



# 1 A new methodology to train fracture network simulation 2 using Multiple Point Statistics

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18 Keywords: geostatistics, multiple training images, probability map, fracture networks, stress-induced  
19 fracture aperture, outcrop.

20

## 21 Abstract

22 Natural fractures have a strong impact on flow and storage properties of reservoirs. Their  
23 distribution in the subsurface is largely unknown mainly due to their sub-seismic scale and to  
24 the scarcity of available data sampling them (borehole). Outcrop can be considered as  
25 analogues where natural fracture characteristics can be extracted. However, acquiring fracture  
26 data on outcrops may produce a large amount of information that needs to be processed and  
27 efficiently interpreted to capture the key parameters defining fracture network geometry.  
28 Outcrops thus become a natural laboratory where the interpreted fracture network can be  
29 tested mechanically (fracture aperture, distribution of strain/stress) and dynamically (fluid  
30 flow simulations (Bisdom et al., 2017)).



31 The goal of this paper is to propose the multiple point statistics (MPS) method as a new tool  
32 to quickly predict the geometry of a fracture network in both surface and subsurface  
33 conditions. This sequential simulation method is based on the creation of small and synthetic  
34 training images representing fracture distribution parameters observe in the field. These  
35 training images represent the complexity of the geological object or processes to be simulated  
36 and can be simply designed by the user. In this paper we chose to use multiple training images  
37 and a probability map to represent the fracture network geometry and its potential variability  
38 in a non-stationary manner. The method was tested on a fracture pavement (2D flat surface)  
39 acquired using a drone in the Apodi area in Brazil. Fractures were traced manually on images  
40 of the outcrop and constitute the reference on which the fracture network simulations will be  
41 based. A sensitivity analysis emphasizing the influence of the conditioning data, the  
42 simulation parameters and the used training images was conducted on the obtained  
43 simulations. Stress-induced fracture aperture calculations were performed on the best  
44 realisations and on the original outcrop fracture interpretation to qualitatively evaluate the  
45 accuracy of our simulations.

46 The method proposed here is innovative and adaptable. It can be used on any type of rocks  
47 containing natural fractures in any kind of tectonic context. This workflow can also be applied  
48 to the subsurface to predict the fracture arrangement and its fluid flow efficiency in water,  
49 heat or hydrocarbon reservoirs.

50

## 51 **I] Introduction**

### 52 **I.1 The importance of the prediction of fracture network geometry**

53 Fractures are ubiquitous in Nature and are known to impact fluid flow and fluid storage in  
54 water (Berkowitz, 2002; Rzonca, 2008), heat (Montanari et al., 2017; Wang et al., 2016) and  
55 hydrocarbon reservoirs (Agar and Geiger, 2015; Lamarche et al., 2017). They are typically



56 organised as networks ranging from nanometre to multi-kilometre scale (Zhang, 2016), and  
57 present systematic geometrical characteristics (i.e. type, orientation, size, chronology,  
58 topology) that are inherited from specific stress and strain conditions. These conditions are  
59 typically well known in folded (Suppe, 1983, 1985; Tavani et al., 2015; Watkins et al., 2017),  
60 faulted (Faulkner et al., 2010; Matonti et al., 2012; Micarelli et al., 2006) and burial-related  
61 contexts (Bertotti et al., 2017; Bisdorn, 2016) and have been used to derive concepts of  
62 fracture arrangements. These concepts are currently used to predict reservoir heterogeneity  
63 and to define potential permeability pathways within the rock mass (Lamarche et al., 2017;  
64 Laubach et al., 2018). Despite the existence of these concepts, fracture networks generally  
65 present an intrinsic complexity (e.g. variability of orientation, local occurrence of new  
66 fracture family, change of topology relationships) due, among others, to local variability of  
67 the orientation and magnitude of stresses. This makes fractures hard to predict. Moreover,  
68 fractures in subsurface reservoirs are largely unknown due to their sub-seismic size and to the  
69 scarcity of available data, which is generally limited to borehole information.

70

## 71 **I.2 Surface rocks as multiscale reservoir analogues**

72 In this context, the study of outcrop analogues is one of the few ways to constrain the  
73 architecture of fracture networks (Bisdorn et al., 2014; Bruna et al., 2017; Lamarche et al.,  
74 2012; Lavenu, 2013). Outcrops can be considered as a natural laboratory where the structural  
75 reality can be observed and quantified at various scales. At the small – measurement station –  
76 scale (order of 10's m), fracture type, chronologies and topology relationships can be  
77 characterised using classical ground-based structural geology method such as scanlines  
78 (Lavenu et al., 2013; Mauldon et al., 2001). At the intermediate – outcrop – scale (order of  
79 10<sup>2</sup>'s m), length of fractures and geometry variability can be qualified and quantified using  
80 unmanned aerial vehicles (UAV - drones). Working on outcrops allows an understanding of



81 the geological history of the targeted area and eventually to decipher how, when and where  
82 fractures were developed. In addition, outcrops constitute an efficient experimental laboratory  
83 where some of properties of the fracture network (i.e. fracture distribution, apertures,  
84 permeability and fluid flow behaviour) can be known and modelled (Bisdom et al., 2017). At  
85 the large – reservoir – scale (order of  $10^{3-4}$  m) satellite imagery and geophysical maps provide  
86 the characterisation of the 100's of meter long objects such as large fracture systems or faults.

87

### 88 **I.3 Modelling approaches classically used to model fracture network geometries**

89 The widely used discrete fracture network (DFN) stochastic modelling tools are providing  
90 statistical representation of fracture network constrained generally by univariate and random  
91 distribution of orientation, size, spacing and density/intensity data (Bisdom et al., 2014;  
92 Bisdom et al., 2017; Huang et al., 2017; Panza et al., 2018). The generated models implicitly  
93 follow a local stationarity hypothesis suggesting the invariance of all of the generated  
94 statistics by translation in the simulated domain (Deutsch and Journel, 1997; Gringarten and  
95 Deutsch, 1999; Gringarten and Deutsch, 2001; Journel and Zhang, 2006). Liu et al., (2009),  
96 highlighted the implicit randomisation that conventional discrete fracture networks models  
97 produce and demonstrated that parameters like fracture connectivity are poorly considered in  
98 these representations. In addition, it is generally admitted that discrete realisations of  
99 thousands of fractures objects at the kilometre scale are computationally very demanding and  
100 often even impossible (Jung et al., 2013). Some authors attempted to use a pixel-based  
101 method to try to predict fracture network geometries. Bruna et al., (2015), used a dense  
102 hydrogeological borehole survey sampling a Lower Cretaceous aquifer in the SE of France to  
103 define fracture facies and to model their distribution with two-points geostatistics. In this  
104 case, the amount of available data and their consistency helped to provide realistic results.



105 However, far from conditioning data (i.e. boreholes) the fractures simulation are under  
106 constrained.

107

#### 108 **I.4 Multi-point statistics as an alternative to classic DFN approaches**

109 Since Liu et al., (2002), few authors highlighted the potential of using multi-point statistics  
110 (MPS) to generate realistic fracture networks (Chugunova et al., 2017; Karimpouli et al.,  
111 2017). Strebelle, (2002) showed how the MPS are able to reproduce any type of geological  
112 heterogeneities of any shape at any size as long as they present a repetitive character. This  
113 characteristic seems particularly well adapted to predict the geometry of a fracture network.  
114 The MPS method uses training images (TI) to integrate conceptual geological knowledge into  
115 geostatistical simulations (Mariethoz, 2009). The TI is a grid containing geological patterns  
116 that are representative of a certain type of geological structure, type and arrangement. The TI  
117 can be considered as a synthetic model of the geological heterogeneity (i.e. all the elements  
118 characterising a geological object) likely to occur in a larger domain (i.e. reservoir, aquifer,  
119 outcrop). The TI must include the possible range and shape of the geobodies that the  
120 geoscientist intends to model, as well as the relationship these geobodies have with each other  
121 (Mariethoz, 2009; Strebelle, 2002).

122

#### 123 **I.5 Objectives and contents of this research**

124 In this paper we propose a MPS workflow considering fracture network geometry variability  
125 over full outcrops and a methodology on how to use this method at the reservoir scale. The  
126 approach is based on the direct sampling method (Mariethoz et al., 2010) and uses multiple  
127 training images for a single realisation (Wu et al., 2008). The concept of the probability map  
128 has been revised here to define where a training image should be used in the simulation grid.  
129 Our outcrop-based simulations also take into account “seismic-scale” objects (i.e. object



longer than 40m) considered as hard conditioning data. The proposed workflow is tested on outcrops considered as analogues of the Potiguar Basin, Brazil where fracture network have been previously characterised and interpreted from drone imagery (Bertotti et al., 2017; Bisdom, 2016). Uncertainties were evaluated by comparing original outcrop interpretation (done manually by a geologist) with the geometrical characteristics of the network generated from MPS. To evaluate the quality of the simulations, we computed mechanical and hydraulic apertures in outcrop fracture interpretation and on the obtained stochastic models. The proposed approach breaks new ground as it provides a quick and efficient way to represent fracture network arrangements at various scales.

139

## 140 II] Methodology

### 141 II.1 The direct sampling method

The direct sampling method (DS) was introduced by (Mariethoz et al., 2010). Figure 1, synthesizes the DS modelling process developed thereafter. The method requires a simulation grid where each node is initially unknown and called  $\mathbf{x}$ , a training image grid (TI) where each node is known and called  $\mathbf{y}$  i.e.  $V(\mathbf{y})$  is defined where  $V$  is the variable of interest (e.g. facies value). The simulation proceeds as follows. First, the set of conditioning data (if present) is integrated in the simulation grid. Then, each remaining unknown node  $\mathbf{x}$  is visited following a random or defined path, and simulated as follows. 1) The pattern  $\mathbf{d}_n(\mathbf{x}) = (\mathbf{x}_1, V(\mathbf{x}_1)), \dots, (\mathbf{x}_n, V(\mathbf{x}_n))$  formed by the at most  $n$  informed nodes the closest to  $\mathbf{x}$  is retrieved. Any neighbour  $\mathbf{x}_i$  of  $\mathbf{x}$  is either a previously simulated node or comes from the conditioning data set. The lag vectors  $\mathbf{h}_i = \mathbf{x}_i - \mathbf{x}$  define the geometry of the neighbourhood of  $\mathbf{x}$ . The combination of the value and position of  $\mathbf{x}_i$  defines the data event or pattern  $\mathbf{d}_n(\mathbf{x})$ . 2) Then, the TI is randomly scanned to search for a pattern  $\mathbf{d}_n(\mathbf{y})$  similar to  $\mathbf{d}_n(\mathbf{x})$ . For each scan node  $\mathbf{y}$ , the pattern  $\mathbf{d}_n(\mathbf{y}) = (\mathbf{y}_1, V(\mathbf{y}_1)), \dots, (\mathbf{y}_n, V(\mathbf{y}_n))$ , where  $\mathbf{y}_i = \mathbf{y} + \mathbf{h}_i$ , is compared to  $\mathbf{d}_n(\mathbf{x})$  using a distance



155 (Meerschman et al., 2013). When the distance is lower than an acceptance threshold ( $t$ )  
156 defined by the user or if the proportion of scanned nodes in the TI reaches a maximal fraction  
157 ( $f$ ) defined by the user, the scan is stopped and the value of the best candidate  $y$  (pattern with  
158 the minimal distance) is directly attributed to  $x$  in the simulation grid (i.e.  $V(x) = V(y)$ ).

