with values of $\sim 5\text{--}5.5\text{ cm yr}^{-1}$ (Fig. 3a, b).
- 10 iii. The third stage starts with the onset of continental lithosphere subduction in the northern half of the subduction zone after 11 Myr and stops when the offset along the vertical tear fault in the center of the subduction zone develops after 20.5 Myr. In the northern part, the average negative slab buoyancy progressively decreases, and the subduction and trench velocities drop. In the center of the northern unit ($y = 500\text{ km}$), trench motion switches from retreat to – moderate – advance after a period of $\sim 8\text{ Myr}$ (Fig. 3a, b) when $\sim 125\text{ km}$ of continental lithosphere has subducted. Closer to the lateral transition between continental and oceanic units ($y = 100\text{ km}$), the decrease in trench migration rate is slower; for 15 the 9.5 Myr duration of this third stage trench velocity drops from 5 to 0.5 cm yr^{-1} (Fig. 3a, b). On the oceanic side ($y = -100\text{ km}$), the decrease of v_t is more limited, with values just below 3 cm yr^{-1} after 20.5 Myr. Farther from the central discontinuity ($y = -500\text{ km}$), the arrival at trench to the north of the continental lithosphere does not decrease the trench retreat velocity, as observed elsewhere. Instead, v_t 20 slightly increases from 5 to 6 cm yr^{-1} between 11 Myr and 20.5 Myr (Fig. 3a, b), meaning that the lateral influence of a decrease in slab buoyancy vanishes at remote locations ($> 500\text{ km}$).
- 25 iv. After 20.5 Myr, the differential trench retrograde motion between the oceanic and continental units offsets the two plates along a vertical tear fault (Figs. 3a, b and 4a). On its northern edge ($y = 100\text{ km}$), v_t keeps decreasing and eventually switches from oceanward to continentward motion with values up to 1 cm yr^{-1}

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(Fig. 3a, b). Instead, on its southern edge ($y = -100$ km), v_t instantaneously increases from 3 to 6 cm yr^{-1} . Farther from the tear fault, changes in trench kinematics are less important. In the center of the southern unit ($y = -500$ km), v_t slightly increases to $\sim 6.5 \text{ cm yr}^{-1}$, $\sim 30\%$ higher than trench retreat velocity during stage 2 when the width of the slab was about twice as large. Finally, the limited decrease in v_t to the south of the tear fault after ~ 23 – 24 Myr are edge effects, as the slab reaches the end wall of the tank.

The retrograde motion of slabs causes the development of toroidal cells at slab edges (Dvorkin, 1993; Funiciello et al., 2006; Piromallo et al., 2006). In the model, the persistent rollback of the oceanic lithosphere to the south excites such a mantle flow that opposes the retrograde motion of the northern continental lithosphere, which explains the decreasing v_t , and even slight advance, to the north.

3.1.2 Large subduction zone without tear faulting (model 8)

In this model, the subduction of positively buoyant lithosphere after 15 Myr also strongly modifies the trench kinematics (Fig. 3c, d). But unlike model 5, along-trench variations of trench velocity are less pronounced. In details, 10 Myr after the entry of positively buoyant lithosphere, the difference of trench velocity between regions located 500 km north and south of the discontinuity is $\sim 3 \text{ cm yr}^{-1}$, half the value observed for model 5 (6 cm yr^{-1}) (Fig. 3b, d). It also holds for regions closer to the discontinuity. The difference in trench velocity 15 Myr after the onset of continental subduction between regions located 100 km away from the discontinuity is restricted to $\sim 1 \text{ cm yr}^{-1}$ for model 8 as opposed to $\sim 6 \text{ cm yr}^{-1}$ for model 5 (Fig. 3c, d). Because in the absence of a tear fault, shear stresses are high between the two plates, they remain coupled throughout and the kinematic evolution of the north and south trenches is never independent from one another. Thus the absence of slab segmentation at the junction between regions with variable buoyancy results in a global slow down of trench motion along the entire subduction zone.

3.1.3 Narrow subduction zone with tear faulting (model 11)

The setups of models 11 and 5 are similar except for the width of the subduction zone, which is half as large in 11 (1200 km vs. 2400 km). It also follows a comparable 4 stage evolution (Fig. 3e, f). During stage 2, the trench migrates slightly faster than in model 5 (5.5–6 vs 5 cm yr⁻¹), in agreement with previous models that show that narrower slabs retreat faster (Guillaume et al., 2010). At the beginning of stage 3 after 18 Myr, trench retreat velocity decreases all along the subduction zone. In the center of the oceanic unit of the subducting lithosphere, where the migration rate slightly increases in model 5, model 11 instead shows a 50 % decrease of v_t .

There is also a delay in the time of tear faulting with respect to the large subduction zone model. It occurs ~ 25 Myr after the positively buoyant unit reaches the trench in model 11 instead of 10 Myr in model 5. This can be explained by the lateral lower variability in trench migration rate that increases the delay necessary for the tear fault to open. In both cases however, the segmentation of the slab at depth occurs when the difference in amount of trench retreat between both sides of the discontinuity reaches values of 200–250 km.

3.2 Trench shape and depth

Figure 4 shows the evolution of trench shape through time for the large subduction zone models with (5) or without (8) tearing. At first order, both models share a common geometry that is controlled by the along-trench variability of trench motion. During stages 1 and 2, the trench retreats faster at the center of the subduction zone than along the edges, which promotes trench curvature. After the arrival of continental lithosphere to the north, the trench remains almost stationary in the northern part whereas in the southern part retrograde motion of the subducting plate continues. This subsequently causes the formation of a concave trench to the south and an almost-linear trench to the north. The transition is sharp in model 5. The lithospheric fault offsets the trench position at an average velocity of ~ 7 cm yr⁻¹, giving a cumulative offset of 500 km after

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7 Myr. Model 8 instead shows continuous transitions from fast trench retreat south of the discontinuity to a stationary – or slowly advancing – trench to the north ~ 16 Myr after continental subduction. The difference is here accommodated by slab deformation on a roughly 400 km wide band (Fig. 4b).

5 Trench depth is also sensitive to along-trench variations in slab buoyancy. We scanned the surface elevation of the model (Fig. 5a) in order to compare the along-trench variations of minimum trench elevation with the corresponding trench migration rate for model 11 (Fig. 5b). Before the subduction of the buoyant lithosphere (16.5 Myr), both trench elevation and trench migration rate are uniform along the entire subduction zone with a ~ 10 km deep trench (below reference level, here the mean mantle surface elevation far from the subduction zone) associated to a trench velocity of 6 cm yr^{-1} .
10 Instead, after 40 Myr, when up to 250 km of buoyant material has entered the trench, trench elevation varies laterally, with a maximum depth in front of the continental unit restricted to ~ 2 km. Figure 5c displays the relationship between trench velocity and trench elevation for points sampled every 60 km along the trench at different times of the same model. Faster trench migration rates match deeper trenches. In these models, the trench depth results from the competition between the buoyancy stresses in the glucose syrup, that tend to restore uniformity, and the shear stresses exerted by the slab that impose the downward flow of the glucose syrup (see Husson et al., 2012).
15 Response of trench topography to variations of trench kinematics is instantaneous and for instance, faster trench retreat of the oceanic part of the subduction zone occurring after slab segmentation at 42 Myr results in a deepening of the trench, from 9 to 11 km at 40 Myr to 11 to 12 km at 46.5 Myr (Fig. 5c). Although the shear stresses between the slab and mantle linearly depend on trench velocity, the relationship shown on Fig. 5c breaks down for low trench retreat rates or advancing trenches because of the effect of
25 surface tension whose magnitude is independent on the kinematics.

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3.3 Mantle flow

Horizontal velocities (v_h) are computed at the surface of the glucose syrup and silicone plate in the model 11 (that has no upper plate) using Particle Image Velocimetry (PIV) on top-view images with a pixel resolution of 0.25 mm and time intervals of 30 s.

PIV relies on basic pattern matching, which reconstructs the Eulerian velocity field on a regular grid (Adrian, 1991; Nogueira et al., 2001, among others). We use a multipass cross-correlation analysis with a 50 % overlap of the interrogation regions.

