



Seismic structure beneath the Gulf of Aqaba and adjacent areas based on the tomographic inversion of regional earthquake data

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1 **Abstract**

2 The Gulf of Aqaba is an elongated basin (~180 x 20 km) with depths reaching 1850 m. It
3 represents the southern segment of the Dead Sea Transform (DST), which is one of the largest
4 transform fault zones in the world. The opening of Gulf of Aqaba is thought to have originated
5 from the relative displacement of the African and Arabian Plates. According to historical and
6 recent earthquake records, it is seismically active. In this study, we present the first 3D model of
7 seismic P and S velocities beneath the Gulf of Aqaba area based on the results of passive travel
8 time tomography. The tomographic inversion was performed based on travel time data from
9 ~9000 regional earthquakes provided by the Egyptian National Seismological Network (ENSN)
10 and the International Seismological Center (ISC). The inversion results are generally consistent
11 for P- and S-velocity patterns at all depths. At all depth intervals in the Red Sea, we observed
12 strong high-velocity anomalies with abrupt limits that coincide with the coastal lines. This
13 finding suggests that the oceanic nature of the crust in the northern Red Sea does not support the
14 concept of gradual stretching of the continental crust. According to our results, in the middle and
15 lower crust, the seismic anomalies seem to delineate a sinistral shift (~100 km) in the opposite
16 flanks of the fault zone that is consistent with other estimates of the left-lateral displacement in
17 the southern part of the DST. However, no displacement structures are visible in the upper-most
18 lithospheric mantle.

19

20 Key words: Seismic tomography, Gulf of Aqaba, Dead Sea Transform, Northern Red Sea

21

22 **Introduction**

23 Tectonic activity in the Gulf of Aqaba region is responsible for high levels of seismicity,
24 which represent a significant hazard for the local population. In 1993 and 1995, two strong
25 earthquake sequences with magnitudes reaching $M_b=5.8$ and $M_b=6.7$ (main shocks), occurred
26 beneath the Aqaba basin (Abdel Fattah et al., 1997; Hofstetter, 2003). Sharp bathymetry features



27 of the Gulf Aqaba floor and the presence of deep-sea segments reaching depths of 1850 m
28 (Figure 1b) provide evidence for ongoing active tectonic processes (Ben-Avraham et al., 1979;
29 Ehrhardt et al., 2005; Makovsky et al., 2008). It appears that in some parts of the Gulf of Aqaba,
30 the sedimentation rate cannot compensate for the rapid subsidence of the sea floor (Ten Brink et
31 al., 1993). This differs from the Gulf of Suez, which is located on the other side of the Sinai
32 Peninsula; many considered it to be a zone of ongoing crustal extension (McClusky et al., 2003;
33 Mahmoud et al., 2005), and it is nearly fully covered by young sediments (Gaullier et al., 1988;
34 Cochran and Martinez, 1988).

35 The Gulf of Aqaba represents a transition zone from the spreading ridge in the Red Sea to
36 the strike slip Dead Sea Transform Fault (DST) (Ben-Avraham et al., 1979). A very similar
37 transition occurs in the Gulf of California at the southern edge of the San Andreas Fault. Many
38 researchers (Joffe and Garfunkel, 1987; Ehrhardt et al., 2005) accept that the opening of the Gulf
39 of Aqaba occurred simultaneously with the initiation of the Dead Sea Transform Fault (DST) 20-
40 15 Ma ago. This fault is one of the largest faults in the world and can be traced for more than
41 1000 km from the Red Sea to the westernmost end of the Zagros collision zone in eastern
42 Turkey. It cuts the continental crust along the Eastern margin of the Mediterranean Sea. GPS
43 observations provide rates of the present left lateral displacement along the DST fault in the
44 range of 3.5-4 mm per year (Gomez et al., 2007; Wdowinski et al., 2004). Geological
45 observations provide evidence for faster rates, ranging from 5 to 10 mm per year, of long-term
46 displacements starting from the initiation of the DST 20-15 Ma ago (Garfunkel, 1981; Chu and
47 Gordon, 1998). Based on geological observations, the total displacement in a segment of the
48 DST between the Gulf of Aqaba and the Dead Sea was estimated to be 105 km (Freund et al.,
49 1968; Bartov et al., 1980; Garfunkel et al., 1981). To the north of the Dead Sea, the displacement
50 is considerably less (Garfunkel, 1981).

51 The initiation of the DST was due to the relative displacements of the African and
52 Arabian plates (Figure 1a). In the no-net-rotation reference frame, the African and Arabian Plates



53 both move northward, but their displacement vectors differ slightly in their lengths and
54 orientations (Smith et al., 1994; McClusky et al., 2003) that leads to the divergence of the
55 African and Arabian Plates in the area of the Red Sea and results in the spreading of this ocean-
56 type basin. In the area of the Dead Sea and to the north, the displacement vectors of these plates
57 are nearly parallel; however, the Arabian Plate moves faster, resulting in conditions for transform
58 faulting.

59 Although the link between the opening of the Aqaba basin and the initiation of DST
60 displacement is generally accepted, the details of this process are still debated. Most scholars
61 associate the origin of deep linear depressions along the DST, such as the Gulf of Aqaba and the
62 Dead Sea, with the pull-apart mechanism (Mann et al., 1983; Petrunin and Sobolev, 2008;
63 Makovsky et al., 2008; Hartman et al., 2014). Lateral displacements along a non-straight fault
64 line should lead to the origin of compression and extension zones at the vicinity of the fault.
65 Many studies have used both numerical modeling (Petrunin and Sobolev, 2008; Petrunin et al.,
66 2012) and geological evidence (Ehrhardt et al., 2005) to demonstrate the possibility of such a
67 scenario.

68 Alternatively, the origin of the present depressions along the DST can be explained by the
69 relative transform-normal extension (Ben-Avraham and Zoback, 1992; Smit et al, 2010) due to
70 relocation of pole of rotation for the DST at about 5 Ma (Garfunkel, 1981). The left plot in
71 Figure 2 depicts a possible structure before the initiation of DST. In this reconstruction, the
72 coastal structures form continuous trends in NW-SE directions indicated with red lines. The
73 present configuration, shown in the right plot, is obtained by a left-lateral displacement of the
74 Arabian Plate to ~100 km with a simultaneous counter-clockwise rotation to 2.7°. The total
75 displacement is generally consistent with estimates made by other researchers, based on the
76 similarity of geological strata (Freund et al., 1968). In this plot, red lines along the DST mark the
77 location of the initial fault in the opposite flanks. Between these lines, there is an extension zone
78 that corresponds to the Gulf of Aqaba and the Dead Sea. This reconstruction demonstrates the



79 origin of the Aqaba basin resulting from simultaneous relative rotation of the Arabian Plate and
80 an offset along the DST. For the Dead Sea, we have defined a step-shaped feature on the fault
81 that facilitates the extension due to the pull-apart mechanism.

82 A further understanding of the mechanisms of tectonic processes in this area requires
83 robust information on the deep crustal and mantle structures. There is a large difference in the
84 studies that have examined different segments of the DST. The most comprehensive studies have
85 been performed in the area of the Dead Sea (DESERT Group, 2004; Weber et al., 2009). Several
86 passive and active seismic experiments of different scales, receiver functions, and magneto-
87 telluric studies have provided information on the crustal and upper mantle structures (Mechie et
88 al., 2005; Ritter et al., 2003; Mohsen et al., 2006).