159 As the DS method does not use a catalogue of all possible patterns found in the TI, it is  
160 extremely flexible and in particular allows taking into account both categorical and  
161 continuous variables and managing multivariate cases, provided that the pattern distance is  
162 suitable. In this paper we are using the DeeSse version of the direct sampling code.

163

## 164 II.2 Multiscale fracture attributes

165 To evaluate how the direct sampling method is dealing with the fracture network, the present  
166 experimentation is based on outcrop data (reference) where the present-day “structural  
167 reality” is observable at various scales. Pavements (i.e. horizontal surfaces in the order of  $10^2$   
168 m scale) were targeted because these objects contain important information that is not always  
169 accessible with standard vertical outcrops (Corradetti et al., 2017a; Corradetti et al., 2017b;  
170 Tavani et al., 2016) or with classic geophysical imagery. Pavement sizes allow the user to  
171 interpret and localise fracture patterns variability (Bruna et al., 2018). For instance, clusters of  
172 fractures (i.e. local increase of the fracture density) can be identified by the interpreter.  
173 Pavements also allow obtain quantitative data on fracture lengths, which are usually difficult  
174 to obtain in vertical cliff objects. In the subsurface, data can be provided by geophysical 3D  
175 maps and fracture attribute detection tools (Chopra and Marfurt, 2007; Somasundaram et al.,  
176 2017). However, these tools are not always available and detect the longer lineaments only  
177 (e.g.  $> 50$  m long depending on the resolution of the imagery).

178 Working with pavements constitutes an asset as small-scale investigation can be conducted in  
179 key zones of the outcrop (i.e. in folded areas, each compartment or dip domain of the fold



180 should be imaged and investigated in detail) where the gathered data will help to calibrate  
181 larger scale information. Classical fieldwork methods (observation and characterisation,  
182 measurements, statistical analyses, sampling) help interpreting fracture families and are  
183 essential to constrain larger scale observation.

184 In this study, UAV-based photogrammetry is used to obtain an orthorectified mosaic and 3D  
185 digital outcrops models (Bemis et al., 2014; Claes et al., 2017; Vollgger and Cruden, 2016).  
186 The scale of these images is an intermediate between the scale of measurement station and  
187 that of satellite imagery. Digitization of fracture traces, geological contacts, sedimentary  
188 structures and structural domain boundaries are currently processed by hand and represent a  
189 considerable time investment. In this contribution, fractures were interpreted in orthomosaic  
190 images with the help of GIS software. Length, azimuth, fracture family proportions and  
191 fracture density statistics were extracted from the interpretation. In addition, a series of  
192 measurement station (area of about  $2 \times 2$  m) information was acquired and compared with the  
193 dataset from the drone imagery in order to align interpretations and provide coherent fracture  
194 history.

195

## 196 **II.3 Training images, conditioning data and probability maps**

### 197 • **Training images**

198 Training images (TI) are the base input data of the MPS simulation. Building them is a critical  
199 step to succeed a realisation (Liu et al., 2009). The TI is a pixelated image based on a local  
200 interpretation of a geological phenomenon (i.e. an interpreted photography taken from a local  
201 zone of interest in the field) or digitised by a geologist and based on geological concepts  
202 (Strebelle, 2002). These images should synthesise all of the recognized geological parameters  
203 that characterise the area to simulate. This implicitly means that the proportion of facies  
204 carried by the TI, will be reproduced into the simulation grid but this also requires extensive





205 pre-processing work. To manage this complexity, we propose to use multiple training images  
206 where facies proportion and geometrical distribution can vary. Hence, each TI has a local  
207 impact on the simulation. Moreover, in our approach fractures sets are grouped in facies in the  
208 TI, based primarily on their orientation and possibly on their length or additional parameters  
209 defined by the user. The fractures classification helps reproducing patterns and simplifies the  
210 process of building the TI.

211 • **Conditioning data**

212 One limitation of the MPS methods is the tendency to disconnect long continuous objects (i.e.  
213 typically fractures, (Bruna et al., 2017). To manage this issue, longer fractures can be  
214 identified and incorporated into the simulation as conditioning data. As per the training  
215 images, these data can be integrated as pixelated grids. They may come from satellite imagery  
216 or they can be interpreted from gravity or magnetic surveys or from 3D seismic imagery  
217 (Magistrone et al., 2014).

218 • **Probability map**

219 The direct sampling method can be used with multiple training images. In this situation, the  
220 user provides a set of TIs, and for each TI a probability map defined on the simulation grid,  
221 giving at each node the probability to use that TI. The pixel-wise sum of these maps should  
222 then be equal to one in every node. If each TI corresponds to a partition of the area of interest,  
223 with for each TI one elementary zone, covering the whole simulation grid, the probabilities in  
224 the map are set to one for specific TI and to zero for the other ones.

225 The probability map comes from a simple sketch (i.e. a pixelated image) given by the MPS  
226 user. It is based on geological concepts that define the geometry variability over the simulated  
227 area. In each of these areas the simulated property will follow the intrinsic stationary  
228 hypothesis (Gringarten and Deutsch, 2001; Journel and Zhang, 2006; Journel, 2005) but the  
229 entire domain will be non-stationary. These maps provide a large-scale framework that may



230 be refined and modified with additional data such as measurement stations or drone surveys  
231 coming from surface exploration or wells data containing fracture network information.

232

#### 233 **II.4 Testing the simulated network: from pixels to segments**

234 MPS realisations are produced as pixelated images. To evaluate the resulting fracture  
235 network, pixels alignments corresponding to fractures are extracted as discrete straight-line  
236 objects defined by starting and an ending x, y coordinates using a custom MATLAB routine.  
237 Fractures are separated from the background and in different sets by automatic image  
238 classification methods. On grayscale images, this is obtained by multilevel image  
239 thresholding through the Otsu's method (Otsu, 1979). On color images, fracture sets are  
240 classified based on their color components with the k-means clustering algorithm built in in  
241 MATLAB (Lloyd, 1982), on images previously converted to the perceptually uniform Lab  
242 color space. Image classification gives in output a series of binary images, one for each  
243 fracture set, where lineaments are represented as foreground. The foreground segments are  
244 finally fitted with straight lines using the *lineseg.m* algorithm by (Kovesi, 2000), which gives  
245 in output a list of starting and ending point coordinates for each fracture set.

246

### 247 **III] Results: test case on analogues of the Potiguar Basin, E Brazil**

#### 248 **III.1 Geological setting**

249 The Potiguar Basin is a rift basin located in the easternmost part of the Equatorial Atlantic  
250 continental margin, NE Brazil (fig. 2). The basin is found both onshore and offshore (fig. 2).  
251 The basin was generated after the initiation of the South American and African breakup  
252 during the Jurassic - Early Cretaceous times. It was structured by a first NW-SE extension  
253 stage latterly rotating to an E-W extensional direction (Costa de Melo et al., 2016). The rift  
254 basin displays an architecture of horsts and grabens striking NE-SW and bounded towards the



255 east and south by major faults systems (de Brito Neves et al., 1984), fig. 2). The Potiguar  
256 Basin displays three sedimentary sequences deposited since the early Cretaceous times (i.e.  
257 syn- and post rift depositions). The last post-rift sequence was deposited from the Albian and  
258 encompasses the Cenomanian-Turonian Jandaíra Formation. This formation consists of up to  
259 700 m thick bioclastic calcarenites and calcilutites deposited in transgressive shallow marine  
260 environment. The stress field affecting the Jandaíra Formation during the Campanian to the  
261 Miocene compression was oriented N-S (Bertotti et al., 2017). From the Miocene to the  
262 Quaternary the onshore part of the Potiguar basin was uplifted. Synchronously, a new stress  
263 field was established trending to a NW-SE direction (Reis et al., 2013).

264

### 265 **III.2 Outcrop data**

266 The area of interest measures  $2.1 \times 1.3$  km and is located about 25 km NE of the city of Apodi  
267 in the Rio Grande Do Norte state (fig. 2). It contains two outcrops AP3 and AP4 (Bertotti et  
268 al., 2017; Bisdorn, 2016), fig. 2) here defined respectively as  $600 \times 300$  m and  $400 \times 500$  m  
269 large pavements localized in the Jandaíra Formation. AP3 and AP4 crop out as pavements  
270 with no significant incision. The outcrops are sparsely covered by vegetation and  
271 consequently they present a clear fracture network highlighted by karstification. In 2013,  
272 images of AP3 and AP4 were acquired using a drone (Bisdorn, 2016) and processed using the  
273 photogrammetry method. Two high-resolution ortho-rectified images of these pavements  
274 (centimetre-scale resolution) were used to complete fracture network interpretation and to  
275 extract fracture parameters. In AP3, 775 lineaments were traced (fig. 3) and in AP4, 2593 (fig.  
276 4). These lineaments are grouped in this article over the general term “fractures”. For each of  
277 these outcrops three fractures sets were identified: set1 striking N135-N165, set2 striking  
278 N000-N010/N170-N180 and set 3 striking N075-N105. Fractures falling outside of these  
279 ranges were not considered in the input data. Consequently, in AP3 we considered 562 only



280 (out of 775 fractures traced in the pavement) and in AP4 we considered 1810 only out of 2594  
281 fractures. In addition, ground-based fieldwork was conducted in AP3 and AP4 to understand  
282 the structural history of the area and to calibrate the interpretation conducted on the drone  
283 aerial photography (Van Eijk, 2014). General location and fracture data are presented in  
284 figure 3 and 4 and in table 1.

285 In AP3, sets 1 and 2 are evenly distributed over the pavement. However, they present intrinsic  
286 intensity variability in the area of interest. Set 3 is mainly expressed in distinct regions of the  
287 outcrop. Small-scale investigations (conducted on measurement stations in the outcrop)  
288 allowed associating set 3 with stylolite and sets 1 and 2 to veins. In addition, sets 1 and 2  
289 present evidences of shear movements and are then considered as a conjugate system.

290 In AP4 small-scale investigations highlight the same characteristics as the ones observed in  
291 AP3. Although the conjugate system (set 1 and set 2) is less developed there than in AP3. It is  
292 also notable that more crosscutting relationships were observed in AP4 compared to AP3.

293

### 294 **III.3 Input data for MPS simulation**

295 AP3 illustrates the effect of conditioning data and of simulation parameters in the stochastic  
296 realisations. To evaluate the effect of conditioning data, results of two simulations were  
297 compared, with and without conditioning data. The sensitivity of simulation parameters was  
298 investigated by varying i) the number of neighbours defining patterns (data events  $d_n$ ), ii) the  
299 acceptance threshold ( $t$ ) defining the tolerance the algorithm authorises to find a matching  
300 data event in the simulation grid (Mariethoz et al., 2010) and iii) the fraction of the TI to be  
301 scanned during the simulation process to search for data events. Results of this sensitivity  
302 analysis help to propose the best possible simulation for AP3 and to optimise the choice of  
303 input parameters for AP4 fracture simulation.



AP3 presents intrinsic fracture network geometry variability. This observation emphasizes that averaging fracture parameters on the entire domain is not well suited to represent the complexity of the network. We observed that the length of fracture per sets and the density of fractures are parameters that vary the most here. The analysis of these variations allow to partition AP3 and AP4 in elementary zones and to synthesize the fracture network characteristics in each of these domains. The following section defines how the TI, PM and conditioning data were built.