Figure 6 displays the horizontal velocity vectors and the magnitude of both W–E and N–S components of the horizontal velocity field 20 Myr, 25 Myr and 40 Myr after subduction initiation for model 11. During the early stage of uniform subduction (20 Myr), the retrograde motion of the subducting panel results in the formation of two toroidal cells centered on the slab edges (Fig. 6, see also Funiciello et al., 2006; Husson et al., 2012). The pattern of mantle circulation is almost symmetrical with (i) fast westward particle motion in the center of the subduction zone with maximum velocities ($v_{h(W-E)} \approx 6 \text{ cm yr}^{-1}$) (Fig. 6b), similar to the westward trench migration rate at the same period, (ii) fast eastward flow ($v_{h(W-E)} > 4 \text{ cm yr}^{-1}$) at the edges of the subduction zones (Fig. 6b).

The early stage of the subduction of continental lithosphere (25 Myr) records variable trench migration rates along the trench (Fig. 3e, f). This directly affects horizontal velocities in the mantle with an asymmetry in the westward particle motion between regions in front of the oceanic unit ($v_{h(W-E)} > 4 \text{ cm yr}^{-1}$) and in front of the continental unit ($v_{h(W-E)} \sim 2 \text{ cm yr}^{-1}$) (Fig. 6b). Even if the surface involved in mantle flow has not significantly decreased with respect to the previous stage, the average motion of particle has slowed down both in the W–E and N–S directions owing to the overall decrease in trench migration rates (Fig. 6b, c).

After 40 Myr of subduction, a switch in mantle flow direction occurs in front of the continental unit, particles moving eastward at low velocities ($v_{h(W-E)} < 0.5 \text{ cm yr}^{-1}$) (Fig. 6b). In front of the oceanic unit instead, the motion remains westward with maximum

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velocities at $\sim 4 \text{ cm yr}^{-1}$. In the mantle wedge just above the slab, mantle flow is mainly trench-perpendicular with fast motion for the oceanic unit whereas above the continental unit, it is mainly trench-parallel with low magnitude.

3.4 Overriding plate deformation

We measure the horizontal strain within the overriding plate at different times of the experiment by tracking the displacement of grid nodes initially evenly-spaced by 60 km. Owing to the newtonian behavior of the silicone used to model the overriding plate, deformation is continuous. Figure 7 presents the displacement field and main strain directions recorded during three time intervals for model 1.

Before the arrival of continental lithosphere at the trench (0.5–14.5 Myr), the finite displacement of the overriding plate with respect to the lower mantle reference frame is larger at its western edge than at its eastern edge, resulting in trench-perpendicular stretching (Fig. 7a). Stretching is not uniform, owing to differential shear stresses exerted at the lithosphere–asthenosphere boundary that resist the trenchward motion of the upper plate. It is maximal within the first 120–180 km from the trench (Fig. 7a) and decreases away from the boundary. Local trench-parallel stretching at the southern and northern edges of the upper plate results from the free lateral boundary conditions that allow the silicone plate to spread laterally above the low-viscosity glucose syrup under the effect of gravity.

The early stage of continental lithosphere subduction (14.5–25 Myr) is associated to a 30 to 60 % decrease in trench retreat rates along the entire subduction zone (Fig. 3g, h). Its deformation decomposes into translation (herein irrelevant), plain rotation and stretching. During this period, the grid nodes rotate clockwise around a pole located $\sim 500 \text{ km}$ north of the northernmost extent of the overriding lithosphere (Fig. 7b). Overriding plate mainly deforms through laterally non uniform stretching. For the first 180 km from the trench, trench-perpendicular stretching occurs in front of the oceanic unit about twice faster than in front of the continental unit ($\sim 3 \times 10^{-16}$ vs. $\sim 1.5 \times 10^{-16} \text{ s}^{-1}$).

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Region of maximum trench-perpendicular stretching coincides with the area where the gradient of the east-west component of horizontal mantle flow at the top of the asthenosphere is maximum (Fig. 6b), i.e. where shear stresses underneath the lithosphere are the highest. Within the first 60 km in front of the continental–oceanic transition, the overriding plate mainly deforms under moderate trench-parallel shortening (Fig. 7b).

In the final stage (25–38.5 Myr), the difference in along-trench kinematics results in a clockwise rotation of grid nodes with a rotation pole located on the trenchward edge of the overriding plate in front of the continental unit (Fig. 7c). Despite the almost null motion of the trench at the location of the continental unit, the trenchward edge of the overriding plate north of the oceanic-continental transition still deforms under trench-perpendicular stretching at higher rates than recorded before ($> 3 \times 10^{-16} \text{ s}^{-1}$) (Fig. 7c). Deformation here is controlled by stresses arising from the far-field, associated with trench retreat for the oceanic unit at moderate rates ($2 \pm 1 \text{ cm yr}^{-1}$) (Fig. 3g, h). Within the first 60 km from the trench, the center of the overriding plate is dominated by trench-perpendicular shortening (Fig. 7c), as a result of the indentation of the continent. Indeed at this specific location, retreat of the oceanic lithosphere to the south triggers the westward absolute motion of the overriding plate at a faster rate than the westward absolute trench motion, slowed down by the subduction of positively buoyant lithosphere to the north. Beyond 120 km, upper plate deforms under a combination of moderate stretching and shortening, the principal axis of stretching rotating from trench-perpendicular on its edges to trench-parallel in its center (Fig. 7c).

3.5 Dynamic topography

Long-wavelength, non-tectonic uplift or subsidence counterbalance the vertical traction caused by the flowing mantle underneath the lithosphere. Ultimately, this flow is excited by density variations in the mantle, and that component of the topography is often referred to as dynamic topography (Ricard et al., 1984; Hager et al., 1985; Hager and Clayton, 1989; Cazenave et al., 1989; Mitrovica et al., 1989; Gurnis, 1993; Le Stunff and Ricard, 1995). Above the anomalies of the slabs, the amplitude

of dynamic subsidence can exceed several hundred meters (Mitrovica et al., 1989; Gurnis, 1993; Zhong and Gurnis, 1994; Husson, 2006; Husson et al., 2012).

We track the vertical deformation of the model surface with a scanner during subduction in model 11 and in particular at the top of the asthenosphere above the subducting lithosphere, north and south of the discontinuity (Fig. 8).

The subduction of buoyant material after ~ 18 Myr of subduction induces an instantaneous response of the surface for the northern continental subduction zone with an uplift of around 0.7 km in ~ 3 Myr at 250 km from the trench (Fig. 8b). Conversely, in the oceanic portion of the subduction zone, although the trench retreat velocity strongly decreases, the variations in surface elevation remain elusive during ~ 10 Myr (Fig. 8c). However, between 30 and 42 Myr, the surface uplifts of ~ 0.7 km, which may be explained by the influence of positively buoyant material to the north, that globally decreases the subduction rate, and as such, the vertical traction exerted by the mantle on the surface.

Surface motion at 500 km from the trench appears insensitive to changes in slab buoyancy (Fig. 8b, c). However on the long-term, the surface gently uplifts at rates of $\sim 0.02 \text{ mm yr}^{-1}$ for both continental and oceanic subductions between 18 and 42 Myr. Dynamic topography being directly sensitive to the vertical component of mantle flow, it once more reflects the fact that during that time interval the vigor of the horizontal mantle flow has decreased (Fig. 6) but also the vertical traction underneath the surface as a result of the overall decrease in slab buoyancy.

After 42 Myr, the tear fault decouples the continental and oceanic units, which strongly modifies the dynamic topography above the oceanic portion of the subduction zone. A ~ 1.7 km downlift of the surface is recorded at 250 km from the trench, yielding a subsidence rate of $\sim 0.3 \pm 0.1 \text{ mm yr}^{-1}$ (Fig. 8c). Decoupling the two slab segments results in a lesser reciprocal influence, in the sense that the kinematics no longer correspond to an average buoyancy of some kind. The narrow oceanic slab unit then subducts at its proper rate, faster than the initial rate that corresponds to a wide slab. Subduction becomes more vigorous, and dynamic topography exceeds by 1000 m

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its initial value, prior to the entry of the continental unit into the subduction zone. This additional 1 km downlift is therefore a consequence of mantle flow reorganization associated to slab narrowing, which in this case promotes faster vertical sinking of the slab.