89 Unfortunately, most of these comprehensive studies cover the areas to the north of the
90 Aqaba basin and do not provide much information on the structures beneath the Gulf of Aqaba.
91 Between the 1960s and 1980s, some reflection and refraction seismic studies used active sources
92 to explore the detailed crustal structure beneath Gulf of Aqaba, although primarily in the upper
93 part (Ben-Avraham et al., 1979, Ginsburg et al., 1981, Ben-Avraham, 1985, Makovsky et al.,
94 2008, Hartman et al., 2014). Seismic refraction data revealed a gradual southward decrease of
95 the Moho depth from ~35 km at the northern edge of the Gulf of Aqaba to ~27 km in the
96 southern part. These results helped identify some of the fault structures that can be used to
97 explain the mechanisms of the opening of the Aqaba basin (Figure 1b).

98 Several regional studies were performed for large areas of Asia and Africa that included
99 the Gulf of Aqaba. Large-scale surface wave tomography studies by Park et al., (2008) and
100 Chang and van der Lee, (2011) did not reveal any particular features related to the Aqaba basin.
101 According to the models of the crustal structure and Moho depth for the entire Eastern
102 Mediterranean region by Koulakov and Sobolev (2006) and Mechie et al. (2013), the crust to the
103 north of the Gulf of Aqaba is locally thicker than that of other areas. A recently derived seismic
104 model for the upper mantle beneath the Arabian region (Koulakov et al., 2015) gives fair



105 resolution for the Sinai, Aqaba, and Dead Sea regions; however, it does not provide any
106 information for structures above a 100 km depth.

107 Between detailed seismic surveys in the Aqaba region and large-scale regional
108 tomographic models, there is a gap in studies of the crust and uppermost mantle beneath the Gulf
109 of Aqaba and surrounding areas. Although there is active seismicity in this region and a fair
110 amount of seismic stations on both sides of the Gulf of Aqaba, no detailed earthquake
111 tomography was performed. Here, we present the first tomographic model based on a large
112 dataset, which was provided by the Egyptian National Seismological Network (ENSN). The new
113 3D models of P- and S-velocities give a new look to the structure beneath the Gulf of Aqaba and
114 surrounding regions and enhance our knowledge of the deep mechanisms driving the
115 geodynamic processes in this region.

116

117 **Data and Algorithm**

118 In this study, we used the arrival times of P and S seismic waves from seismicity
119 occurring beneath the Gulf of Aqaba and surrounding regions. The dataset was mostly extracted
120 from the Catalogues of the Egyptian National Seismological Network (ENSN) and was
121 complemented by data from the International Seismological Center (ISC) catalogues to enlarge
122 the study area and improve data sampling. The collected arrival time data from different
123 catalogues merged into one catalogue for the same events list. When merging events presented in
124 both catalogues, higher priority was given to the data of the ENSN. The data used in this study
125 are part of a dataset that covers a much larger area than presented in the resulting maps. This
126 helped us avoid some of the edge effects that occurred when stations and/or events were located
127 close to the limits of the processed area. The data for this study were recorded by approximately
128 300 seismic stations in Egypt and surrounding countries; of these stations, only 53 were located
129 in the study region (Figure 3). The same dataset was used in a recent study by Khrepy et al.
130 (2016) providing crustal and uppermost seismic structures beneath the Gulf of Suez.



131 In total, we used more than 9000 events over all of Egypt, of which approximately 3000
132 events corresponded to the Aqaba region and northern Red Sea (Figure 3). To select the data for
133 tomography, we used a criterion of a minimum of 6 picks with any phases (P or S) per event. In
134 total, we selected ~65,000 P and ~17,000 S picks, with an average of 9 picks per event. The
135 relatively small ratio is due to a sparse distribution of stations and mostly low magnitudes of
136 events. To remove outliers from the data, we selected the picks with absolute residuals of less
137 than 1.5 and 2 seconds for the P and S data, respectively, that corresponded to the stage of source
138 location in the starting 1D velocity model.

139 The tomographic inversion was performed using LOTOS code (Koulakov, 2009),
140 expanded for the case of large areas. This algorithm accounts for the sphericity of the Earth when
141 computing the travel times of seismic rays. This code has been described in many previous
142 tomography studies; thus, we only briefly present the major steps and features. The workflow
143 begins with a preliminary calculation of source locations based on the grid search method. For
144 faster calculations, we approximated the model travel times by using a set of tabulated values
145 derived at a preliminary stage. Then, the locations of sources were recomputed using the 3D ray-
146 tracing algorithm based on the “bending method” (Um and Thurber, 1987). The 3D velocity
147 distribution was parameterized using nodes that were distributed in the study area according to
148 the density of rays. The minimum grid spacing was defined as 10 km in the horizontal direction
149 and 3 km in the vertical direction. The distribution of the parameterization nodes, together with
150 the ray paths, corresponding to the depth sections of 10 and 30 km are presented in Figure 4. To
151 reduce grid dependency, we performed the inversions for four differently oriented grids with
152 basic orientations of 0°, 22°, 45° and 67° and then averaged the results. The inversion was
153 performed simultaneously for 3D P and S anomalies, source corrections (4 parameters for each
154 source), and station corrections. The velocity solution was damped by a smoothing matrix, which
155 minimizes the velocity gradients between all neighboring parameterization nodes. The inversion
156 was performed using the LSQR algorithm (Page and Saunders, 1982; Nolet, 1987). The steps of



157 source locations in the derived 3D models, the calculation of the first derivative matrix, and the
158 inversion were iterated five times (a compromise between the computing time and accuracy of
159 the solution). The values of free parameters (e.g., weights for smoothing, station and source
160 corrections) were determined based on the results of synthetic modeling. Values of the main
161 parameters used for calculation of the main model are given in Table 1.
162

Table 1. Values of some parameters used to calculate the main tomographic model

Parameter description	Value
Grid spacing, horizontal	10 km
Minimum grid spacing, vertical	3 km
Minimum number of picks per event	6
Maximum residual deviation, for P and S	1.5 and 2 s
Number of the LSQR iterations	100
Smoothing for the P velocity	1.5
Smoothing for the S velocity	3
Amplitude damping, P and S	0 and 0
Station corrections, P and S	0.1 and 0.3
Weight for the source coordinate correction	5
Weight for the source origin time correction	5

163
164 The data analysis began with finding an optimal starting velocity model. We used a fairly
165 simple approximation, implying a 1D distribution of P-velocity and a constant value of the
166 V_p/V_s ratio. The P-velocity was defined in several depth levels; between these depths, the
167 velocity was linearly interpolated. The optimal model was determined using the trial method.
168 The initial location of sources (i.e., grid search with tabulated travel times) was performed in
169 many different models using different P-velocities and V_p/V_s ratios. The best model is the one
170 that provides the minimum number of rejected outliers and minimum values of average residual



171 deviations. We performed the optimization for the entire dataset of the Egyptian networks and
172 obtained an optimal V_p/V_s value of 1.74. The distribution of the optimal P-velocity is presented
173 in Table 2.

174

175 Table 2. The optimal 1D P-velocity distribution used as a reference model for the tomographic
176 inversion

Depth, km	P-velocity, km/s
-3	4.9
10	6.0
20	6.7
30	7.5
50	8.0
100	8.2

177

178 **Results**

179 Before discussing the main velocity models, we present the results of synthetic tests
180 assessing the horizontal and vertical resolution. Synthetic data were computed using the same
181 ray configuration as the observed data catalogue used to calculate the main tomography model.
182 The synthetic travel times were calculated using the algorithm for 3D ray-tracing based on the
183 bending method. Random noise with a magnitude of 0.15 s was added to the synthetic travel
184 times. Before starting the reconstruction, we perturbed the locations of events and origin times so
185 their true values remained unknown. The reconstruction procedure included all of the steps
186 provided by the LOTOS code, including the preliminary locations of sources in the starting 1D
187 model. This step strongly biases the synthetic residuals and leads to a trade-off between source
188 and velocity parameters, similar to the processing of observed data. The synthetic tests help
189 derive the most optimal values for the inversion parameters and enable the highest quality
190 reconstruction. These parameters were then used to perform the inversion of the observed data.