#### • Partitioning, training images and probability map for AP3 and AP4

We divided AP3 in 5 elementary zones (EZ) based on visual inspection the pavement (fig. 5A-B). The number of fractures per EZ is synthesized in the figure 5. The proportion of fracture per elementary zone is available in table 1. A limited part of the fractures belong to two neighbours elementary zones. This issue is quantified in table 1.

A probability map with sharp boundaries (fig. 5B) was created for AP3. Sharp boundaries are justified by the variability of the network geometry, which is known from the visual inspection of the interpreted image. Smooth transitions could also be defined (see discussion). The input data to build the probability map is an image of the partition of the area of interest containing the different outcrops. In this image, the indexed zones (elementary zones EZ) are characterised by a distinctive colour.

The goal of this research is to show that MPS is able to accurately reproduce an existing fracture network (interpreted on AP3 outcrop) from small and simplified sketches (training images) representing what the network should look like in each elementary zone. At the scale of a reservoir where some outcrops analogues and fracture tracing may be available, the “interpreted reality” of the network can be directly used as a training image. We chose to ignore the tracing and to rely on parameters that are classically available without having access to drone images of an entire outcrop (i.e. orientation, spacing, abutment) and to



329 compare the interpretation with the simulated network. In that respect fracture orientation  
330 were averaged to a single value. Hence, set 1 strikes N150, set 2 strikes N000 and set 3 strikes  
331 N090. According to the outcrop partitioning, five training images were created (fig. 5C). In  
332 each training image, three facies corresponding to the three fracture sets were created. Set1  
333 (N090) is green, set 2 (N150) is red and set 3 (N000) is blue (fig. 5C). Topology is a crucial  
334 problem in fracture simulations because it influences the connectivity of the network. In the  
335 MPS simulations abutments are particularly well reproduced as they represent singular pixels  
336 arrangements that are efficiently taken into account. However, crosscutting relationships  
337 imply the use of a different facies at the intersection locus. This method respects and  
338 reproduces intersections during the simulation process. In AP3, the analysis of the topology  
339 relationships showed three main crosscutting interactions:

- 340 - Long N150 cross-cut long N000 fractures (conjugated sets)
- 341 - N000 cross-cut N090
- 342 - N150 cross-cut N090

343 To take into account these topological parameters a different facies colour was attributed to  
344 the cross-cutting locus (the crossing facies, fig. 6). When the MPS realization will be later  
345 discretized, the younger fractures will be truly represented as continuous segments. The older  
346 fractures will be cut in pieces but their alignment will be, in most of the case, maintained  
347 during the simulation process.

348 • **Dimensions of the simulations grids and of the training images**

349 The dimensions of the simulation grid for AP3 and of each training image (in pixels) are  
350 shown in fig.5. The number of pixels is automatically determined by the size of the original  
351 drawing made by the geologist.

352 The size of the input training image is generally not influencing the simulation. However, it  
353 has to be chosen sufficiently large with respect to the complexity of the patterns in order to



354 get reliable spatial statistics. The DS method tends to identify patterns (i.e.  $d_n$ 's see above) in  
355 the TI and to paste them into the simulation grid. However, at a constant resolution and  
356 specifically for fractures patterns, it is likely that a  $50 \times 50$  m training image will carry more  
357 complexity and variability than a  $10 \times 10$  m one. This parameter should be taken into  
358 consideration when starting digitizing training images, especially when spacing between  
359 fractures is not consistent across the simulation grid.

#### 360 • Long fractures conditioning

361 Because the MPS method has the tendency to cut long individual segments into smaller  
362 pieces, the fractures longer than 40 meters – the ones visible from satellite/drone imagery in  
363 AP3 – were isolated and considered as hard conditioning data (fig. 5D). This threshold was  
364 arbitrarily determined from the dataset we have. In AP3, less than 8% of the fractures are  
365 longer than 40 m.

366 In AP3, long fractures belong only to the sets oriented/striking N000 or N150 (fig. 5D). 18  
367 N000 fractures (3% of the whole) and 30 N150 fractures (5% of the whole) were digitized and  
368 integrated as conditioning data in the simulation.

369

### 370 III.4 Outcrop scale simulations

#### 371 III.4.1 Impact of conditioning data on AP3 simulations

372 In AP3, the 50 long fractures were manually digitized and imported into the simulation grid as  
373 categorical properties to be considered as hard conditioning data during the MPS simulation  
374 process. The MPS simulation is consequently in charge of stochastically populating the  
375 smaller fractures within the grid.

376 Results of the influence of these data are presented in figure 7. The principal simulation  
377 parameters in the considered scenarios (with and without conditioning data) were set up



378 identical (constant acceptance threshold (5%), constant percentage of scanned TI (25%) and  
379 constant number of neighbours (50)).

380 Results showed that the realisation without conditioning data creates 20% less fracture than  
381 the original outcrop reference. The simulation with conditioning data creates 9% less fractures  
382 than AP3, which makes the simulation satisfactory. It is also remarkable that the non-  
383 constrained simulation represents only 23 fractures above 40 meters (compared to the 50 long  
384 fractures interpreted on the AP3 outcrop). In this simulation the long fractures are essentially  
385 located in the zone 3 of the outcrop. Because the simulation is a stochastic process, the  
386 location of the long fractures is randomly determined in the absence of hard conditioning  
387 data. Considering hard-conditioning data also gives a more realistic representation of the  
388 fracture network.

389

#### 390 **III.4.2 Sensitivity analysis on the AP3 simulation parameters**

##### 391 **• Simulation parameter set-ups, duration and analyses conducted on the results**

392 Simulation parameters were varied for each simulation in order to emphasize their effect on  
393 each realisation. One realisation per test was performed during this analysis. The goal of this  
394 analysis is to show how the different parameters influence the reproduction of fracture  
395 segments and not to evaluate how good is the matching between the simulation and the  
396 reference.

397 The MPS realisations are pixelated images. The sensitivity analysis is based on the discrete  
398 segments extracted from these pixelated images (see II.4). All of the simulations present a  
399 variable percentage of segment lengths that are below the minimal fracture length interpreted  
400 in the AP3 outcrop (i.e. simulation noise). Consequently all segments smaller than 2.2m  
401 were removed from the simulation results. A length frequency distribution was compiled for  
402 each of the generated simulations.





403 The influence of the number of neighbours was evaluated through 7 simulations (SIM1 to  
404 SIM7). The acceptance threshold and the number of neighbours was investigated by  
405 comparing 8 simulations (SIM8 to SIM15) where the scanned fraction of the TI was fixed at  
406 25%. The percentage of the scanned fraction of the TI was combined with the 2 other  
407 simulation parameters. This combination was tested over 12 simulations (SIM16 to SIM27).  
408 The models set-ups and the duration of the simulations are presented in (table 2). It is notable  
409 that SIM8 / SIM9, SIM10 / SIM11 and SIM13 / SIM14 produce exactly the same network  
410 despite the modification of the simulation parameters. Also The MPS algorithm successfully  
411 performed SIM16 but the segment extraction generated an error preventing the discretisation  
412 of all of the objects. No solution was found to solve this issue.

413 The total amount of generated fractures was counted and compared with the total number of  
414 fractures interpreted from the original outcrop. A deviation of 10% compared to the original  
415 amount of interpreted fractures is considered as a satisfactory result as it is very close to the  
416 reference amount of fractures. A deviation of 20% compared to the original amount of  
417 interpreted fractures is considered as an acceptable result. This deviation is consequent but  
418 can be adjusted by varying the simulation parameters. A deviation above 20% was rejected as  
419 a complete reconsideration of the parameters is required. Results are synthesized in table 3.

420 The total amount of segments was initially counted in the entire simulation domain. The sum  
421 of segment per part is constantly higher than the initial total amount of segments because  
422 segments cutting a sharp boundary are divided in two - segments falling within two  
423 elementary zones and are consequently counted twice. The number of generated fractures per  
424 simulation zone was also computed and the same deviation thresholds were applied to  
425 evaluate if the simulation is satisfactory, acceptable or rejected. Tables 4 to 6 synthesize the  
426 sensitivity analysis conducted of 27 realisations of the AP3 outcrop.



427 The length of the segments have been computed for each realisation and are presented in  
428 figure 8.

429 The influence of the hard conditioning data and of the drawing of the training image was also  
430 quantitatively investigated and compared respectively with the length of the generated  
431 segments and with the amount of segments generated per zones

432 • **Summary of the results**

433 Increasing the number of neighbours rises the computation time (table 2, SIM 1 to 7). A small  
434 amount of neighbours results in a noisy simulation (table 2, SIM1). The contrary lead to a  
435 downsampling of the generated segments that becomes longer than the interpreted fractures in  
436 AP3 (table 2, SIM7). Decreasing the acceptance threshold leads to an increase of the  
437 simulation time (table 2 SIM8-15). Increasing the scanned fraction of the TI is the most time  
438 consuming operation (table 2 SIM17-27).

439 Increasing the number of neighbours only is generally not sufficient to accurately generate a  
440 satisfactory or acceptable total amount of fractures (table 3). Increasing the scanned fraction  
441 of the TI produces in all cases the closest total number of fractures compared to the reference  
442 outcrop (table 3).

443 The counting of fractures in simulation zones revealed that set 2 and set 3 in zone 1, set 3 in  
444 zone 4 and set 1 in zone 5 are generally underestimated during the simulation process. In  
445 contrast, fracture set 1 in zone 2 is generally overestimated. The consistency of the error over  
446 almost the entire set of simulations indicates an issue on the training image representation  
447 (table 4-6). Increasing the scanned fraction of the TI generally allows to better represent a low  
448 proportion of fracture facies within a TI (Zone TI5, set 2, table 6).

449 An acceptance threshold below 5% leads to an overestimation of the number of small  
450 fractures (between 0-10 m), fig 8. In this case, amount of segments between 0-20 m is  
451 generally close to the reality. Increasing the scanned fraction of the TI produces the highest



452 quantity of fractures ranging from 0-10 m (fig. 8). Increasing the number of neighbours and  
453 the percentage of the scanned TI will result in an increase of the length of the fractures used  
454 as hard conditioning data. However, the fracture elongation does not affect all of the hard  
455 conditioned fractures and represents a very small percentage of the whole modelled fracture  
456 network.

457

#### 458 **III.4.3 Attempt at an optimisation: OPT1**

459 OPT1 was parameterised in regard of the previous observations in order to generate a  
460 simulation that is the closest-to-reality possible. For this purpose, the amount of fractures  
461 from set 2 and set 3 drawn in TI1 and set 3 drawn in TI4 was increased. In contrast, the  
462 amount of fractures from set 1 drawn in TI2 was decreased significantly (fig. 9). We choose  
463 to setup the number of neighbours at 50 and the acceptance threshold at 2%. TI1 and TI4 will  
464 be scanned at 75% and the rest of the TIs will be scanned at 50% (table 2).

465 The simulation time for the proposed simulation is 2 min 31s (table 2). The total amount of  
466 generated fractures is satisfactory compared to the amount of fractures interpreted in the  
467 original outcrop.

468 To evaluate the repeatability of the optimised simulation, 6 realisations using the same  
469 parametrisation were generated for OPT1. The total amount of fracture generated for these  
470 simulation always fall below the 10% deviation compared to the reference outcrop.

471 The number of segments comprised between 0-20 m in OPT1 is slightly above the  
472 satisfactory deviation limit. As per all the generated simulations, the number of fractures  
473 between 2.21 m and 10 m is largely overestimated.