4 Comparison to the Hellenic subduction

4.1 Geological setting

The Hellenic subduction is a small remnant of the vast Tethyan subduction that drove the collision of Africa and Eurasia (Fig. 1). Another few of those small subduction zones are found in the Mediterranean (e.g. Royden, 1993; Malinverno and Ryan, 1986) but the Aegean slab is probably the last that remains powerful enough to be considered an active tectonic system, for the subducting Ionian lithosphere could be the oldest seafloor on Earth (Speranza et al., 2012). In the general framework of the now very slow African-Eurasian collision, the subduction of the Aegean slab, that is attached to Africa, resembles the *fixed* mode of subduction of our models. Fast rollback accompanied the subduction, triggering pervasive lithospheric extension in the Aegean domain (see Jolivet et al., 2013, for a review), trenchward migrating volcanism and exciting adjacent mantle flow (Paul et al., 2010).

However, this activity did not prevail throughout the entire Tertiary (e.g. Papanikolaou and Royden, 2007; Brun and Sokoutis, 2010; Royden and Papanikolaou, 2011; Jolivet et al., 2013). The Aegean domain globally spreads until Mid-Miocene, until the right lateral *North Anatolian Fault* (NAF) isolated Anatolia from the Eurasian continent (Sengör et al., 2005; Royden and Papanikolaou, 2011), cut through the Marmara Sea and reached the Aegean Sea and formed the *North Aegean Trough* (NAT). During that early stage, lithospheric stretching accommodated slab retreat and faults trended parallel to the uniformly retreating trench.

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Then, a brief Late Miocene to Early Pliocene episode of localized arc parallel extension occurred in the outer rim of the Hellenic arc, in the Cretan Sea and Peloponnese in particular (Fig. 9a). This event is coeval to the inception of the right lateral Kefalonia Fault (Papanikolaou and Royden, 2007) which, from Pliocene onwards, further modified the kinematics of the area. The subduction of a plate of laterally variable buoyancy along the Hellenic trench could have profoundly modified the Aegean dynamics. Indeed, since Late Miocene times, the Kefalonia Transform Fault isolates the Adriatic continental unit from the Ionian oceanic plate (Kahle et al., 1993; Vassilakis et al., 2011). Subduction rates at the North and South Hellenic trenches occur at rates of 5 to 12 mm yr⁻¹ and 25 to 40 mm yr⁻¹ (e.g. McClusky et al., 2000; Royden and Papanikolaou, 2011; Pérouse et al., 2012), respectively, which offsets the South and North Hellenic subduction zones by a few tenths of kilometers at present day. The formation of the fault itself results from the entry in the subduction zone of a very negatively buoyant oceanic plate to the south, while in the north the subduction of a continental unit of increasingly positive buoyancy proceeds, as the buoyancy difference of the two plate units suffices to trigger a laterally variable regime along the trench (Royden and Papanikolaou, 2011).

The Aegean Sea then migrated along with the trench to the South-West (with respect to stable Eurasia), as an apparently almost rigid unit (McClusky et al., 2000; Kreemer and Chamot-Rooke, 2004). Extension is now focussed in the *West Anatolian Shear zone* (WASZ), on the western margin of Turkey, in the Peloponnese and in Mainland Greece (Gautier et al., 1999; Jolivet et al., 2013; Royden and Papanikolaou, 2011, Fig. 9b). Only in Mainland Greece and Peloponnese deformation remains somewhat diffuse (Vassilakis et al., 2011; Bradley et al., 2013); only in this area the Anatolian plate is not separated from Eurasia by a discrete right lateral fault. The Kefalonia Fault could be linked to the North Anatolian Fault via the diffuse transtensional *Central Hellenic Shear zone* (CHSZ) (Royden and Papanikolaou, 2011) that separates the Peloponnese from Mainland Greece (Fig. 9b). In this area, normal faults, including the Corinth Rift, developed obliquely to the trench. From north to south, faults trend ~ N90 in Mainland

Greece, gently swing to \sim N120 across the Gulf of Corinth, and reach \sim N170 (approximately trench parallel) in the South Peloponnese (e.g. Doutsos, 2001). From the western tip of the NAF to the Kefalonia Fault (i.e. in the NAT and CHSZ), only normal faulting is unequivocally identified; this lead Pérouse et al. (2012) to advocate that the

GPS inferred strain field does not require any dextral shear component in this area.

Despite the inherent oversimplifications of our experimental setup, our dynamic models resemble the Hellenic subduction by many aspects. The Kefalonia Fault shall be considered as the tear fault (possibly shear-stress free) that isolates plate units of contrasted buoyancies. In the following, we interpret the observables for the Hellenic subduction (trench and upper plate kinematics, mantle flow and topography) at the light of our dynamic models.

4.2 The Hellenic trench

The Hellenic trench initially migrated continuously along the outer rim of the Aegean domain. It accompanied the global expansion and spreading, that is well reproduced by our models, where the initially linear trench becomes concave during trench retreat (Fig. 4), as in earlier models (e.g. Funicello et al., 2003; Morra et al., 2006; Loiselet et al., 2009). The shape of the trench responds efficiently to the entry of a plate of laterally variable buoyancy into the subduction zone. In the models, it corresponds to the introduction of a low buoyancy unit that locally decreases the trench migration rates (Fig. 3); in the Hellenides it is the introduction of the old Ionian oceanic lithosphere after the consumption of the Adria block that speeds up trench migration to the south. In both cases, the difference in trench migration rates imposed by lateral slab buoyancy variability increases by a few tenths of mm yr^{-1} after a few million years. It is accompanied, in the models, either by a viscous shear of the subducting plate when no built-in tear fault accommodates the differential trench motion, or by a right lateral slip along the tear fault when present (Fig. 4). This setting is akin to the Kefalonia Fault, and we confirm that it is this mechanism that excites the Kefalonia Fault and that offsets the margin of the overriding plate by some $\sim 100\text{ km}$ at a rate of ~ 14 to 25 mm yr^{-1} (Vassilakis et al.,

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2011; Royden and Papanikolaou, 2011). This value corresponds to the difference in the trench velocities of the northern and southern Hellenic subduction zones, a figure that is also obtained in the models after a few million years (Fig. 3). Interestingly, the models show that it takes more than ~ 4 Myr, i.e. the time since the onset of the activity of the Kefalonia Fault, before steady state is reached. This suggests that the slip rates along the Kefalonia Fault may be accelerating and continue to speed up in the future (along with an acceleration of the southern trench migration, as also shown by Royden and Papanikolaou, 2011).

Trench depth varies along strike; while in the Northern Hellenides the trench is shallower than ~ 1000 m, in the southern counterpart, it is more than 3000 m deep (Fig. 11). The absolute trench depth in the models overshoots that figure by 5000 to 8000 m (Fig. 5b, c, and Husson et al., 2012), because our setup does not account for faults (as in Zhong and Gurnis, 1994, for instance), and because the meniscus caused by surface tension increases the depth by a constant. Those undesired effects are particularly high at low rates. However, relative depths for similar subduction rates are comparable in our models (Fig. 5c), i.e. some 2000 to 4000 m deeper for fast subducting plates (at $\sim 30 \text{ mm yr}^{-1}$) than for the slowly subducting plates (at $\sim 10 \text{ mm yr}^{-1}$). This results confirms that the along strike variations in the Hellenic trench depth mirror the laterally variable subduction rates.

4.3 Aegean deformation

Trench migration in our models follows the mechanism that was initially proposed by Royden and Papanikolaou (2011). In addition, our models explore the impact of the inception of the Kefalonia Fault onto the upper plate. Silicone plates behave as quasi-Newtonian fluids at experimental strain rates. Thus in our simplified model, upper plate deformation is diffuse and the models do not produce any of the faults that may also accommodate deformation of the overriding lithosphere in nature. However, upon the assumption that the brittle crustal deformation is a surface expression of the overall viscous lithospheric deformation, the comparison between the continuous deformation

of the models to the discrete deformation observed on Earth holds. Indeed, our models show comparable patterns of deformation and explain the temporal evolution of Aegean tectonics though, of course, the diffuse deformation and the unaccounted Anatolian extrusion prevent the reproduction of the discrete dextral shear found in the NAT and NAF.

During the early stage of Aegean expansion, prior to the inception of the Kefalonia Fault, lithospheric stretching accommodated slab retreat and faults trended parallel to the uniformly retreating trench, in agreement with the deformation seen during the early stages of our models: extension is widespread and reaches its fastest rate on the entire plate (Fig. 7a). The inception of the tear fault initiated a non uniform rollback and trench migration (see Sect. 4.2) that caused a wholesale rotation of the upper plate around a Euler pole located some 1200 km from the triple junction (Fig. 7b). Deformation remained essentially extensional, and the deformation axis in the models show that normal faults in front of the oceanic unit are expected to trend parallel to the trench (Fig. 7b). This episode explains the arc parallel “transitional” episode of deformation of Papanikolaou and Royden (2007) (Fig. 9a).