191 Here, we present results for two synthetic models. The first model (Figure 5) was used to
192 assess the horizontal resolution. In this case, cells with positive and negative anomalies with an
193 amplitude of $\pm 5\%$ and a size of 50x50 km were defined without depth changes. The
194 reconstruction of this model is presented at four depth levels. This model is generally well
195 recovered in most parts of the study area. Some loss of resolution is observed for the S-model at
196 the 40 km depth.

197 The second model (Figure 6) was aimed at estimating the vertical resolution. Due to the
198 trade-off between source and velocity parameters, in most cases of earthquake tomography, the
199 vertical resolution is lower than the horizontal resolution. In this test, we defined checkerboard
200 anomalies along the same vertical sections, as was used for presenting the main results. Across
201 the section, the thickness of anomalies was 40 km. The presented results were obtained from the
202 reconstruction of three separate models. In two of these models, the anomalies were defined
203 along single sections (1 and 3), and in one model, anomalies in both the 2nd and 4th sections were
204 defined. Here, we show the results for the P-model; for the S-model, the resolution appeared to
205 be similar. We see that in most sections, the change in the anomaly sign at 15 km depth is
206 correctly recovered. The anomalies between 15 and 45 km are only recovered in the presence of
207 deep earthquakes; alternatively, they are strongly smeared. Beneath the Gulf of Aqaba and
208 surrounding areas, we can resolve the second boundary of change in the anomaly sign at 45 km.
209 This test shows that the vertical resolution is strongly variable; this should be considered when
210 interpreting the results.

211 Five iterations were performed for the inversion of observed data. During the inversions,
212 the average absolute residuals were reduced from 0.232 to 0.173 seconds (25.5%) for the P-data
213 and from 0.348 to 0.208 seconds (40.2%) for the S-data. The values of the final residuals are
214 generally compatible with the picking accuracy estimates reported by the ENSN. The larger
215 reduction for the S-data seems to be paradoxical, considering the lower quality of the S-picks.
216 However, the S-data are more sensitive to velocity anomalies because the same percent value of



217 an anomaly gives a larger S-residual compared with the P-residual. In addition, the amplitudes of
218 the S-anomalies are usually stronger than those of the P-anomalies.

219 The inversion results for the P- and S-anomalies are presented in horizontal sections in
220 Figure 7. For reference, in the section at the 10 km depth, we show the locations of the main
221 faults. At the 20 and 30 km depths, we give reconstruction markers of the left-lateral
222 displacement of DST introduced in Figure 2. Velocity anomalies are shown only in areas with a
223 sufficient amount of data. Outside the resolved areas, the anomalies are shaded.

224 Absolute P and S velocities are shown at 30 km depth with four vertical sections (Figures
225 8 and 9). The contour lines in the vertical sections roughly represent deviations in the main
226 interfaces. For example, $V_p=7.3$ km/s and $V_s=4.3$ km/s (violet layer) are the average values
227 between the lower crust and uppermost mantle and may represent the Moho interface. Beneath
228 the Red Sea, the crustal thickness is approximately 20 km. The largest crustal thickness observed
229 was in the area of DST (northern part of Section 1) and beneath Saudi Arabia (NE part of
230 Section 2), where the Moho depth reaches ~40 km. A relatively thin crust (25-30 km) is observed
231 beneath the middle part of Sinai (NW part of section 3 and SW part of Section 4). The maps of
232 absolute velocities at 30 km show different areas corresponding to mantle velocities beneath the
233 Red Sea and crustal velocities in most of surrounding areas. A more detailed description of these
234 models and interpretation is given in the next section.

235 An informal argument for the robustness of the computed tomography models is the clear
236 correlation of the main P- and S-velocity anomalies. Although P- and S-velocities should not
237 necessarily fit each other, in practice, the main geological structures behave similarly in both
238 cases, especially on a large scale. Thus, the correspondence of the P- and S-velocities might
239 serve as a “first look” verification of the results.

240

241 **Discussion**



242 The resulting 3D models of the P- and S-velocity anomalies are presented in horizontal
243 sections in Figure 7; the absolute velocities are shown in Figures 8 and 9. These velocity
244 distributions can be compared with previous results of various scales based on different methods.
245 For example, in the regional tomography model by Chang and van der Lee (2011), the study area
246 is entirely located within one large low-velocity pattern. The other regional tomography models
247 mentioned in the introduction are also too rough to identify the details observed in the present
248 model. Some similarities are observed with seismic velocity anomalies for the Aqaba region in
249 the model by Koulakov and Sobolev (2006), which was based on the data from the ISC
250 catalogues, especially for the distributions of the S anomalies. However, that area was on the
251 margin of the model and thus had lower data density and poorer resolution. For the upper mantle,
252 the P-velocity model is similar to a recent tomography model of the entire Arabian region by
253 Koulakov et al. (2015), in which the southern part of the Gulf of Aqaba corresponds to the
254 higher-velocity anomaly at 100 and 200 km depths. Meanwhile, the large area corresponding to
255 the Dead Sea and surroundings coincides with the lower-velocity anomaly.

256

257 The main feature, which is clearly observable in both P- and S-velocity models, is a
258 strong high-velocity anomaly that corresponds to the Red Sea. At the 30 km depth, the high
259 velocity in the Red Sea may be related to a significantly thinner crust. In offshore areas, this
260 depth corresponds to the mantle, whereas in continental areas, this is still the lower crust. The
261 high-velocity anomalies in the upper sections may support the notion for the prevalence of mafic
262 rocks with higher velocities compared with felsic rocks typical for the upper continental crust in
263 surrounding areas. This fact may renew debates regarding the nature of the crust in the northern
264 Red Sea. According to a concept proposed by some authors (e.g., Cochran and Martinez, 1988)
265 based on absence of clear signature of spreading ridges and linear magnetic anomalies (e.g.
266 McKenzie et al., 1970), the crust in the northern part of the Red Sea was formed due to gradual
267 stretching and, as a result, has both felsic and mafic components. However, more recent studies



268 (Cochran, 2005; Cochran and Karner, 2007) report clear axial depression of bathymetry and
269 aligned magnetic anomalies as well as a chain of dykes that are more typical for rifting
270 processes. In our study, we see that the high-velocity anomaly in the Red Sea has very sharp
271 bounds coinciding with the coastline; this presumes an abrupt difference in crustal properties
272 between the on- and off-shore areas at all depth intervals. This would mean that the upper felsic
273 crust is almost absent at this area. This would be not possible in the case of gradual stretching of
274 the continental crust. We propose that such slow spreading might be due to a dispersed system of
275 dykes covering large areas of the sea bottom. However, to prove this hypothesis, additional
276 studies are required.

277 At the 10 km depth, in addition to the large high-velocity anomaly beneath the Red Sea,
278 the structure of the P- and S-anomalies are unexpectedly inconsistent with the distribution of the
279 main geologic units. Neither the location of the Gulf of Aqaba nor the distributions of the main
280 faults can be unambiguously associated with seismic anomalies. The seismic patterns in the
281 Aqaba area look patchy and non-structured. However, after shifting the eastern flank with
282 respect to the western one according to our back-reconstruction (Figure 2), the structures become
283 more consistent (Figure 10). For example, the negative seismic anomalies at the 10 km depth
284 seem to form two continuously curved zones, which are highlighted with violet lines that appear
285 to be nearly parallel. These anomalies may represent hidden geological structures that existed in
286 the crust prior to the initiation of the DST fault. The complex shapes of these structures may be
287 due to intensive tectonic processes in previous stages of geologic development of the region.