474 OPT1 contains a more satisfactory and acceptable fracture count than any other simulation  
475 generated before (table 6). The amount of segments generated in zone 1 and 2 for set 1 slightly  
476 overestimate the amount of segments. In zone 3, OPT1 fails to represent the amount of



477 fractures for set 1 (25% deviation) and for set 3. Fracture set1 in zone 4 is largely  
478 overestimated.

479

#### 480 **III.4.4 Using the sensitivity analysis results to model AP4**

481 As per AP3, AP4 present intrinsic fracture network geometry variability. This outcrop was  
482 divided in 3 elementary zones (fig. 10A-B). According to AP4 partitioning, a probability map  
483 with sharp boundaries (fig. 10B) was created. For AP4, the configuration of the outcrop led to  
484 mask the area where no interpretation data were performed. In these particular zones a “no  
485 data value” was attributed and these masked areas were excluded during the modelling  
486 process. In AP4 three training images were created (fig. 10C). As per AP3, the size of the  
487 AP4 simulation grid was doubled compared to its original dimension (available in fig.10). In  
488 AP4, fractures longer than 40 meters were also considered as hard conditioning data. Here,  
489 less than 1.5% of the fractures are longer than 40m (fig. 10D). In AP4, long fractures were  
490 found in the 3 sets and mainly in the south-eastern part of the outcrop (fig. 10D, elementary  
491 zone 6). 11 N000 fractures (0.5% of the whole), 13 N150 fractures (0.6% of the whole) and 9  
492 N090 fractures (0.4% of the whole) were digitized and integrated as conditioning data into the  
493 simulation.

494 Based on the results of the sensitivity analysis of AP3 we generated one simulation for the  
495 AP4 outcrop (fig. 11). The modelling parameters for SIM AP4-1 were selected as following:  
496 the number of neighbours was set up at 50 and the acceptance threshold at 2%. The 3 training  
497 images used in the simulation are presented in figure 11 and are considered as representative  
498 of the fracture arrangement in each region of simulation. The scanning percentage of TI6 and  
499 TI7 was set up at 50%. The scanning percentage of TI8 was set up at 100% because a lot of  
500 small segments need to be represented. With this configuration, the simulation lasts slightly  
501 more than 5 minutes. The fact of intensely scanning TI8 is probably responsible of this



502 duration. Analysis was conducted on the total amount of segments generated and of segments  
503 per set of fractures. In AP4 the total number of segments is 1810. The simulation realises  
504 1682 segments in total, which constitutes a satisfactory result. AP4 original presents 252  
505 segments striking N150 (set 1), 856 segments striking N000 (set 2) and 702 segments striking  
506 N090 (set 3). The results of Simulation AP4-1 are always satisfactory or acceptable with 206  
507 segments striking N150 (set 1), 834 segments striking N000 (set 2) and 642 segments striking  
508 N090 (set 3). A detailed analysis was not conducted here because AP4 contains a lot of small  
509 fracture intersections (especially in the TI8 zone) and this makes the segment extraction a  
510 complex process. However, these results are promising for the future.

511

## 512 **IV] Uncertainty analysis**

### 513 **IV.1 Smooth transitions between elementary zones: towards reservoir scale** 514 **models**

515 The strength of the method proposed here relies on the use of a probability maps and on the  
516 opportunity to consider multiple training images in a single realisation to generate non-  
517 stationary models of fracture network geometries. In the case of AP3 and AP4, the probability  
518 maps are essentially constrained by the variation of geometry of the fracture networks  
519 observed on the geological interpretation made on the drone imagery. Consequently, the  
520 defined areas are pragmatically bounded and the nature of the limit between one zone and  
521 another is a sharp boundary.

522 AP3 and AP4 outcrops are separated by about 2.5 km and very little is known about the  
523 fracture network geometry between these two locations. Assuming that there is no major  
524 structural deformation (fold or faults) that may cause a change in fracture geometry at the  
525 close vicinity of the outcrop “reality”, zones initially defined on the AP3 and AP4 outcrop can  
526 be extended to the limits of the reservoir-scale model boundaries (fig. 12). In this particular



527 case, filling the gap between the two outcrops appears to define how the transition between  
528 one side of the simulation grid and the other should be determined.

529 Fractures are localised objects that do not need to be necessarily continuous from one  
530 simulation zone to another. The constant higher proportion of the non-fractured matrix facies  
531 versus localised and thin fracture elements ensures the coherency and relative compatibility  
532 from one simulation region to another. The idea of the simulation grid region partitioning was  
533 re-evaluated and an alternative method, using probability of inverse distance proportion, was  
534 proposed here. Contrarily to the definition of sharp boundaries in the probability maps used  
535 for AP3 and AP4, as probability map with smooth transitions is defined as if each TI  
536 correspond to a partition of the area of interest, with for each TI one elementary zone,  
537 covering a part of simulation grid, the probabilities in the map are set to one for specific TI  
538 and to zero for the other ones. On each remaining zones, called transition zones, one has to  
539 define which TIs may be involved. On a transition zone, the probabilities of involved TI's are  
540 set proportional to the inverse distance to the elementary zones of the corresponding TI's.  
541 This process creates smooth transitions in low constrained area decreasing the influence of  
542 one TI towards another (from one elementary zone to another).

543 No faults or folds can be initially identified between AP3 and AP4 to condition the drawing of  
544 the probability map. In this first case, a rectangular compartment representing a gradual  
545 probability transition to use the training image associated to one outcrop or to the other filled  
546 the blank space between the two outcrops. For instance, fig 12E shows in the  
547 Transition\_Zone\_1 a decreasing probability to use TI1 from left to right (i.e. zone 1 to zone 6)  
548 and conversely to use TI6 from right to left.

549 Recently, investigations conducted on the Rio Grande do Norte geological map (Angelim et  
550 al., 2006), demonstrated the presence of a fault crossing the simulation grid near the AP3  
551 zone. This structure may explain the variability of fracture geometry from AP3 (EW stylolites



552 and strong presence of conjugated NS/NW-SE system) to AP4 (EW stylolites associated to  
553 NS fracture) system, the NW-SE conjugated system is here subordinate). Further geological  
554 investigations need to be conducted in this particular place to proof the influence of this fault  
555 on the network geometry. However, fig 12F, shows an alternative probability map taking into  
556 account this interpretation and present how flexible the probability map can be. The proposed  
557 method demonstrates its adaptability in various geological contexts.

558

#### 559 **IV.2 Evaluation of the accuracy of the simulation using mechanical** 560 **modelling**

561 Uncertainty analysis is required while performing simulations of geological parameters,  
562 especially far from input data. The sensitivity analysis presented in this paper is a way to  
563 appreciate how good the result provided by the MPS simulation is compared to the reference.  
564 However, this test has little meaning when the reference is unknown (e.g. subsurface).

565 In this case the evaluation of fracture network permeability (i.e. which of the considered  
566 fractures are open and are potentially capable to conduct fluid from one point to another) can  
567 be tested dynamically and appears to be a good way to validate the provided simulation. This  
568 approach can also be extended to fluid flow simulations through the permeable fractures. We  
569 calculated mechanical and hydraulic apertures using a Barton-Bandis stress induced aperture  
570 model (Barton, 1982; Barton and Bandis, 1980) on the original AP3 interpreted outcrop and  
571 on four selected MPS realisations.

572 Flow in naturally fractured reservoirs is driven by the occurrence of open fractures. The  
573 contribution of fractures to fluid flow at in-situ stress conditions in reservoir models can be  
574 defined by the Mohr-Coulomb critical stress method (Hoek and Martin, 2014; Rogers, 2003).  
575 If shear stress acting on a fracture exceeds normal stress it becomes critically stressed and  
576 forms a conduit to flow. The fracture aperture is a key parameters to know for reservoir



577 evaluation and production. The Barton-Bandis empirical model quantifies the aperture that  
578 remains when irregular mismatching fracture walls are partially closed under in-situ stress  
579 (Fig. 13). The theory and equations behind the use of the Barton-Bandis model are presented  
580 in the appendix A of this article.

581 We chose four MPS generated simulations and the original interpreted fracture dataset for the  
582 aperture calculations. We used ABAQUS (Dassault Systemes), a commercial finite element  
583 solver for the stress calculations. A conformal mesh consisting of triangular elements is  
584 generated around the fracture traces, which are represented as lower dimensional polyline  
585 seams within a 2D plane strain geometry. The number of elements used to mesh the  
586 geometries in AP3 original interpreted outcrop is 282020, in SIM1 is 277172, in SIM7 is  
587 272598, in SIM26 is 277778 and in OPT1 is 276702.

588 An anisotropic load is applied on the four edges of the model to replicate a scenario where the  
589 maximum horizontal stress is thrice the minimum horizontal stress in the displacement-  
590 loading step. The normal local stress and shear slip, which is heterogeneous, and variable  
591 across fracture trace length is hence calculated for the entire fracture system. Longer fractures  
592 and intersecting fractures have a larger tendency to slip. Also fractures, which are  
593 preferentially aligned to the maximum horizontal stress, would have a greater magnitude of  
594 local normal stress. The parameters used for the simulations are tabulated below:

$$\begin{array}{lll}
Sh_{\max} = 30MPa & \nu = 0.3 (-) & JRC = 15 (-) \\
Sh_{\min} = 10MPa & E = 35 GPa & JCS = 120MPa
\end{array}$$

596 The resulting aperture distributions can be seen in figure 14. A qualitative comparison of the 5  
597 different DFN's hydraulic aperture distributions demonstrated similar heterogeneities. There  
598 are areas within the network, which are open to flow, but also regions, which serve as flow  
599 bottlenecks and hence would have a lower permeability. The actual effective permeability of  
600 the fractured system under stress would however depend upon the balance between the matrix





601 permeability versus the heterogeneous fracture permeability. Our results indicate that the  
602 MPS generated fracture realizations preserve similar regions of open and closed apertures  
603 when compared with the deterministic outcrop derived network.

604

## 605 **V] A method to create 3D DFN out of 2D MPS realisations**

606 The MPS simulation outputs presented in this paper are on the form of 2D pixelated maps.  
607 MATLAB codes were developed to extract starting and end point coordinates (georeferenced)  
608 of a series of aligned colorized pixels that represent a fracture trace from these images.  
609 Transforming this output in geologically realistic 3D surfaces is not easy. (Karimpouli et al.,  
610 2017) studied samples coming from coalbed methane reservoirs in the fractured Late Permian  
611 Bowen Basin in Australia. They realised multiple 2D and pseudo 3D images (i.e. orthogonal  
612 2D images) and used the cross-correlation based simulation (CCSIM) to represent the internal  
613 organisation of coal cleats and the heterogeneity of the coal matrix in 3D. Their approach  
614 greatly improved the understanding of the internal complexity of coal samples and gives  
615 better results than classical DFN's based on averaged distributions. However, their method  
616 requires an important initial amount of information (i.e. CT scans slices used as training  
617 images) that is generally not available at a larger scale. The use of MPS in 3D seems  
618 particularly not suited for fracture network representation because: i) they require to associate  
619 fractures from 2D map view and from 2D section view (3D or pseudo-3D), ii) it appears  
620 difficult to consider isolated fractures in this type of approach and iii) in the subsurface  
621 fracture height and/or fracture length are generally unknown.