The third stage of deformation (Fig. 7c) occurs at the time where the tear fault reaches mantle depths. Then, the Euler pole shifts to a much closer location to the triple junction between the tear fault and the trench, at ~ 300 km. It approximately matches the location of the Euler pole for post-Eocene (and probably post-Oligocene) rotations that was found close to Scutari-Pec, Albania, on the basis of paleomagnetic measurements (Speranza et al., 1992). It is similar to the Euler pole proposed by van Hinsbergen et al. (2005) on the basis of paleomagnetic measurements for western Greece, on average since Mid-Miocene (thus compatible). It also matches the location of the Euler pole found by Brun and Sokoutis (2010), on the basis of a comparison between stretching lineations and seismic anisotropy; however, these authors reach slightly contrasting conclusions, for they suggest that the location of the pole has remained stationary for the last 45 Myr, while our models suggests it may have only began since the onset of the Kefalonia Fault. The rotation pole in our model is also a little further from the

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rotation pole proposed by Pérouse et al. (2012) from kinematic indicators. That rotation is accompanied by strong extension in the vicinity of the trench. In the models, the extension axis is approximately oriented N–S in front of the triple junction, at an equivalent location to the CHSZ (Fig. 7c). The two last stages therefore reproduce the structural pattern of the Peloponnese and Mainland Greece, where extension shifts from arc-parallel to arc-crossing trends. In particular, the ~ EW trending Corinth rift is well explained by our models. In addition, our models predict some localized compression next to the triple junction (Fig. 7b), a somewhat less abundant, yet present, feature in Greece around Kefalonia (Sachpazi, 2000; Vassilakis et al., 2011, and Fig. 9b).

A synthetic view is given by the horizontal divergence and curl of the model surface velocity fields (Fig. 9c, d), that we use to locate stretching and shear, respectively. After the first stage of widespread extension, the divergence field reveals the initiation of an elongated extensional zone in front of the triple junction during the second stage (after the inception of the tear fault) (Fig. 9c), i.e. at a location that compares to that of the CHSZ and NAT with respect to the Kefalonia Fault; this episode continues during the third stage, but decreases in magnitude (Fig. 9d). Furthermore, divergence in this area indicates that the extensional zone in our models enlarges and increases in magnitude north-eastward, away from the triple junction, i.e. at comparable location to the NAT. This pattern of scissors-like stretching is that of the deformation from the Gulf of Patras towards the Aegean sea. A second zone of extension appears by the oceanic trench, at a location that compares to that of the Cretan Sea and Peloponnese, a feature that decreases during the third stage, in accordance with the geological record. Second, mapping the curl of the horizontal velocity field locates occurrences of toroidal flow, that is the local rotation about the vertical axis, that we interpret as the location where strike slip faulting is expected (Fig. 9c, d). The curl shows that very little shear occurs during the second stage, but seriously increases during the third stage. Besides the strong shear that the models show immediately adjacent to the trenches (dextral next to the oceanic unit, sinistral by the continental unit), dextral shear is found on a band that branches onto the triple junction, normally to the trench, that narrows eastward. It

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is largest close to the trench, at a location that compares to that of the wide CHSZ with respect to the Kefalonia Fault. It thins away at a location that matches that of the narrow NAT and NAF, as opposed to divergence. In summary, deformation evolves through time from extension towards strike-slip via transtension, as indicated by the ratio divergence/curl that decreases through time, by an average factor of ~ 4 from the second to the third stage. As dextral shear builds up, the deforming zones narrow, which resembles the evolution of the broad extensional NAT, Cretan Sea and Peloponnese (during Late Miocene and Early Pliocene, i.e. the second stage) towards a more localized dextral transtension across the CHSZ and NAT (during the third, Plio-Quaternary stage), as suggested by Papanikolaou and Royden (2007). This resemblance lead us to conclude that together, the divergence and curl fields of the model horizontal velocities clearly predict the deformation field as revealed from structural analysis (Papanikolaou and Royden, 2007) but also from the focal mechanisms at present-day (Fig. 9b). In details, eastward from Kefalonia, observed deformation shifts from (dominantly) compression to (dominantly) dextral strike slip and (dominantly) extension around Corinth. Our models successfully reproduce the observed kinematics, with a late episode of $\sim N50$ trending dextral shear (akin to the NAT and NAF) and $\sim N90$ trending normal faults (akin to the Gulf of Corinth) that follows a transitional episode of arc parallel normal faulting. The dynamic causes shall be explored thanks to the analysis of the mantle flow.

4.4 Mantle flow

The three stage tectonic evolution of the Hellenic domain is successfully reproduced by our models; they correspond to the subduction of uniformly buoyant slab, to the entry of the heterogeneous slab, and last, to the complete subduction of the tear fault. How it forces the deformation of the upper plate is due to the changes in the driving forces, and it is in the mantle that they vary most efficiently during transient subduction. Significant insight for this comes for the fact that the curl does not show any influence of the incipient Kefalonia Fault until the tear fault reaches mantle depth and modifies

the underlying mantle flow; this suggests that it is mostly mantle drag that efficiently controls the kinematics of plate boundaries (Husson, 2012).

At present-day, the Hellenic slab is most likely teared between Rhodes and Cyprus and a window allows for mantle flow underneath West Anatolia (Govers and Wortel, 2005). The situation is less clear for the Kefalonia Fault; seismic tomography (Spakman et al., 1988; Piromallo et al., 2006; Suckale et al., 2009) possibly reveals a discontinuous slab and more detailed seismic experiments suggest that the surface of the slab is offset horizontally by some 100 km across the Kefalonia Fault (Gesret et al., 2011). However, whether the mantle flows through a potential Kefalonia window remains uncertain, and it is most likely small, if any. Only seismic anisotropy (Fig. 10a, Paul et al., 2010; Hatzfeld et al., 2001; Evangelidis et al., 2011) possibly advocates for along-arc mantle flow that could be interpreted as originating from the Kefalonia window, but the not-so-clear nature of along-arc anisotropy (e.g. Russo and Silver, 1994; Long and Silver, 2009; Faccenda and Capitanio, 2013) prevents from being conclusive. Overall the trend of seismic tomography in the sublithospheric mantle does not accurately match the motion of Anatolia. In particular, anisotropy is not imprinted yet by the too young shear underneath the North Anatolian fault (Kreemer et al., 2004; Jolivet et al., 2009); this observation precludes its use as a mean to explore recent changes in mantle deformation.

However, based on the comparison to surface deformation, Pérouse et al. (2012) concluded that the Kefalonia window is opened. Indeed, surface strain shows what Pérouse et al. (2012) refer to as two toroidal cells, dextral and sinistral at the western and eastern edges of the oceanic slab. Our models shows that this behavior is also obtained just before the actual opening of the tear fault (Fig. 7c). However, our models also showed that it is only when the tear fault is actually subducted that dextral shear appears. Although our main conclusions hold, this contradicts the interpretations of Pérouse et al. (2012) on the timing of events. Our models show that the onset of differential motion between the two units leads to a more vigorous mantle flow in the oceanic section than in the continental section, which induces dextral shear in the

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overriding plate. This shear only happens when the diversion of the mantle flow thanks to the Kefalonia tear fault begins, and not before (when the fault has not reached mantle depths). If the slab window was fully opened, and allowed for mantle flow through it, dextral shear would be even more dramatic. This shows that it is mantle flow, and not trench pull or any shallow process, that causes it. Instead, we conclude that the increasingly vigorous toroidal flow around the edges of the oceanic slab is responsible for dextral shear across the two units: basal, southwestward drag grows larger in the southern section than in the northern one and is enough to shear the overriding plate, possibly helping the NAF to make its way across the Aegean and Mainland Greece and Peloponese.