288 It is interesting that no prominent features are observed in the basin of the Gulf of Aqaba
289 at all depth intervals, with the exception of the DST-aligned positive S-wave anomalies that are
290 visible within an interval of 20-40 km and continue further north but are thought to be correlated
291 with the DST rather than the Gulf of Aqaba itself. The lack of a prominent anomaly at shallow
292 depths may indicate a relatively thin sedimentary covering, which does not considerably
293 contribute to the seismic model, or insufficient resolution of our model at this depth. Compared



294 with the shallow water basin of the Gulf of Suez, which is completely covered with sediments,
295 the Gulf of Aqaba is deep and has strongly variable bathymetry features, which indicate that the
296 rate of extension here exceeds the sedimentation rate. According to seismic surveys by Ben-
297 Avraham et al. (1979), the maximum thickness of sediments in the Aqaba basin may reach 2-3
298 km, but the thickness appears to be strongly variable. The sedimentation in the Aqaba basin
299 appears similar to the average sedimentary cover thickness in the surrounding onshore areas and
300 thus does not produce a prominent relative negative anomaly in the shallow velocities.
301 Furthermore, the ray configuration used in this study does not allow the recovery of shallow
302 anomalies in the offshore areas.

303 In sections at depths of 20 and 30 km, we depict the markers of the lateral displacements
304 since the initiation of the Dead Sea Fault with green dotted lines in Figure 7. The line along the
305 coast, which has a step-shaped form after 100 km of left-lateral displacement, almost perfectly
306 fits the transition between high- and low-velocity anomalies (Figure 10). This feature may
307 indicate the deformation of the continental crust by the fault and corresponds well to the total
308 estimates of the lateral displacements along the DST derived from independent sources.

309 At a 30 km depth, the negative anomaly along the Gulf of Aqaba (especially clear for the
310 S-velocity model in Figure 7) possibly indicates crustal thinning and local heating due to the
311 slip-parallel extension of the basin. However, seismic anomalies only indirectly represent crustal
312 thickness variations, and they are sensitive to only large deviations of the Moho depth. Other
313 methods, such as seismic reflection surveys or receiver function analysis, would be more suitable
314 for this purpose.

315 At the 40 km depth, the structure corresponds with the uppermost mantle. As observed in
316 synthetic tests, the vertical resolution of the S-model at this depth is poor. Therefore, this
317 structure, which appears to similar to that at 30 km, is probably due to the vertical smearing and
318 does not accurately represent distribution in the mantle. At the same time, the mantle structure
319 for the P-velocity appears to be robust. The presence of high velocities in the uppermost mantle



320 beneath the northern Red Sea at this depth does not confirm the hypothesis of significant hot
321 asthenosphere upwelling, which would exist in the case of active rifting. This result supports the
322 passive nature of extension, which is likely due to relative displacements of large lithospheric
323 plates, namely the African and Arabian Plates.

324 At the 40 km depth, the structure of P-velocities is considerably different than that
325 observed at the 30 km depth. Instead of the step-shaped contact zone identified at the 30 km
326 depth, we observe a nearly linear transition oriented from SSE-NNW. This feature may represent
327 the contrast between crustal velocities, which can still be observed at this depth for some
328 segments of the thick crust, and mantle velocities in the remaining areas with thinner crust.
329 According to the model of Moho depth from Mechie et al., (2013, Figure 5), this low-velocity
330 anomaly at the 40 km depth corresponds to the area of the crust with a thickness of more than 35
331 km, which is thicker than the crust in surrounding areas.

332 It would be interesting to study the relative velocity anomalies at depths that fully
333 correspond to the mantle to identify the link between mantle processes and crustal
334 displacements. Unfortunately, our model does not have sufficient resolution for depths greater
335 than 40 km. At our scale and in our area of interest, information on mantle structures can only be
336 derived from analysis of teleseismic data. Such work was performed for the Dead Sea area by
337 Koulakov et al., (2006), but it did not reveal any connection between crust and the mantle. If
338 such a connection existed in the Aqaba region, however, it should be much clearer because both
339 oceanic and continental mantle lithosphere coexist. Our future work will focus on analyzing the
340 teleseismic records provided by stations distributed in the whole area and will provide rich
341 information on mantle processes beneath the northern part of the Red Sea.

342

343 **Conclusions**

344 A large dataset containing arrival times from regional earthquakes provided by the
345 Egyptian National Seismological Network was used for a tomographic investigation of the



346 crustal structure beneath the area of the Gulf of Aqaba and northern Red Sea. The main results of
347 this work are the 3D models of P and S seismic velocities in the crust and uppermost mantle for
348 these regions. These models close the gap between the existing small-scale active source studies
349 of the uppermost crust beneath the offshore areas of the Red Sea and Gulf of Aqaba and large-
350 scale regional mantle models beneath Africa and Arabia derived from the inversion of body and
351 surface wave data.

352 The new seismic models reveal a strong high-velocity anomaly in the northern Red Sea,
353 with sharp boundaries coinciding with the coastal line. This implies an oceanic type crust and
354 seems to oppose the concept of gradual stretching of continental crust in the northern Red Sea
355 proposed by some authors. However, the question about development of the oceanic crust,
356 specifically regarding the absence of any traces of ridges and spreading centers in the northern
357 Red Sea that would require a rather dispersed extension of oceanic crust opposed to spreading
358 localized along rifts, still remains.

359 In the middle and lower crust, the seismic anomalies seem to delineate a step-shaped
360 pattern, which indicates the left-lateral displacement of the crust along the Dead Sea Transform
361 Fault. The estimated value of this displacement from the seismic tomography model is
362 approximately 100 km; this is consistent with existing estimates from geological and
363 geomorphology data for the southern part of the DST.

364 At the 40 km depth, no apparent link between the location of the Gulf of Aqaba and the
365 DST fault zone is observed. Instead, there is a zone of relatively low P waves speed to the north
366 of Aqaba continuously crossing the fault, which was also detected in the independent crustal
367 model of Eastern Mediterranean by Koulakov and Sobolev (2006). It is not entirely clear how
368 this continuous zone could be conserved after more than 100 km of displacement along the DST
369 fault. Considering the relatively thin lithosphere (60-70 km), which has a tendency for southward
370 thinning (Mohsen et al., 2006) in this region, one might assume that the anomalies are mostly
371 controlled by present-day thermo-mechanical processes in the lower-most lithospheric mantle



372 and asthenosphere, rather than the tectonic history of the region. However, this question still
373 requires further investigations.

374

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380

381 Figure captions:

382 Figure 1. A. Major tectonic framework of the study area schematically representing the main
383 displacements of the major plates. The blue line is the transform fault, the red lines are
384 the divergent areas, and the violet line depict the convergent boundaries. DST is the
385 Dead Sea Transform Fault. B. Tectonic units in the area of Gulf of Aqaba. Grey lines
386 are faults in Egypt (Darwish and El Ababy, 1993, Bosworth and McClay, 2001); blue
387 lines are the faults in Saudi Arabia and red dotted lines are dykes according to Eyal et
388 al. (1981).

389 Figure 2. Back reconstruction of the displacements along the DST since the initiation in Early
390 Miocene in the left (Eyal et al., 1981) and present topography along DST. Red lines
391 mark the main structures at the initial stage for reference.

392 Figure 3. Distributions of seismic stations (blue triangles) and seismic events (orange dots) used
393 in this study for tomographic inversion.

394 Figure 4. Distributions of the ray paths (grey dots) and nodes of the parameterization grid (red
395 dots). Depth intervals and types of data are indicated in the caption.



396 Figure 5. Results of the checkerboard test with the model unchanged with depth for P and S
397 velocity anomalies. Dotted lines indicate the configurations of the “true” synthetic
398 patterns. Triangles depict seismic stations.