622 To tackle these problems, we choose to generate statistic fracture networks in 2D map  
623 environment only. In the presented approach, the 3D is obtained by extruding 3D fracture  
624 planes in fracture units (fig. 15). In this approach we consider that fractures are entirely bound  
625 to the units, which can appear as a limitation if isolated or aborted fractures occurs inside a



626 layer. However, we can consider variable levels of fracture units. Figure 15 presents an  
627 hypothetical scenario where red fractures are confined to a large fracture unit (FU1) cross-  
628 cutting smaller ones (FU4 containing also smaller red fractures but smaller. In such a  
629 representation, one 2D planar simulation is required at each top mechanical unit to generate a  
630 new set of fracture.

631 In real-world subsurface configurations, mechanical units can be extracted from well logs  
632 (resistivity, density, lithology; Laubach et al., 2009). In outcrop, the resort to vertical cliffs  
633 adjacent to 2D horizontal pavement is required to define fracture height. This method is  
634 already implemented in gOcad-SKUA software as a macro that extrudes planes of a single  
635 fracture family (i.e. all the red fractures in AP3) vertically into a bounded volume (Fig. 15).  
636 More developments are in process to generate oblique planes and to be able to extrude planes  
637 in portions of the fracture family.

638

## 639 **V] Conclusions**

640 In this paper a new method to predict the geometry of a natural fracture network using the  
641 multiple-point statistic algorithm is presented. The method allows to provide a realistic non-  
642 stationary fracture network arrangement in 2D based on the use of multiple, simplified, small  
643 training images capturing the natural fracture attributes in specific zones defined by a  
644 probability map. Probability maps are adaptable and follow geological rules of fracture type  
645 and arrangement distribution specific to various tectonic contexts (i.e. faulting, folding and  
646 poor deformation context/no fault, no folds). We developed methods to be able to consider  
647 transition zones into the probability maps (e.g. zones far from hard data) that allow simulating  
648 fracture network geometry at a larger scale (i.e. reservoir scale).

649 The realisation obtained from 2D MPS constitutes a statistical laboratory close enough to the  
650 reality to be tested in terms of fracture mechanical parameters and response to flow.



651 Comparison between mechanical aperture calculation, fluid flow simulations conducted on  
652 both “reality” fracture network interpretations performed on drone imagery and series of MPS  
653 realisations gives similar results.

654 The method proposed here is applicable to all rock types and to a wide range of tectonic  
655 contexts. Initially calibrated using outcrop data, the method is fully adaptable to the  
656 subsurface in order to better characterise fractures in water, heat or hydrocarbon reservoirs.  
657 The challenge there, remains on the definition of the different training images on which is  
658 simulation is based. Very few data are generally available in the subsurface and geological  
659 rules need to be found to define the geological characteristics of the fracture network  
660 (orthogonal or conjugate network) and the associated fracture attributes (length, height,  
661 spacing, density, topology).

662

## 663 **Acknowledgments**

664 The authors want to thank ENI S.P.A. for the financial support of this research. Silvia  
665 Mittempergher from the University of Milano Bicocca is acknowledged for providing the  
666 code extracting segments from pixelated images. We would like also to thank the entire  
667 SEFRAC group for their interest in developing this method and for their valuable geological  
668 advices. Acknowledgements are extended to Philippe Renard from the University of  
669 Neuchâtel, to Hadi Hajibeygi from TU Delft and to Wilfried Tsoblefack from Paradigm Geo  
670 for the constructive discussions we had together. Prof. Hilario Bezerra from the Universidade  
671 Federal do Rio Grande do Norte is acknowledged for providing datasets concerning Apodi  
672 area and for his advises on the local geology. We would like to thank Jan Kees Blom from the  
673 TU Delft for the improvement he provided to this manuscript.

674

## 675 **Appendix A**



676 In the Barton-Bandis stress aperture model, the hydraulic fracture aperture is a function of  
 677 local stresses, shear displacement, initial roughness of the fracture and mechanical properties  
 678 of the rock. A set of empirical functions for the mechanical aperture was defined by (Barton,  
 679 1982). (Olsson and Barton, 2001) defined the hydraulic aperture as a function of the  
 680 mechanical aperture. The initial mechanical aperture is given by the following relation from  
 681 which the mechanical aperture is a function of the Joint Roughness Coefficient (JRC), Joint  
 682 Compressive Strength (JCS) and uniaxial compressive strength (in MPa).

$$E_0 = \frac{JRC}{5} \left( 0.2 \frac{\sigma_c}{JCS} - 0.1 \right)$$

683  
 684 The JRC is a measure of the relative roughness of the rock fracture surface and is commonly  
 685 measured using a Barton comb. The JCS can be measured in the field using Schmidt hammer  
 686 rebound measurements. The joint compressive strength (in MPa) is a mechanical property of  
 687 the rock. For our simulations, we set  $JRC = 15$  and JCS equal to the uniaxial compressive  
 688 strength of 120 MPa, so that we obtain an initial unstressed mechanical aperture of 0.3 mm  
 689 which is independent of length or network geometry. This is valid for an un-weathered  
 690 fracture where the initial unstressed aperture is only a function of roughness. The mechanical  
 691 aperture is a function of the normal stress, initial stiffness and the maximum closure.

$$E_n = E_0 - \left( \frac{1}{v_m} + \frac{K_{ni}}{\sigma_n} \right)^{-1}$$

692  
 693 The initial stiffness (in MPa/mm) and maximum closure (in mm) are functions of the JRC,  
 694 JCS and the initial mechanical aperture.

$$K_{ni} = (-7.15) + 1.75JRC + 0.02 \left( \frac{JCS}{E_0} \right)$$

$$v_m = A + B(JRC) + C \left( \frac{JCS}{E_0} \right)^D$$



697 The values of the coefficients in the maximum closure equation, vary according to cycles of  
 698 loading. These coefficients have been given by Asadollahi et al., (2010) and we use the  
 699 corresponding values for the third cycle where  $A = -0.1032 \pm 0.0680$ ,  $B = -0.0074 \pm 0.0039$ ,  
 700  $C = 1.1350 \pm 0.3261$  and  $D = -0.2510 \pm 0.1029$ . The hydraulic aperture,  $e$  (in mm) is a  
 701 function of shear displacement, normal stress, peak shear displacement and mobilized fracture  
 702 roughness. The shear displacement is obtained numerically. The domain for which  $0.75 \leq u_s /$   
 703  $u_{peak} \leq 1$  is calculated using linear interpolation (Olsson and Barton, 2001).

$$e = \begin{cases} \text{for } \frac{u_s}{u_{peak}} \leq 0.75; \frac{E_a^2}{JRC^{2.5}} \\ \text{for } \frac{u_s}{u_{peak}} \geq 1; \sqrt{E_a} JRC_{mob} \end{cases}$$

704

705 The peak displacement and mobilized JRC is obtained using the following relations.

$$u_{peak} = 0.0077L^{0.45} \left( \frac{\sigma_n}{JCS} \right)^{0.34} \cos \left( JRC \log_{10} \left[ \frac{JCS}{\sigma_n} \right] \right)$$

706

$$JRC_{mob} = JRC \left[ \frac{u_s}{u_{peak}} \right]^{-0.381}$$

707 The peak displacement is a function of JRC, JCS, normal stress and the block size,  $L$  (in  
 708 metres). Within a fracture network, the block size is the spacing of the fracture set intersecting  
 709 the fracture of interest (Barton, 1982). The mobilized JRC indicates the shear activated  
 710 fracture wall roughness and is dependent upon the ratio between shear displacement and peak  
 711 shear displacement.

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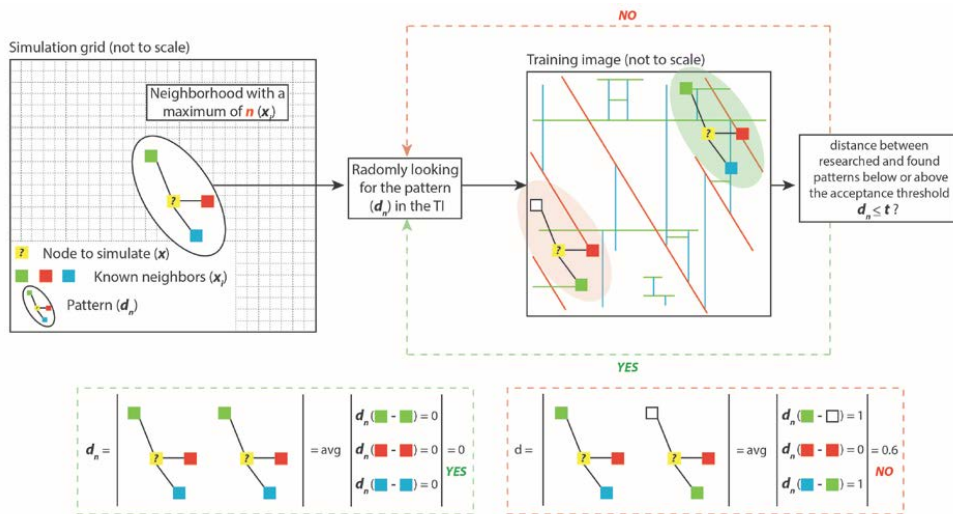
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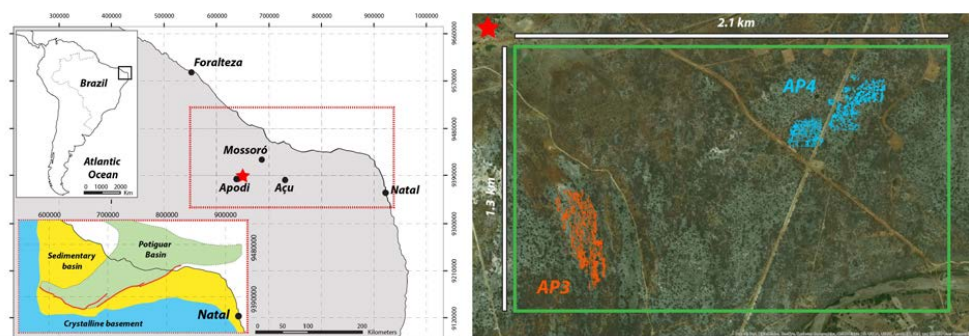


717 **Figure captions**

718 **Figure 1:** Direct Sampling method workflow applied to fracture network modelling (modified  
 719 from (modified from (Meerschman et al., 2013)).



720  
 721 **Figure 2:** Location of the area of interest and of the studied pavements near Apodi area (red  
 722 star).