4.5 Dynamic topography

Mantle flow causes the sufficient drag force to shear the Aegean lithosphere. It also induces vertical tractions that deflect the surface. Mantle flow models indicate that dynamic topography is likely in excess of 1000 m in the Cretan Sea (Husson, 2006; Boschi et al., 2010; Faccenna and Becker, 2010). In particular, it may be responsible for the very deep Cretan Sea (Fig. 11). Of course, residual topography is not real topography. Nevertheless, we note that in the Aegean domain, crustal thickness only varies by a few kilometers (e.g. Tirel et al., 2004) and isostasy by no means shall suffice to explain the ~2000m variations in elevation. Indeed, elevation drops from north to south across the CHSZ, from the continental North Hellenic subduction to the oceanic South Hellenic one (Fig. 11). Second, flooding of the Aegean sea started after roll-back started (see the paleogeographic reconstructions of Dermitzakis and Papanikolaou, 1981) and likely increased during Late Neogene (Wright, 1978; van Hinsbergen et al., 2004, 2005). It remains difficult to evaluate the subsidence rates, but we observe that subsidence therefore took place above the oceanic slab, at the time during which its purported negative buoyancy increased (Royden and Papanikolaou, 2011). These observations match our model results (Fig. 8) that predict an increasing difference in

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elevation between the two units. This result corroborates the idea that dynamic topography plays a critical role in shaping the Aegean seafloor.

5 Discussion and conclusions

We use three-dimensional analogue models of subduction to explore the interplay between mantle flow and surface tectonics during the subduction of a slab of laterally variable buoyancy. The simplified experimental setup provides the necessary ingredients to successfully reproduce the kinematics and tectonic history of the Aegean–Anatolian region since middle Miocene and for the analysis, in particular, of the role played by mantle flow around the Kefalonia Fault.

For a fixed ridge configuration, slab pull controls the subduction velocity, which essentially scales with trench velocity. Lateral density variations modify this simple scaling law and cause a profound, three-dimensional reorganization of the subduction system. Trench migration rates are not only controlled by the local slab pull force but are also influenced by the changes in neighboring slab density. This is the case of the Hellenic subduction zone, where the buoyancy of the subducting lithosphere purportedly drastically changes across the Kefalonia Fault, from a dense oceanic to a continental lithosphere. In all models, trench migration rates within the oceanic unit decreases after the onset of continental unit subduction despite the unchanged local slab pull force. The influence is gradual and vanishes at larger distances than ~ 500 km from the density discontinuity. The reciprocal effect, that would be trench retreat for the continental unit despite the low or null local slab pull force, is not verified. Instead, trench stops retreating in spite of the still active local slab pull force. This illustrates the three-dimensional effect, which is the role played by the toroidal flow underneath the continental plate, excited by the adjacent fast retreating oceanic plate. Compressive stresses underneath the slow-retreating continental unit cause it to prematurely stall and even advance. Geological observations seem to indicate that the Cretan portion of the trench migrated substantially further to the south and southwest than did the Peloponnesus portion of

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the trench from Middle to Late Miocene onwards (Royden and Papanikolaou, 2011), illustrating the decreasing trench retreat rates in Peloponnesus due to the subduction of more buoyant material beneath the northern Hellenides.

Our analysis also shows how mantle flow is controlled by changes in along-trench kinematics. During the subduction of a uniform slab, trench retreat is almost uniform along the entire length of the subduction zone and two symmetrical toroidal cells develop at the edges of the subduction zone. In the Central Mediterranean, such mantle flow pattern has been proposed to explain for instance anomalous uplift around the Calabrian subduction zone (Faccenna et al., 2011). A direct comparison with the Hellenic subduction zone at this stage is more hazardous since only one slab tear between the western edge of the Cyprus slab and the eastern edge of the Hellenic slab is clearly imaged by tomographic models (e.g. Salaün et al., 2012). The following stages instead more likely resemble the Hellenic subduction zone with the introduction of a lateral buoyancy variation, similar to the difference in slab buoyancy across the Kefalonia region, that diverts horizontal mantle flow from its previous symmetry. Toroidal flow through the western Anatolian slab window, as imaged by SKS splitting data (Paul et al., 2010), results here from the fast retreat of the oceanic unit in the southern portion of the subduction zone. The latter is also responsible for trench-parallel mantle deformation north of the discontinuity, that could be one explanation for the NW–SE direction of fast polarization of SKS data observed beneath Mainland Greece (Fig. 10). However, strain calculated in the model is short-term (calculated over a 0.5 Myr period) whereas fast direction of SKS data most likely reflects the long-term deformation of the mantle beneath the Aegean-Anatolian region. In addition, interpreting trench-parallel direction of SKS data close to the trench is not trivial (e.g. Long and Silver, 2009).

Thanks to their simple setups, our models reveal the main lines of the dynamic events that drove the tectonics of the Aegean domain. It allows to disentangle competing mechanisms and to interpret the geological history of the Aegean. We interpret the three stages of deformation that are recognized from the geological record by a first stage of subduction of a uniformly buoyant plate that only lead to the global expansion

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of the Aegean domain during Mid-Miocene (Fig. 12a). This was followed by a Late Miocene–Early Pliocene transitional stage during the inception of the Kefalonia Fault (Fig. 12b). This event initiated the disruption of the chiefly poloidal flow underneath the Aegean. The Aegean plate got dextrally sheared thanks to the underlying mantle flow, while arc-parallel normal faulting prevailed in the outer rim of the Aegean. From Pliocene onwards, the ongoing subduction of the Kefalonia tear fault increased the differential rollback between the two units (Fig. 12c). Dextral shear along the CHSZ grew stronger because of the underlying mantle that flowed at fast rates in the South while in the North it only got sucked by the adjacent oceanic plate, in a toroidal mode. Deformation became chiefly transtensional, thanks to the closer location of the Euler pole to the triple junction. It is thanks to this transitional regime that normal faulting started in the Corinth Rift. In our models as in nature, the differential motion across the Kefalonia Fault is $\sim 20 \text{ mm yr}^{-1}$. When the tear fault operates at mantle depth, this is also the range of difference in trenchward mantle flow rates. We emphasize that this is mantle flow, and not trench pull or any shallow process, that helped localizing deformation along the narrowing CHSZ and NAT, which occurred only when the tear fault separating the continental and oceanic units reached mantle depths.

Because the tear fault is not entirely subducted and the slab window is only beginning to open, the difference in trench velocity across the Kefalonia Fault is at a transient state and shall increase with time. Our models suggest that the current, Plio-Quaternary phase, requires moderate to null opening of the window. The northern toroidal cell gradually built up while the mantle flowed from the front of the continental unit towards the oceanic unit. The slab window will be an additional outlet for mantle flow in the north, and mantle is expected to flow through the window, reshaping the toroidal cell and promoting an increasingly faster rollback of the southern unit. Trenchward sublithospheric mantle drag will grow stronger through time in the south than in the north, that integrates into a net shear force that excites dextral shear in the NAT, CHSZ and Kefalonia. Because it controls upper plate tectonics, we thus anticipate that the further modification of mantle flow, in particular its diversion through the Kefalonia

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Table 1. Experimental parameters. L : length; W : width; h : thickness; $\Delta\rho$: $\rho - \rho_{\text{mantle}}$; η^* : $\eta/\eta_{\text{mantle}}$. Considering a natural case with the following parameters ($h_{\text{slab}} = 72 \text{ km}$; $\eta_{\text{mantle}} = 1 \times 10^{20} \text{ Pas}$ and $\Delta\rho_{\text{slab}} = 71 \text{ kg m}^{-3}$), 1 km in nature corresponds to 0.14 mm in the lab, a period of 1 Myr in nature corresponds to 57 s in the lab, and a velocity of 10 cm yr^{-1} in nature to a velocity of 17.6 mm min^{-1} in the lab (models 8–11).