399 Figure 6. Checkerboard tests with the model changing the sign of anomalies at 20 km depth.
400 Dotted lines indicate the configurations of the “true” synthetic patterns. Triangles depict
401 seismic stations.

402 Figure 7. P and S anomalies resulted from the observed data inversion in four horizontal
403 sections. At 10 km depth, major tectonic units, same as in Figure 1b, are shown. In
404 sections at 20 and 30 km depth, the reference lines marking the displacements along the
405 DST are depicted with green dotted lines.

406 Figure 8. Absolute P-velocity at 30 km depth and in four vertical sections. Locations of the
407 sections are shown in the map. White dots are the projections of earthquakes onto the
408 profiles.

409 Figure 9. Same as Figure 8, but for the S absolute velocities.

410 Figure 10. Back-reconstruction of the P-velocity model at 10 km and 30 km depth according to
411 the DST displacements presented in Figure 2. Green dotted lines depict the reference
412 markers for the displacement. Violet lines are the structures discussed in the text.

413

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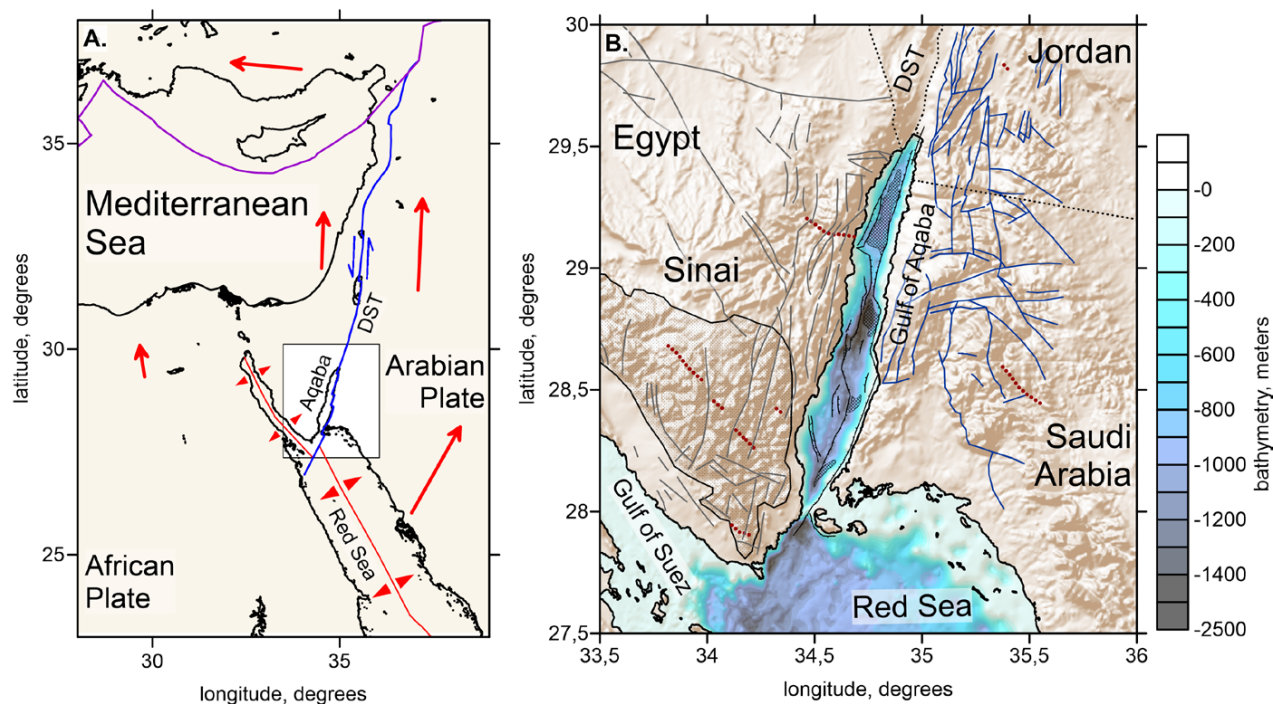


Figure 1. A. Major tectonic framework of the study area schematically representing the main displacements of the major plates. The blue line is the transform fault, the red lines are the divergent areas, and the violet line depict the convergent boundaries. DST is the Dead Sea Transform Fault. B. Tectonic units in the area of Gulf of Aqaba. Grey lines are faults in Egypt [Darwish and El Ababy, 1993, Bosworth and McClay, 2001]; blue lines are the faults in Saudi Arabia and red dotted lines are dykes according to Eyal et al. [1981].

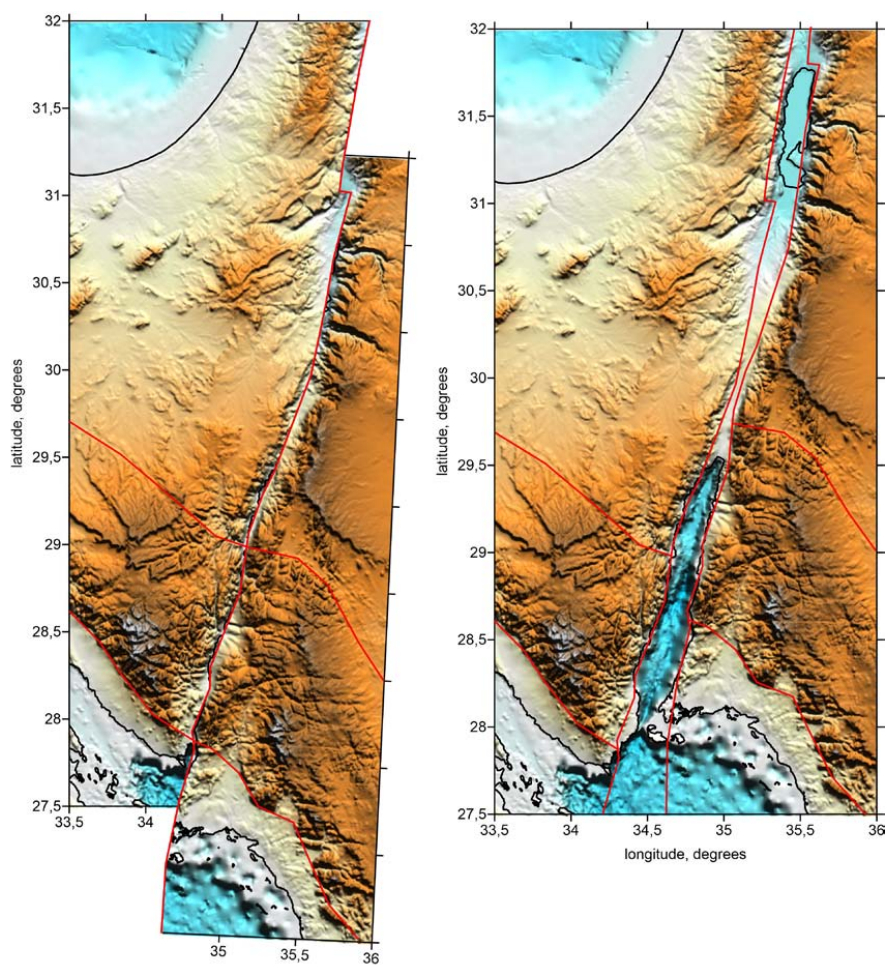


Figure 2. Back reconstruction of the displacements along the DST since the initiation in Early Miocene in the left [Eyal et al., 1981] and present topography along DST. Red lines mark the main structures at the initial stage for reference.