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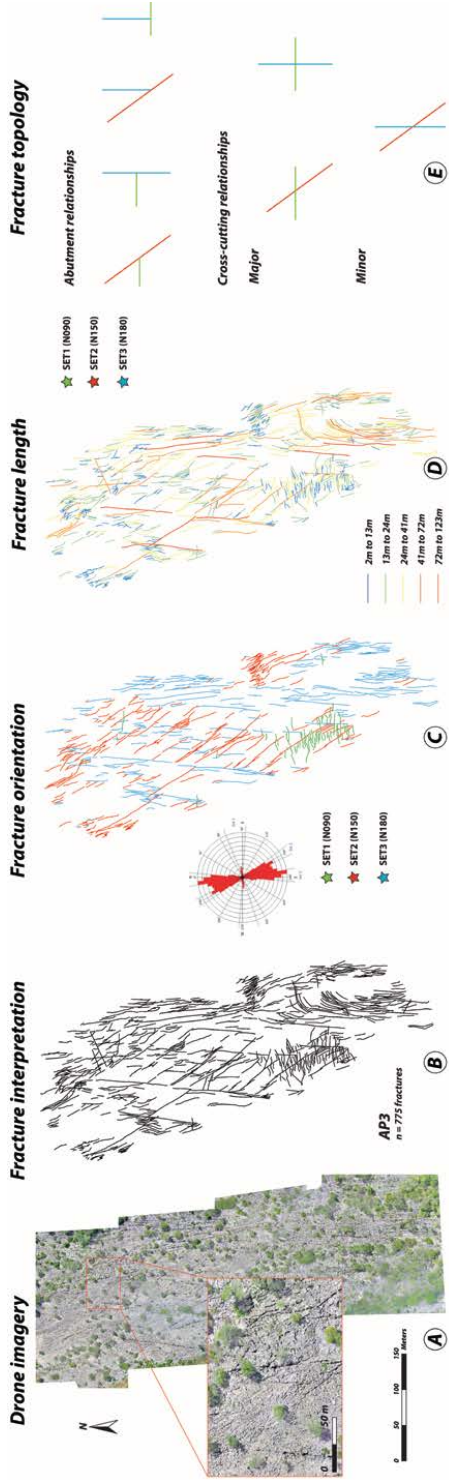
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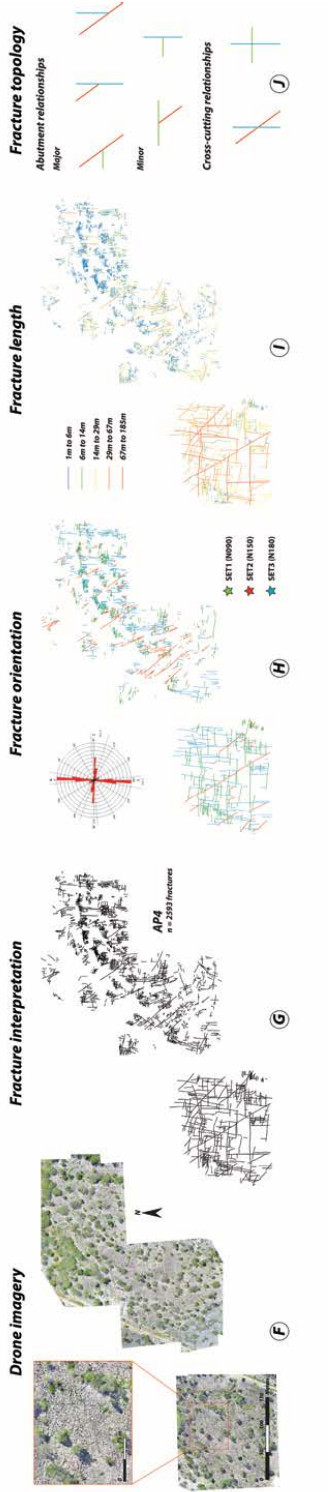
**Figure 3:** data acquired in the area of interest in pavements AP3. A) ortho-rectified high-resolution pavement aerial images acquired with a drone, B) fracture interpretation on ortho-rectified images, C) fracture orientation calculated from the north in GIS-based environment. Corresponding rose diagram for both outcrops, D) length of each fracture trace and E) fracture topology relationship for each pavement observed on fracture network interpretation.





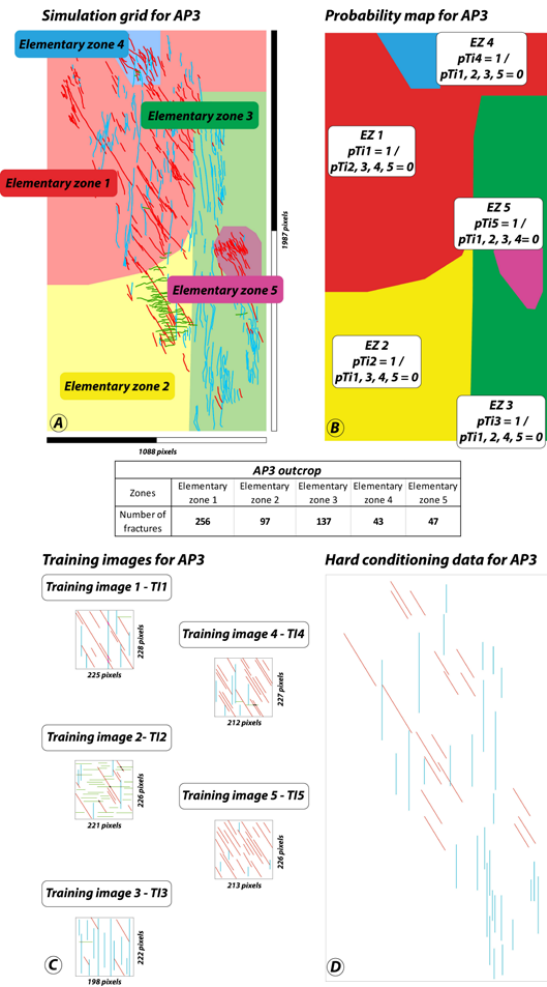


**Figure 4:** data acquired in the area of interest in pavements AP4. F) ortho-rectified high-resolution pavement aerial images acquired with a drone, G) fracture interpretation on ortho-rectified images, H) fracture orientation calculated from the north in GIS-based environment. Corresponding rose diagram for both outcrops, I) length of each fracture trace and J) fracture topology relationship for each pavement observed on fracture network interpretation





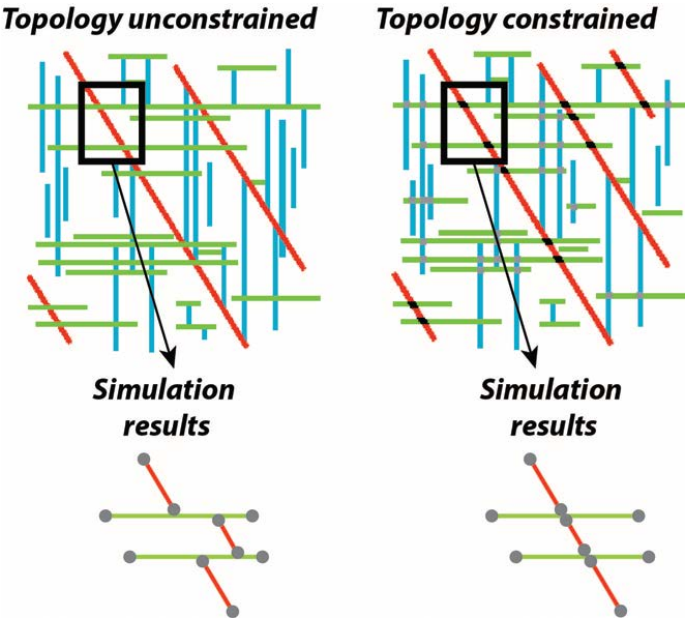
760 **Figure 5:** A) Partitioning of AP3 in 5 elementary zones (EZ). This partition is defined (with  
 761 respect to fracture orientation (fracture facies), fracture density and geometry variability over  
 762 the entire simulation domain. B) probability map and associated statistics for each EZ. C)  
 763 training images associated with the partition of AP3. In each EZ, the corresponding training  
 764 image has a probability (pTI) of 1 to be used. In this zone the other training images are not  
 765 used (pTI = 0). D) hard conditioning data for AP3. All the fractures longer than 40 m are  
 766 considered deterministically in the simulation process



767

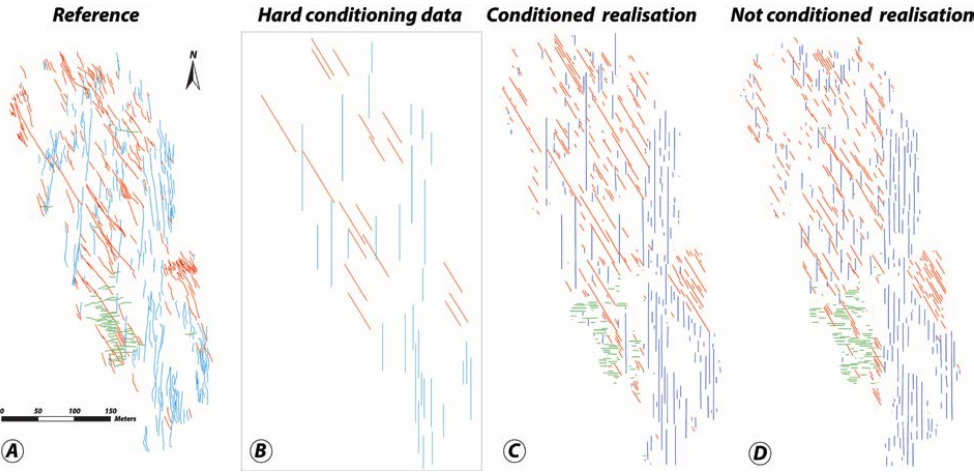


768 **Figure 6:** comparison between results obtained without constraining the topology and with  
769 topological facies constraints.



770  
771

772 **Figure 7:** visual comparison between: A) the reference fracture network interpretation (AP3),  
773 B) the extraction of the longer segments (50 fracture longer than 40m), C) a simulation  
774 conditioned by the long segments, D) a simulation not conditioned by the long segments



775

**Table 2:** simulation parametrisation, models set-ups and duration of each run.

Tested parametrisation	Number of neighbours influence							Number of neighbours + Acceptance threshold							
Realisation name	SIM1	SIM2	SIM3	SIM4	SIM5	SIM6	SIM7	SIM8	SIM9	SIM10	SIM11	SIM12	SIM13	SIM14	SIM15
A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =
5% N. =	5% N. =	5% N. =	5% N. =	5% N. =	5% N. =	5% N. =	5% N. =	4% N. =	3% N. =	2% N. =	1% N. =	4% N. =	3% N. =	2% N. =	1% N. =
10 Scan=	20 Scan=	30 Scan=	40 Scan=	50 Scan=	75 Scan=	100 Scan=	40 Scan=	40 Scan=	40 Scan=	40 Scan=	40 Scan=	50 Scan=	50 Scan=	50 Scan=	50 Scan=
Simulation parameters	25%	25%	25%	25%	25%	25%	25%	25%	25%	25%	25%	25%	25%	25%	25%
Simulation duration	22"	19"	33"	36"	55"	101"	136"	52"	52"	90"	95"	56"	76"	76"	121"

Tested parametrisation	Number of neighbours + Acceptance threshold + % TI scan												Optimisation
Group	Group 1				Group 2				Group3				
Realisation name	SIM16	SIM17	SIM18	SIM19	SIM20	SIM21	SIM22	SIM23	SIM24	SIM25	SIM26	SIM27	OPT1
A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	A. th. =	
3% N. =	2% N. =	3% N. =	3% N. =	2% N. =	3% N. =	2% N. =	3% N. =	2% N. =	3% N. =	2% N. =	3% N. =	2% N. =	
40 Scan=	40 Scan=	50 Scan=	50 Scan=	50 Scan=	40 Scan=	50 Scan=	50 Scan=	50 Scan=	40 Scan=	40 Scan=	50 Scan=	50 Scan=	Custom
Simulation parameters	50%	50%	50%	50%	75%	75%	75%	75%	100%	100%	100%	100%	
Simulation duration	80"	148"	123"	124"	105"	196"	152"	154"	104"	203"	150"	149"	151"

**Table 3:** Comparison between the total amount of segments interpreted in the reference outcrop and in the different sets of simulations (tested parametrisation). Evaluation of the results in terms of satisfactory (green symbol), acceptable (orange symbol) or non-satisfactory (red symbol)

				Results evaluation		
	Reference outcrop	Tested Parametrisation	Number of tested configurations	✓	≈	✗
Total segments	562	Influence of the number of neighbours	n=7	1	1	5
		Number of neighbours + Acceptance threshold	n=8	3	2	3
		Number of neighbours + Acceptance threshold + % TI scan	n=12	5	6	1



794 **Table 4:** results of the sensitivity analysis on the influence of the number of neighbours. The  
795 table presents the number of segments per simulation zone for AP3 (used as reference). Red  
796 symbols show a total amount of segments of the considered set in the considered zone  
797 deviating to more than 20% from the reference case. Yellow symbols show a deviation of  
798 more than 10% from the reference case. Green symbols do not deviate significantly from the  
799 reference outcrop interpretation.