Model	Oceanic lith.					Continental lith.					Continent				
	L cm	W cm	h cm	$\Delta\rho$ kg m^{-3}	η^* $\times 10^2$	L cm	W cm	h cm	$\Delta\rho$ kg m^{-3}	η^* $\times 10^2$	L cm	W cm	h cm	$\Delta\rho$ kg m^{-3}	η^* $\times 10^2$
1	35	20	1.2	83	9.1	21	10	1.2	−35	8.5	16	25	1.0	−35	8.5
2	40	20	1.2	83	7.75	20	10.5	1.2	−41	17	18	25	0.9	−35	7.25
3	45	20	1.2	83	7.75	25	10	1.2	−41	17	–	–	–	–	–
4	45	40	1.2	83	7.75	25	20	1.2	−41	17	–	–	–	–	–
5	45	40	1.2	83	7.75	25	20	1.2	−41	17	–	–	–	–	–
6	45	40	1.2	83	7.75	25	20	1.2	−41	17	–	–	–	–	–
7	45	40	1.2	83	7.75	25	20	1.2	−41	17	20	40	0.5	−35	7.25
8	45	40	1.2	71	11.5	25	20	1.2	−43	25	–	–	–	–	–
9	45	30	1.2	71	11.5	25	15	1.2	−43	25	–	–	–	–	–
10	45	20	1.2	71	11.5	25	10	1.2	−43	25	–	–	–	–	–
11	45	20	1.2	71	11.5	25	10	1.2	−43	25	–	–	–	–	–

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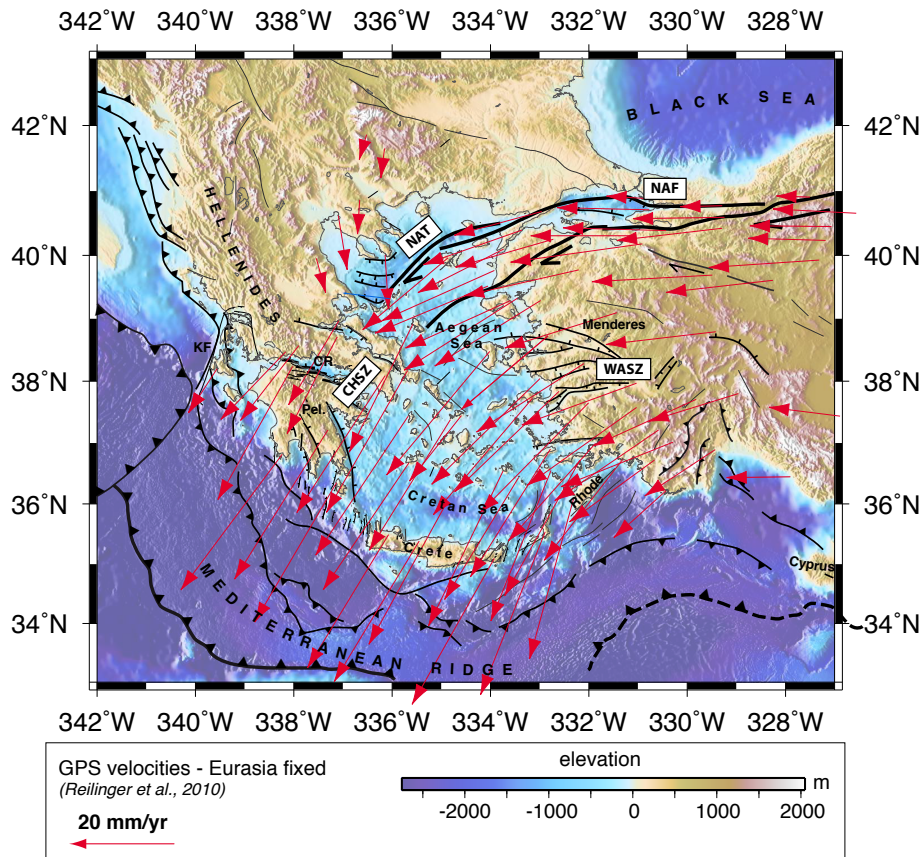


Fig. 1. Tectonic map of the Aegean and Anatolian regions showing the main active structures (after Jolivet et al., 2013) and GPS velocity field (Eurasia fixed, after Reilinger et al., 2010). Topographic data come from the ETOPO1 global relief model (Amante and Eakins, 2009). CHSZ: Central Hellenic Shear Zone; CR: Corinth Rift; KF: Kefalonia Fault; NAF: North Anatolian Fault; NAT: North Aegean Trough; Pel: Peloponnese; WASZ: Western Anatolian Shear Zone.

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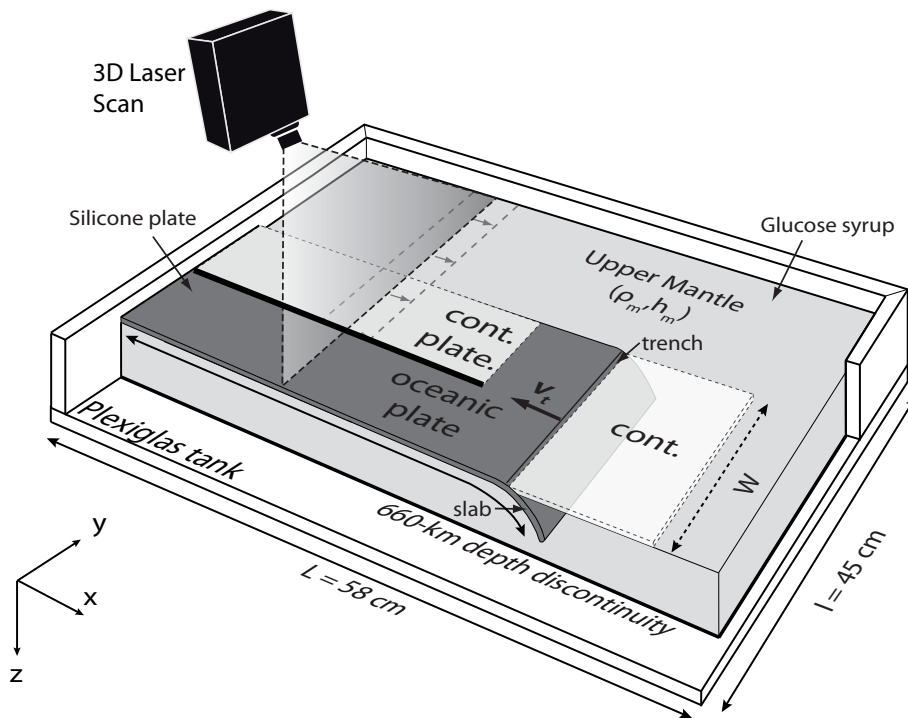


Fig. 2. Experimental setup. The subducting lithosphere is modeled by a silicone plate made of two different materials, a positively buoyant one (defined as *continental* lithosphere) and a negatively buoyant one (defined as *oceanic* lithosphere). The upper mantle is simulated by means of glucose syrup, the bottom of the box corresponding to an impermeable lower mantle–upper mantle discontinuity. The plate is *fixed*, i.e. its trailing edge is attached to the box. The surface topography is monitored by a 3-D laser scan and pictures are taken from the top and the side of the model every 30 s. See Table 1 for experimental parameters.

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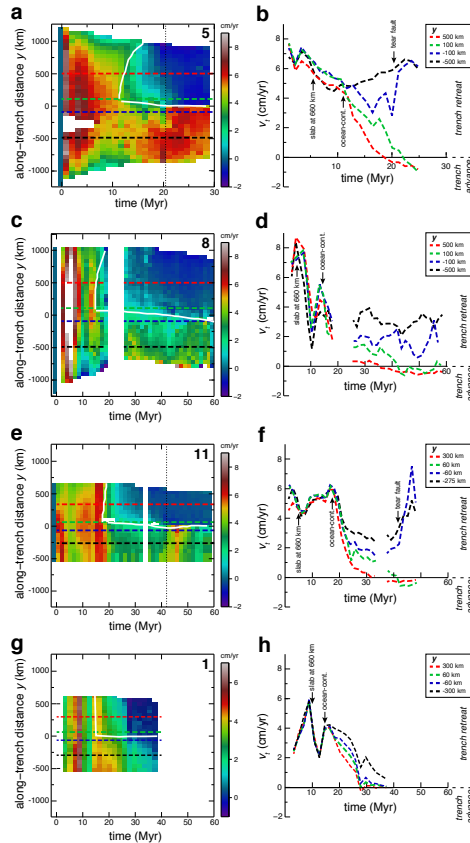


Fig. 3. (a) Trench migration rate as a function of time along y -axis for model 5, i.e. a large subduction zone with a vertical tear fault developing after 20.5 Myr of subduction (black dotted line). Zero on the y -axis corresponds to the location of the discontinuity between oceanic and continental lithospheres. Positive and negative values indicate oceanward and continentward trench motions, respectively. Solid white line underlines the onset of continental lithosphere subduction. (b) Trench migration rate as a function of time for sections located 500 km (red line) and 100 km (green line) north of the discontinuity and 100 km (blue line) and 500 km (black line) south of it (see location on Fig. 3a). Slab reaches the upper-lower mantle discontinuity after 6 Myr. Subduction of the postively-buoyant slab starts after 11 Myr. (c) Same as (a) but for a large subduction zone without a vertical tear fault (model 8). The area in white corresponds to a period of no data acquisition. (d) Same as (b) but for model 8. (e) Same as (a) for a narrow subduction zone with a vertical tear fault developing after 42 Myr (model 11). (f) Same as (b) but for model 11 and sections located 300 km (red line) and 60 km (green line) north of the discontinuity and 60 km (blue line) and 275 km (black line) south of it (see location on Fig. 3e). (g) Same as (a) for a narrow subduction zone with an overriding plate (model 1). (h) Same as (b) but for model 1.