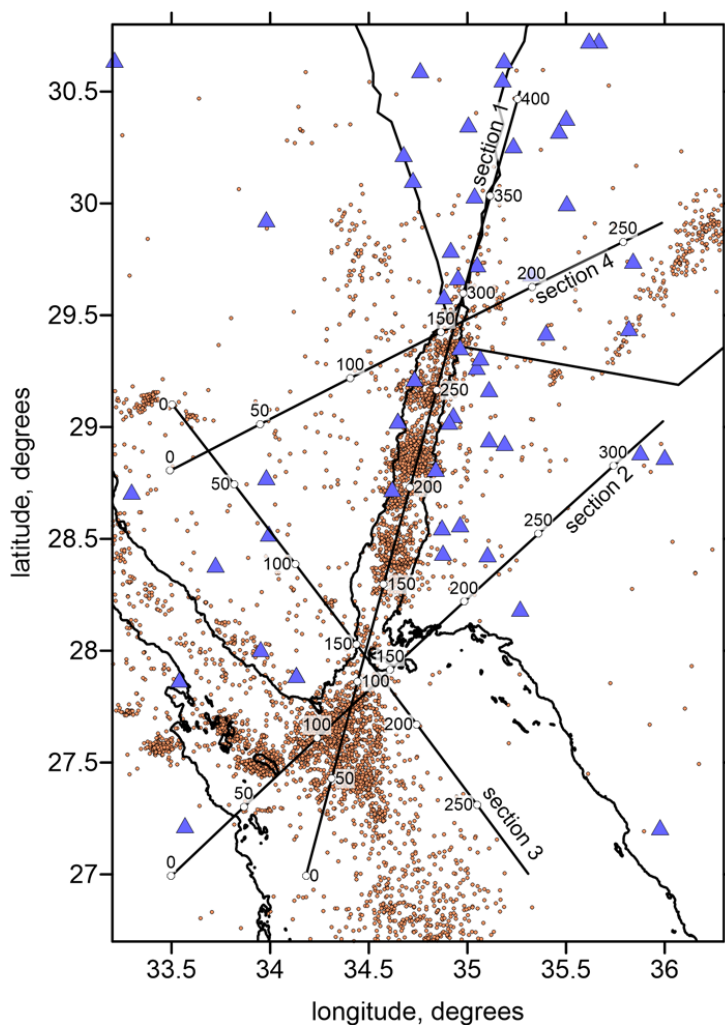


Figure 3. Distributions of seismic stations (blue triangles) and seismic events (orange dots) used in this study for tomographic inversion.

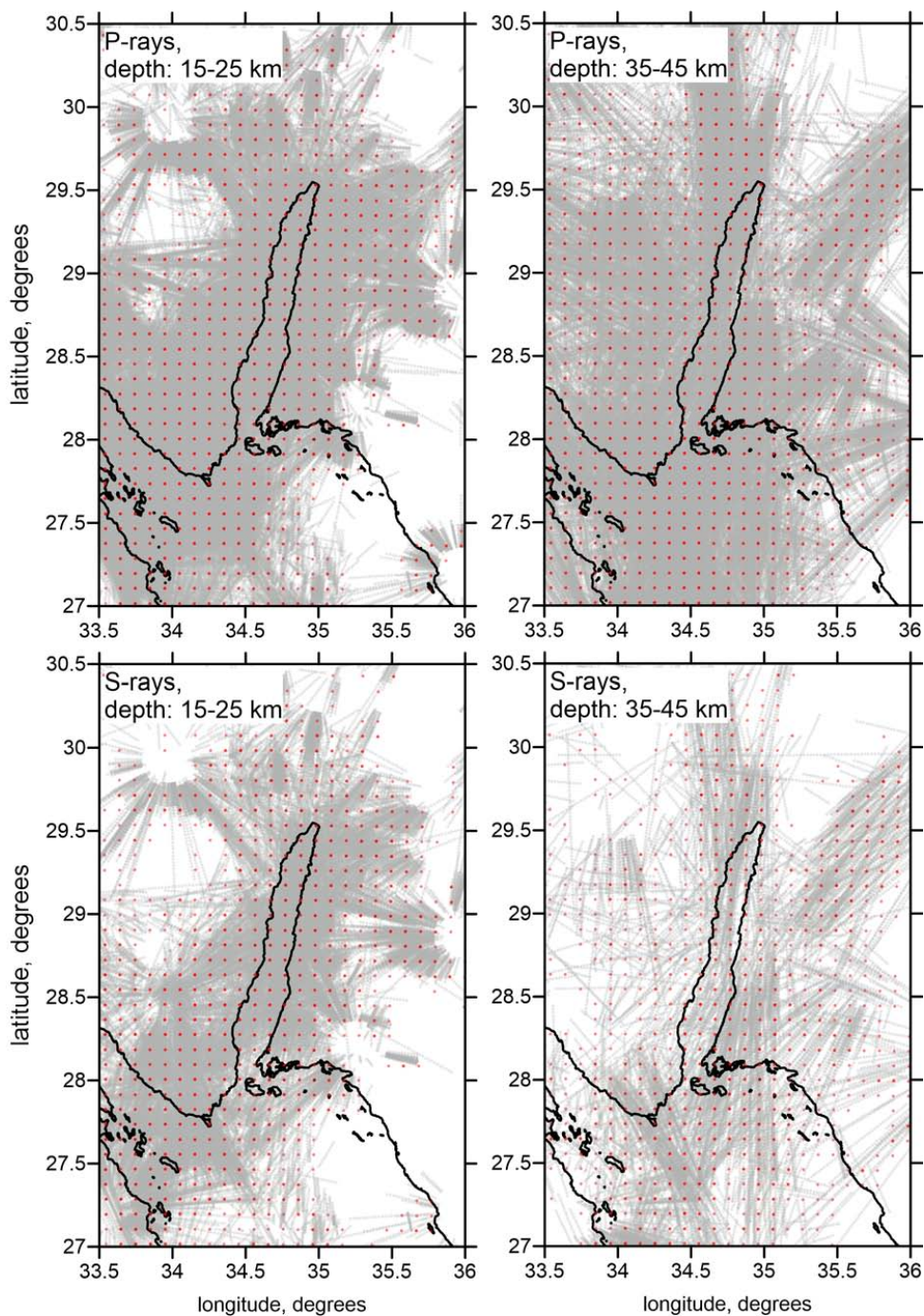


Figure 4. Distributions of the ray paths (grey dots) and nodes of the parameterization grid (red dots). Depth intervals and types of data are indicated in the caption.