			Number of neighbours						
Reference			SIM1	SIM2	SIM3	SIM4	SIM5	SIM6	SIM7
Segments per parts									
Zone TI1	Set1	156	✗	≈	≈	✗	✗	✗	✗
	Set2	95	✗	✗	≈	✗	✗	✗	✗
	Set3	6	✗	✗	✗	✗	✗	✗	✗
Zone TI2	Set1	22	✗	✗	✗	✗	✗	✗	≈
	Set2	12	✗	✗	✓	✗	✗	✗	✗
	Set3	57	✗	≈	✓	✓	✓	≈	✓
Zone TI3	Set1	20	✗	✓	✗	✗	✗	✗	✗
	Set2	113	✗	≈	✓	≈	≈	✗	✗
	Set3	2	✗	✗	✗	≈	≈	✗	✗
Zone TI4	Set1	25	✗	✗	✗	✓	✓	≈	✗
	Set2	10	✓	✓	✓	✓	≈	≈	≈
	Set3	3	✗	✗	✗	✗	✗	✗	≈
Zone TI5	Set1	39	✓	≈	✗	✗	✗	✗	✗
	Set2	2	✗	✗	✗	✗	✓	✓	≈
	Set3	0	✓	✓	✓	✓	✓	✓	✓
Satisfactory total			No	Yes	Yes	No	No	No	No
# satisfactory			3	3	5	4	4	2	4
# acceptable			0	4	2	2	3	3	2
# not acceptable			12	8	8	9	8	10	9



808 **Table 5:** results of the sensitivity analysis on the influence of the number of neighbours and  
 809 of the variation of the acceptance threshold. The colour code is the same as the one used in  
 810 table 4.

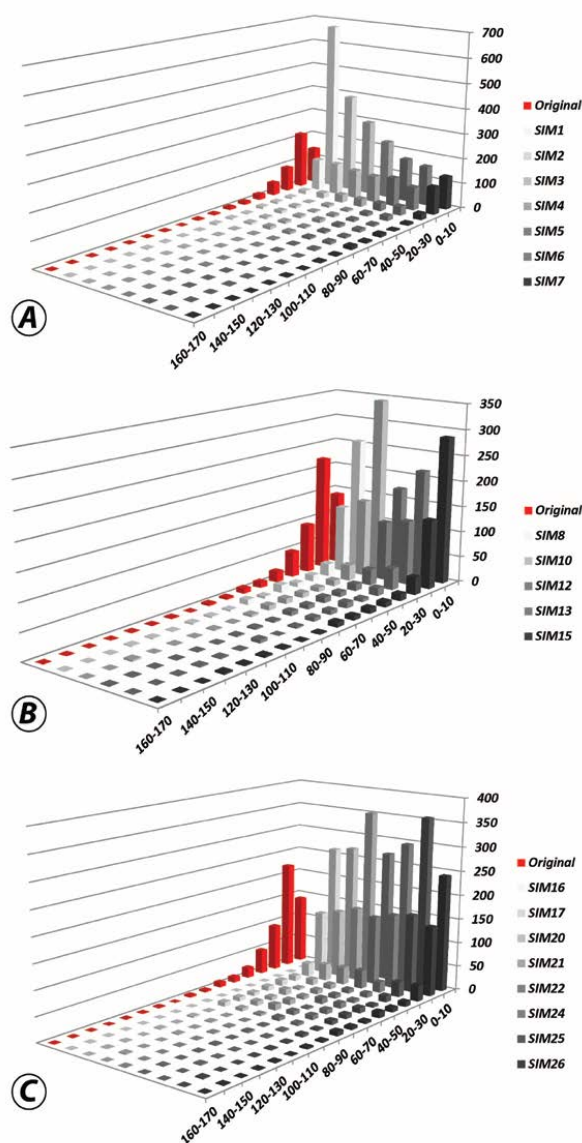
			Number of neighbours + Acceptance threshold								
			SIM8	SIM9	SIM10	SIM11	SIM12	SIM13	SIM14	SIM15	
			Segments per parts								
Zone T11	Set1	156	✓	✓	≈	≈	✗	✓	✓	✓	
	Set2	95	✗	✗	✗	✗	✗	✗	✗	✗	
	Set3	6	✗	✗	✗	✗	✗	✗	✗	✗	
Zone T12	Set1	22	✗	✗	✗	✗	✗	✗	✗	✗	
	Set2	12	≈	≈	✓	✓	✗	✗	✗	✗	
	Set3	57	✓	✓	✗	✗	✓	✓	✓	≈	
Zone T13	Set1	20	✗	✗	✓	✓	✗	✗	✗	✗	
	Set2	113	✓	✓	≈	≈	≈	✓	✓	≈	
	Set3	2	≈	≈	✓	✓	≈	✗	✗	✓	
Zone T14	Set1	25	✓	✓	✗	✗	✓	✓	✓	✓	
	Set2	10	✗	✗	≈	≈	≈	≈	≈	✓	
	Set3	3	✗	✗	✗	✗	✗	✗	✗	✗	
Zone T15	Set1	39	✗	✗	✗	✗	✗	✗	✗	✗	
	Set2	2	≈	≈	≈	≈	✓	≈	≈	≈	
	Set3	0	✓	✓	✓	✓	✓	✓	✓	✓	
		Satisfactory total	Yes	Yes	Yes	Yes	No	No	No	Yes	
		# satisfactory	5	5	4	4	4	5	5	5	
		# acceptable	3	3	4	4	6	2	2	3	
		# not acceptable	7	7	7	7	9	8	8	7	

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 812 **Table 6:** results of the sensitivity analysis on the influence of the number of neighbours, of  
 813 the variation of the acceptance threshold and of the variation of the percentage of the scanned  
 814 fraction of the training image. The colour code is the same as the one used in table

				Number of neighbours + Acceptance threshold + % TI scan												Optimisation
				Group 1				Group 2				Group3				
		Reference		SIM16	SIM17	SIM18	SIM19	SIM20	SIM21	SIM22	SIM23	SIM24	SIM25	SIM26	SIM27	OPT1
Segments per parts																
Zone T11	Set1	156		✓	✓	✓	✓	✗	✓	✓	✓	✓	✗	✓	✓	✗
	Set2	95		✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✓
	Set3	6		✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✓
Zone T12	Set1	22		✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✗
	Set2	12		✗	✗	✗	✗	✗	✗	✗	✗	✓	✗	✓	✓	✓
	Set3	57		✓	✓	✓	✓	✗	✓	✓	✓	✓	✗	✓	✓	✗
Zone T13	Set1	20		✗	✗	✗	✓	✗	✗	✗	✗	✗	✗	✓	✓	✗
	Set2	113		✓	✓	✓	✗	✓	✓	✓	✓	✓	✗	✗	✗	✓
	Set3	2		✗	✗	✗	✗	✗	✓	✓	✓	✗	✗	✗	✗	✗
Zone T14	Set1	25		✗	✗	✗	✗	✗	✓	✓	✓	✗	✗	✗	✗	✗
	Set2	10		✓	✓	✓	✗	✓	✓	✓	✓	✗	✗	✗	✓	✓
	Set3	3		✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✗	✓
Zone T15	Set1	39		✗	✗	✗	✗	✗	✗	✗	✗	✓	✗	✗	✗	✗
	Set2	2		✗	✗	✗	✗	✗	✗	✓	✓	✗	✗	✗	✗	✓
	Set3	0		✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
		Satisfactory total		Yes	Yes	Yes	No	No	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
		# satisfactory		5	5	5	4	4	8	8	6	2	7	7	7	8
		# acceptable		3	3	3	3	2	0	0	3	7	2	2	2	2
		# not acceptable		7	7	7	8	9	7	7	6	6	6	6	6	5



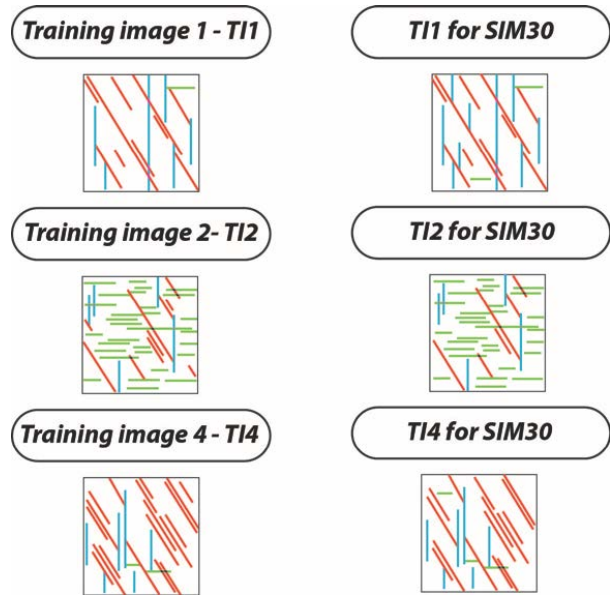
**Figure 8:** fracture length distributions tested during the sensitivity analysis. A) fracture length distribution for SIM1 to SIM7, B) fracture length distribution for SIM10, SIM12, SIM13, SIM15 and C) fracture length distribution for SIM16, SIM17, SIM20, SIM21, SIM22, SIM24, SIM5, SIM26.