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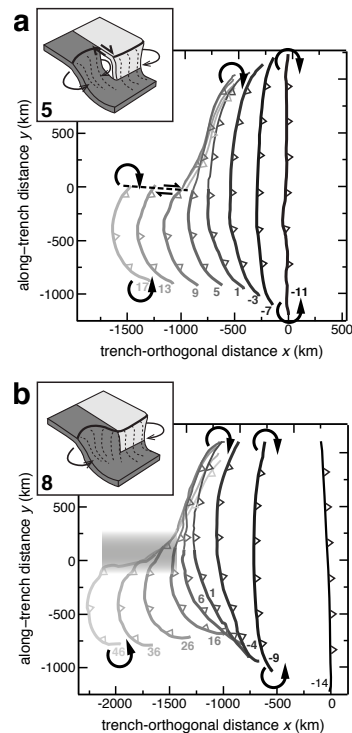


Fig. 4. Evolution of horizontal trench shape for models **(a)** 5 and **(b)** 8. Thick and thin lines indicates locations of oceanic and continental subductions, respectively. Numbers at the bottom indicate the time after subduction of continental lithosphere in Myr. Dashed line in **(a)** indicates the location of the tear fault and gray box in **(b)** the area where the slab deforms to accommodate differential roll-back velocities. Black arrows show schematic mantle flow pattern associated with subduction. Insets show 3-D sketches of the subducting plate shape at the end of each experiment.

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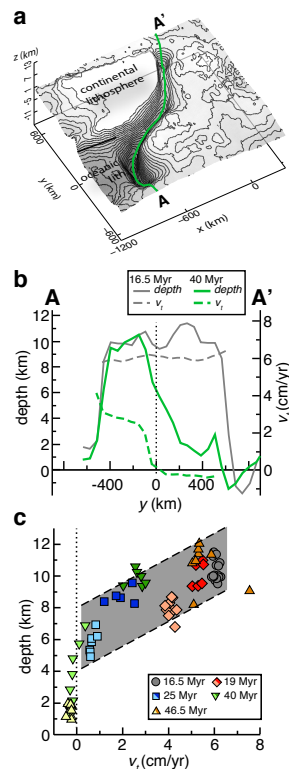


Fig. 5. (a) Digital Elevation Model for the surface of model 11 after 40 Myr of subduction. Zero is the average elevation of the glucose syrup away from the subduction zone. (b) Maximum trench depth (solid line) and corresponding trench migration rate along x-direction (dashed line) after 16.5 Myr (in gray) and 40 Myr (in green) of subduction. (c) Trench maximum depth as function of v_t at different times during subduction. Light and dark symbols correspond to points located in front of continental and oceanic units, respectively. To minimize boundary effects, only points located within a distance of 400 km from the center of the subduction zone are included. Dashed lines and gray box indicate the regression envelope for $v_t > 0$.

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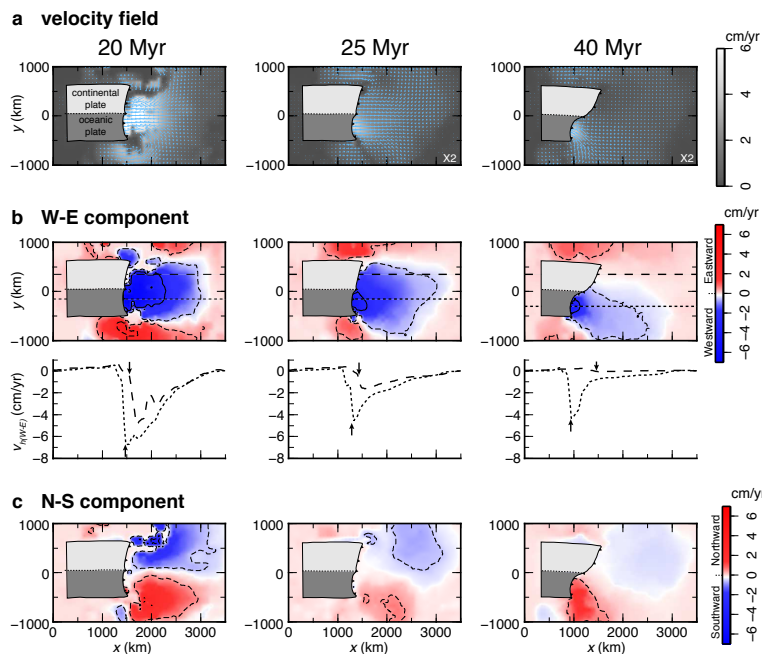


Fig. 6. (a) Velocity vectors and magnitude of the horizontal velocity field for model 11 after 20 Myr (left panel), 25 Myr (central panel) and 40 Myr (right panel) of subduction. Note the changing size of the arrows. (b) Magnitude and along-x profiles of the W–E component of the velocity field. On the maps, black dashed lines underline regions with horizontal mantle flow velocity (v_h) higher than 0.5 cm yr^{-1} and black solid lines with $v_h > 4 \text{ cm yr}^{-1}$. Positions of continental and oceanic units of the subducting plate are indicated in light gray and dark gray, respectively, and the position of the trench by a black line with triangles. W-directed mantle flow is represented as negative values. Profiles pass through the center of the continental (dashed line) and oceanic (dotted line) units. Black arrows indicate the position of the trench. (c) Same as (b) but for the N–S component of the velocity field. Southward mantle flow is represented as negative values.

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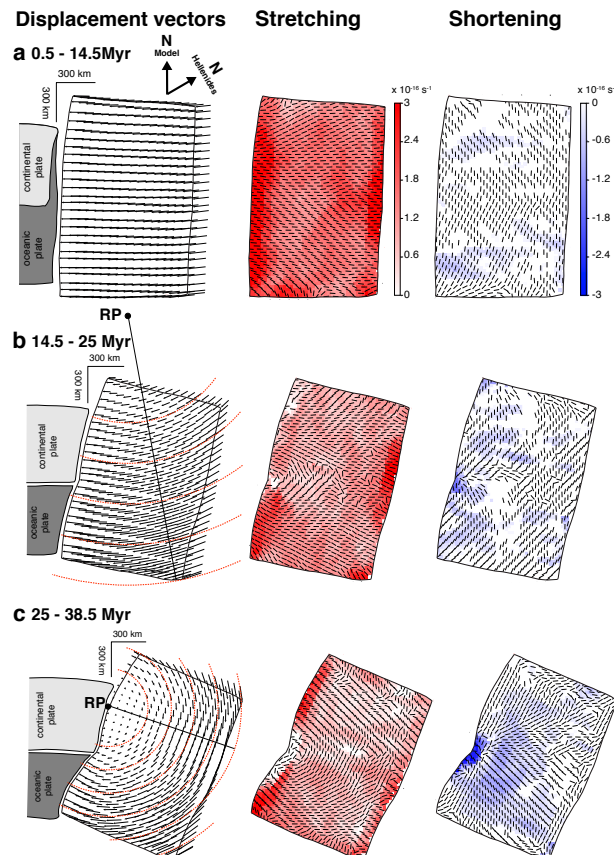


Fig. 7. Motion and deformation of the overriding plate for model 1, **(a)** between 0.5 and 14.5 Myr, **(b)** 14.5 and 25 Myr, and **(c)** 25 and 38.5 Myr after the initiation of subduction. Left panel shows displacements fields for each time interval. Central and right panels show the main directions and rates of stretching and shortening, respectively. RP is for rotation pole.