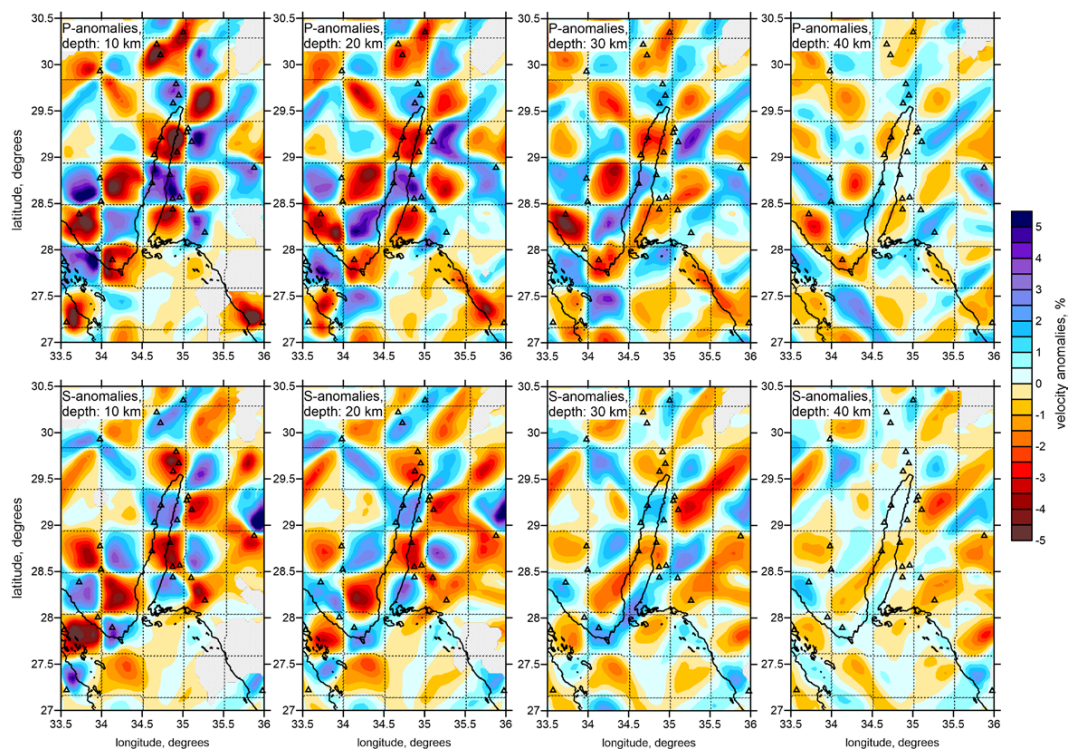


Figure 5. Results of the checkerboard test with the model unchanged with depth for P and S velocity anomalies. Dotted lines indicate the configurations of the “true” synthetic patterns. Triangles depict seismic stations.

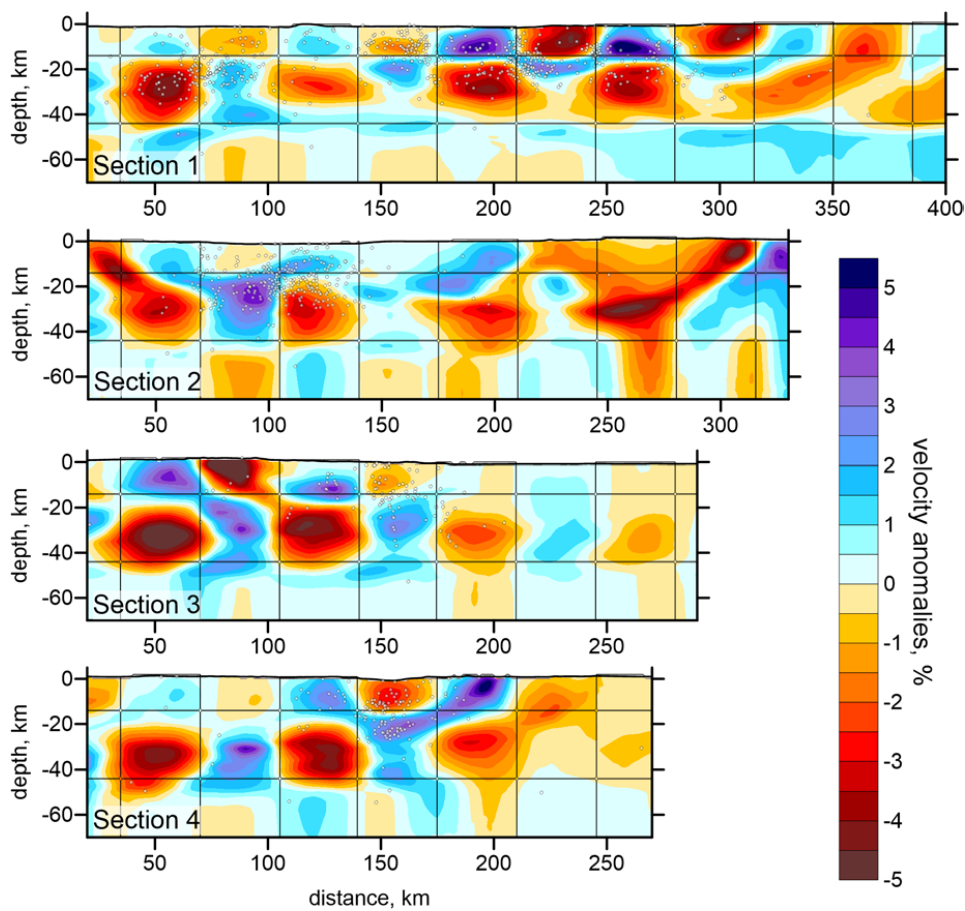


Figure 6. Checkerboard tests with the model changing the sign of anomalies at 20 km depth. Dotted lines indicate the configurations of the “true” synthetic patterns. Triangles depict seismic stations.

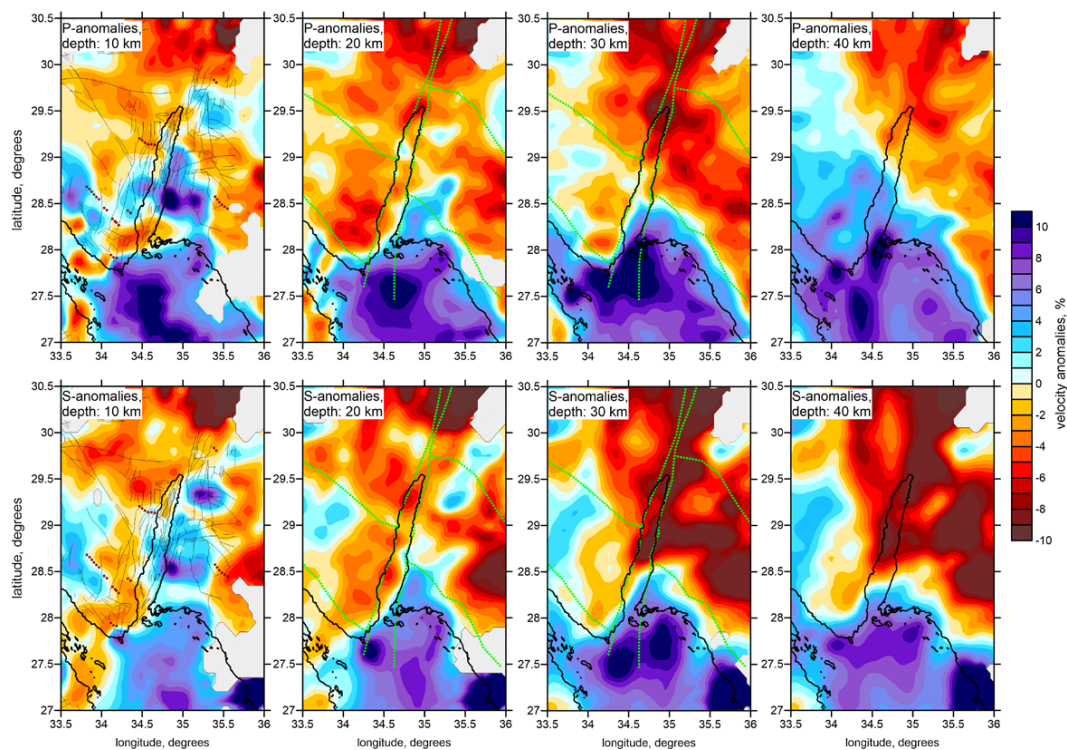


Figure 7. P and S anomalies resulted from the observed data inversion in four horizontal sections. At 10 km depth, major tectonic units, same as in Figure 1b, are shown. In sections at 20 and 30 km depth, the reference lines marking the displacements along the DST are depicted with green dotted lines.

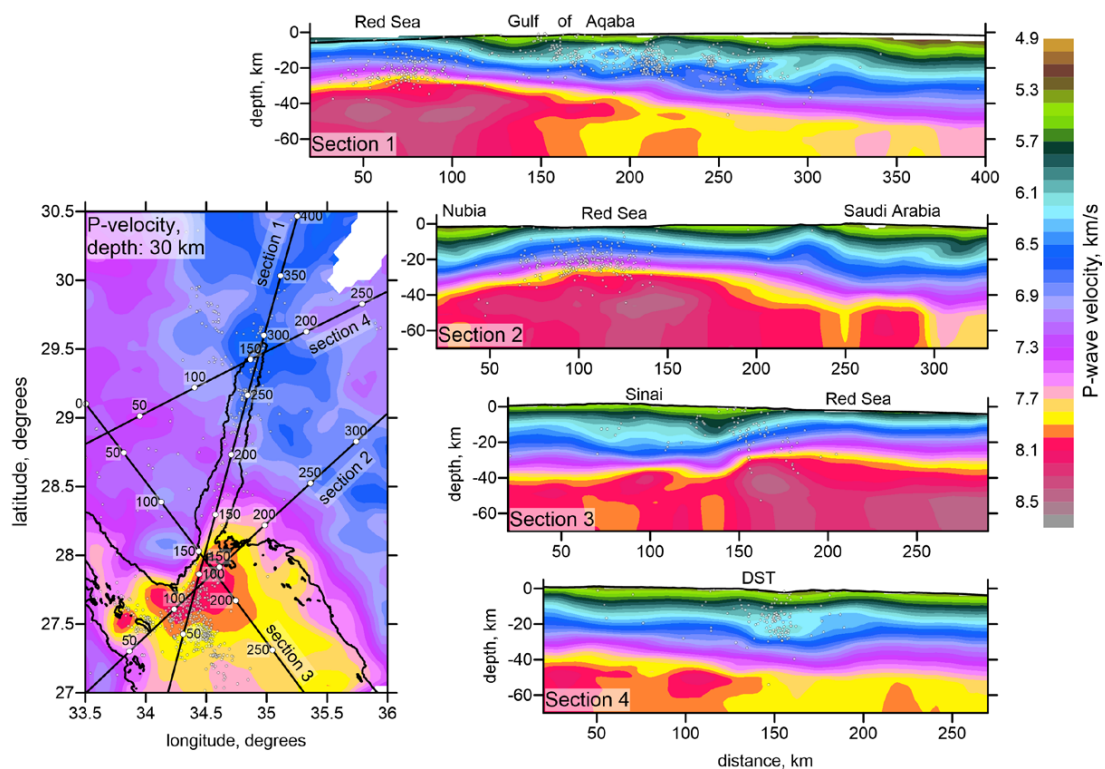


Figure 8. Absolute P-velocity at 30 km depth and in four vertical sections. Locations of the sections are shown in the map. White dots are the projections of earthquakes onto the profiles.

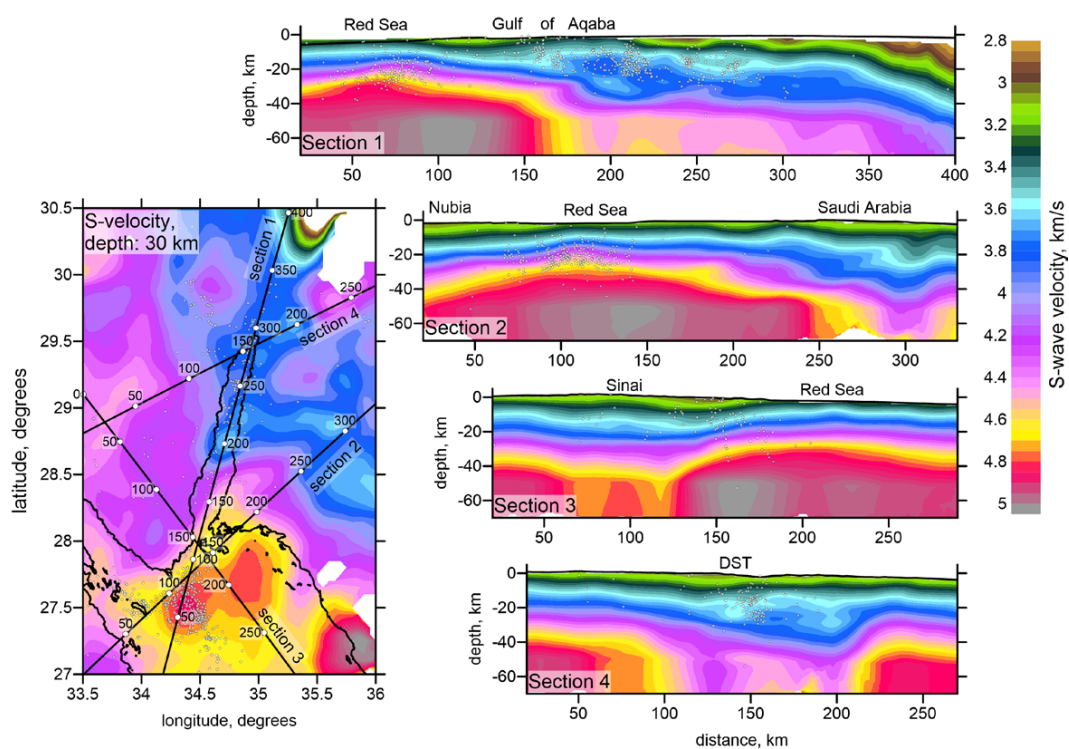


Figure 9. Same as Figure 8, but for the S absolute velocities.

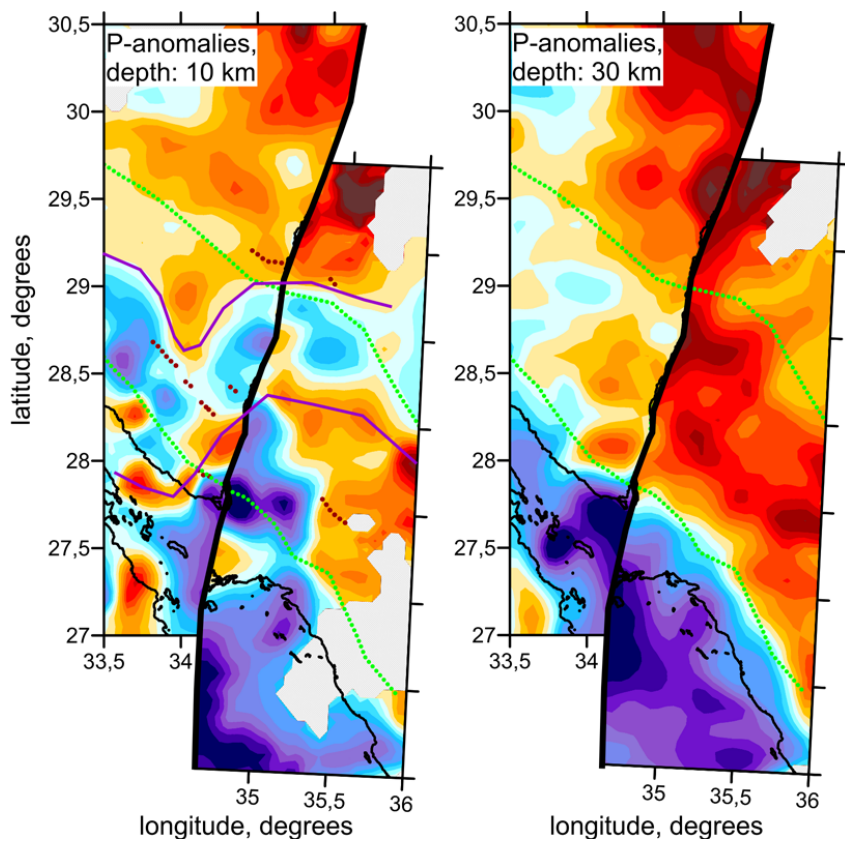


Figure 10. Back-reconstruction of the P-velocity model at 10 km and 30 km depth according to the DST displacements presented in Figure 2. Green dotted lines depict the reference markers for the displacement. Violet lines are the structures discussed in the text.