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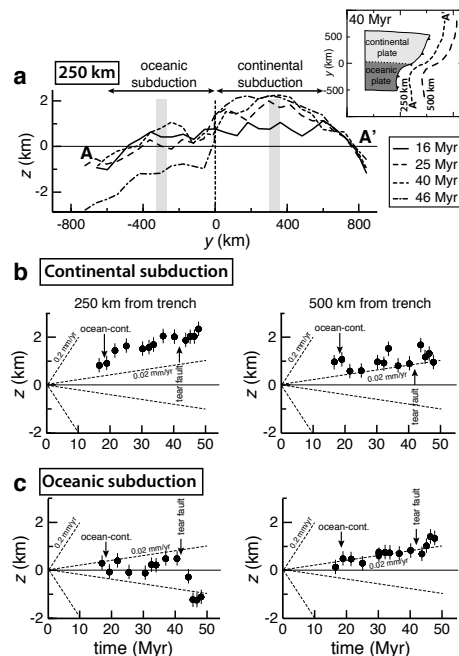


Fig. 8. (a) Dynamic topography measured at the surface of the asthenosphere for model 11 at a distance of 250 km from the trench after 16, 25, 40 and 46 Myr of subduction. Inset indicates the location of cross-sections at 250 and 500 km from the trench after 40 Myr of subduction. (b) Time-evolution of dynamic topography for the same model above the center of the continental subduction zone at 250 km from the trench (left panel) and 500 km from the trench (right panel). Elevations are averaged on a 60 km wide trench-perpendicular swath to remove any shorter wavelength perturbations (see position of swath on Fig. 8a). (c) Same as (b) for the oceanic subduction. Trends for uplift and downlift velocities of 0.02 and 0.2 mm yr⁻¹ are indicated by dashed lines.

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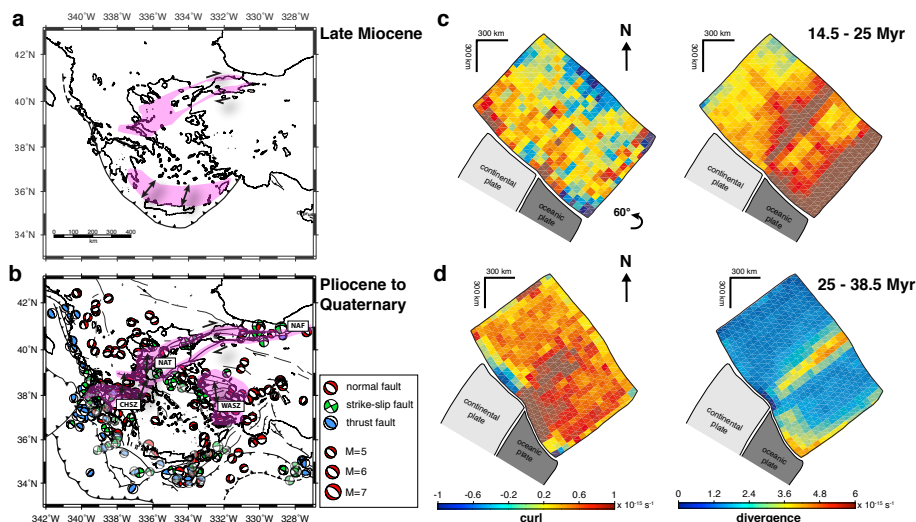


Fig. 9. Upper plate deformation within the Aegean region for **(a)** the Late Miocene and **(b)** Pliocene to Quaternary periods (after Royden and Papanikolaou, 2011; Jolivet et al., 2013). The approximate areas affected by extension and/or strike-slip activity for the considered time period are indicated in pink (deformation is not palinspastically restored) and the main active structures and focal mechanisms of earthquakes at depths lower than 50 km (source: CMT, 2011) are shown in **(b)**. Earthquakes with depths between 30 and 50 km are indicated with transparent beachballs. **(c)** Curl (left panel) and divergence (right panel) computed from the overriding plate horizontal displacement field for the 14.5–25 Myr time period of model 1. **(d)** Same as **(c)** for the 25–38.5 Myr time period. A 60° counterclockwise rotation has been applied to panels **(c)** and **(d)** to make the trench orientation fit the orientation of the Hellenic trench.

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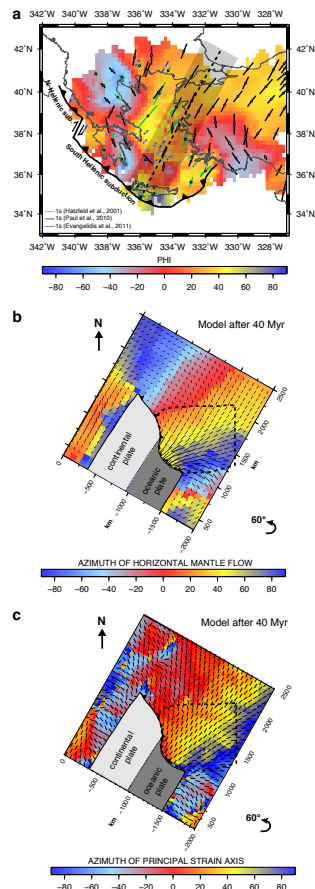


Fig. 10. (a) Azimuth (interpolated, colorscale) and delay (bars) of seismic anisotropy in the Aegean–Anatolian region obtained from SKS waves (green bars, Hatzfeld et al., 2001; black bars, Paul et al., 2010; blue bars, Evangelidis et al., 2011). (b) Azimuth of horizontal mantle flow for model 11 after 40 Myr of subduction. Black bars indicate the direction and relative magnitude of mantle flow. The black dashed lined underlines the approximate corresponding region of SKS data shown in Fig. 10a. (c) Azimuth of the principal strain axis for model 11 after 40 Myr of subduction. Black bars indicate the direction of principal strain component. A 60° counterclockwise rotation has been applied to panels (b) and (c) to make the trench orientation fit the orientation of the Hellenic trench.

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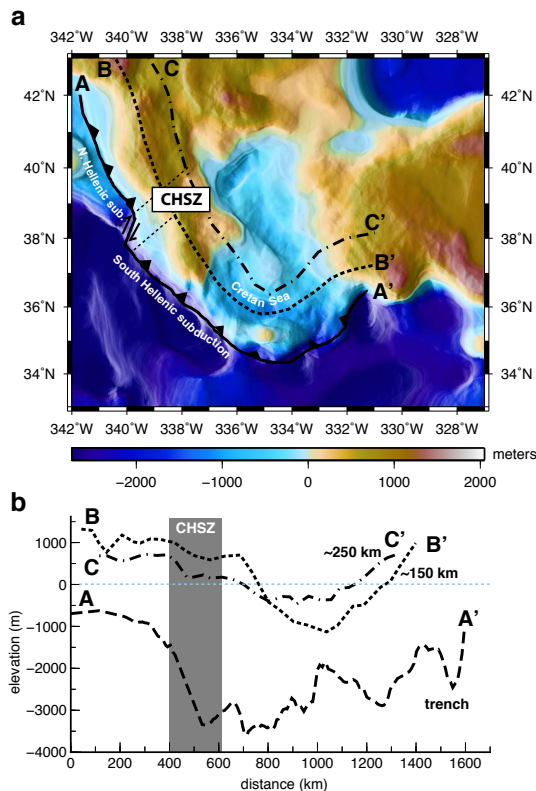


Fig. 11. (a) Smoothed topography of the Aegean region. ETOPO1 global topography (Amante and Eakins, 2009) has been filtered with a 150 km large median filter using Generic Mapping Tools (Wessel and Smith, 1998). **(b)** Topographic profiles of the trench (A–A'; dashed line) and of the Aegean overriding lithosphere at a distance of ~ 150 km (B–B'; dotted line) and ~ 250 km (C–C'; dashed-dotted line) from the trench.

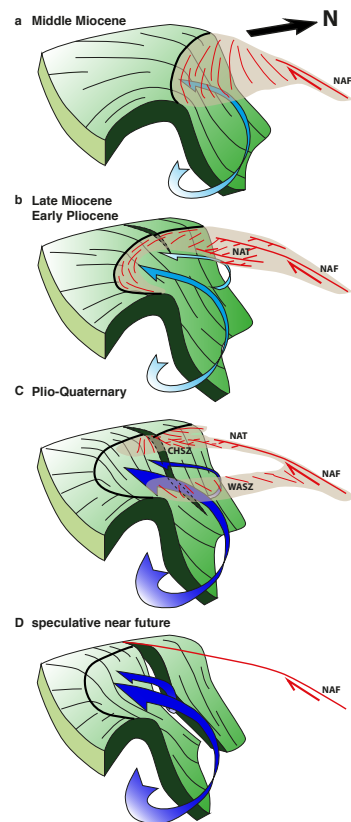


Fig. 12. 3-D sketches (redrawn after Jolivet et al., 2013) showing middle Miocene to present-day evolution of slab geometry, mantle flow and overriding plate deformation in the Aegean–Anatolian regions and speculative interpretation of their evolution in the near future on the basis of outputs from the three-dimensional dynamic models.

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