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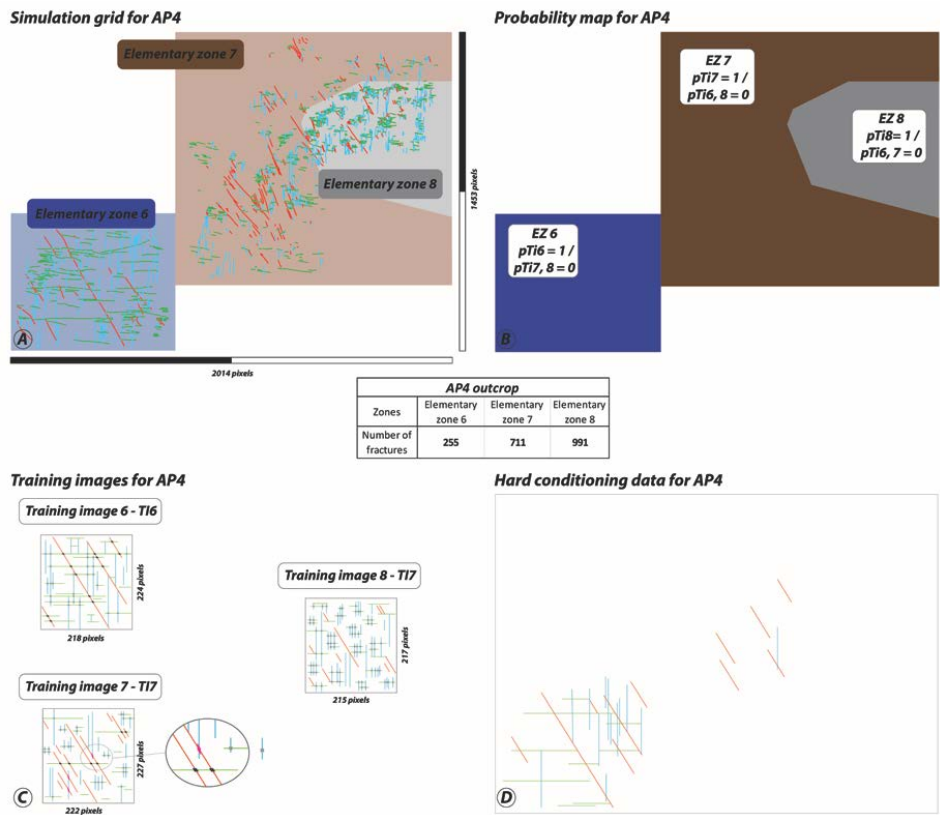
**Figure 9:** comparison of the training images 1, 3 and 4 used during the sensitivity analysis  
(27 simulations) and their modification for SIM 3





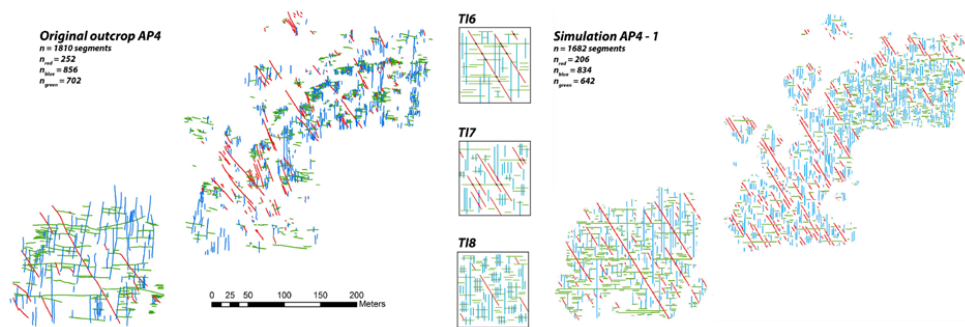


**Figure 10:** A) Partitioning of AP4 in 3 EZ. B) probability map and associated statistics for each EZ. C) training images associated with the partition of AP4. D) hard conditioning data for AP4





849 **Figure 11:** comparison of the AP4 original outcrop with a MPS simulated version AP4-1



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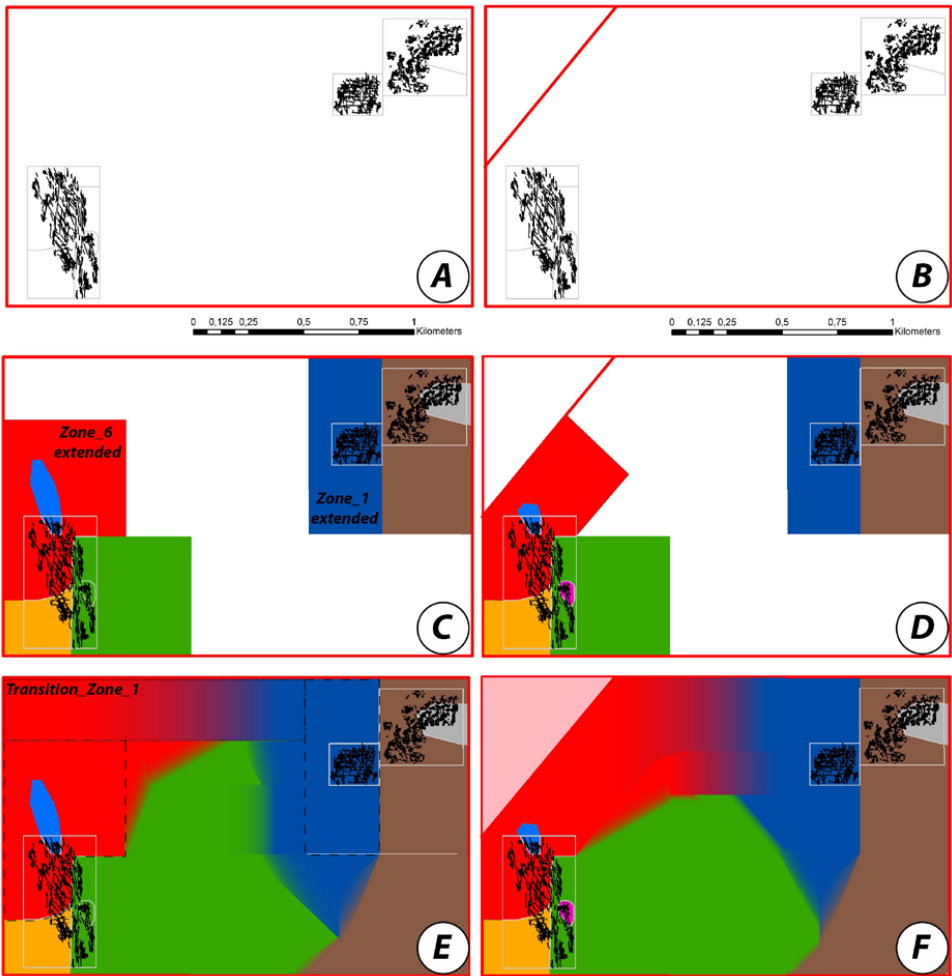
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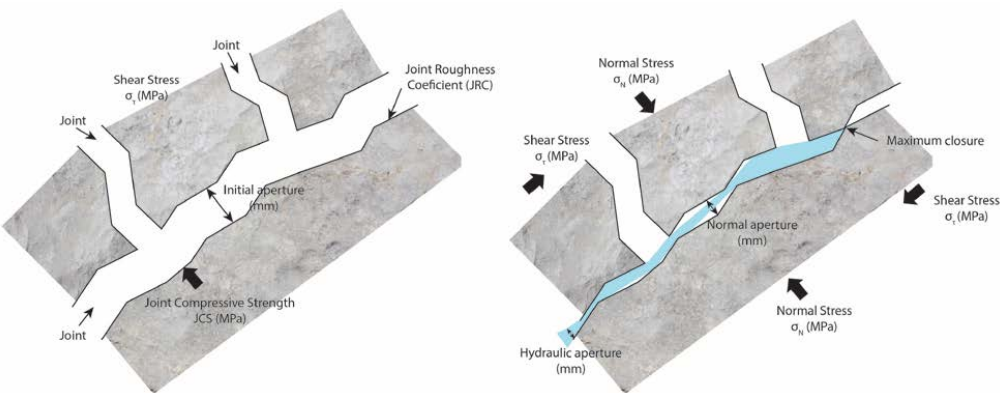
869 **Figure 12:** smooth probability map at the reservoir scale (combination of AP3 and AP4). A)  
 870 Relative position of AP3 and AP4 outcrops. B) Apodi fault added into the area of interest.  
 871 Extension of the probability map regions in AP3 and AP4 without geological drivers C) and  
 872 with the influence of the Apodi fault D). Probability maps with smooth transition zones  
 873 without geological drivers E) and with the influence of the Apodi fault F).



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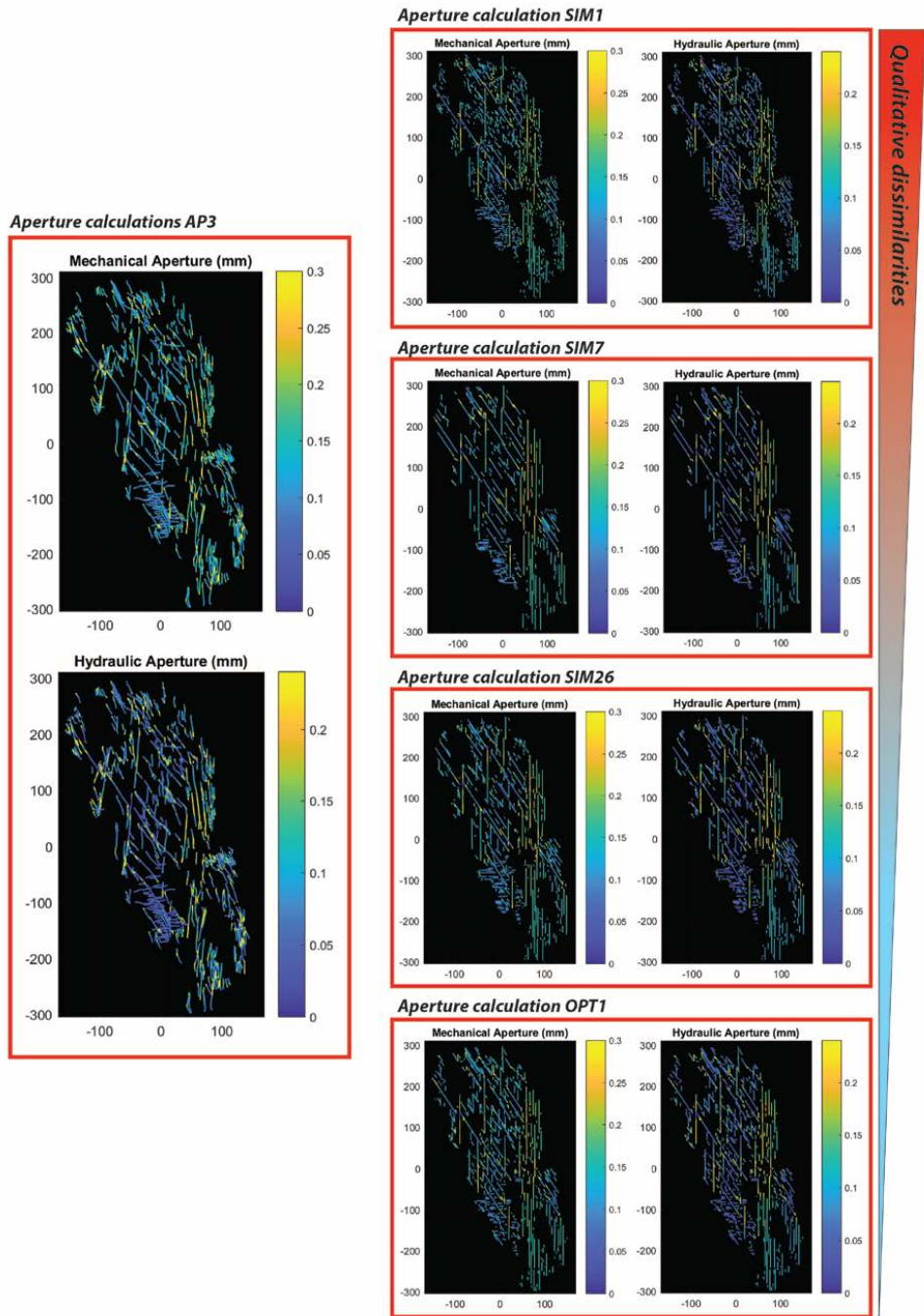


877 **Figure 13:** principle and parameters used in the calculation of stress-induced mechanical and  
878 hydraulic aperture using the Barton-Bandis approach (modified from (Bisdom, 2016)). The  
879 left hand-side sketch represents the initial stage where the fracture is not submitted to stress  
880 (aperture is constant). The right hand side sketch represents the same configuration submitted  
881 to stress (aperture is not constant).



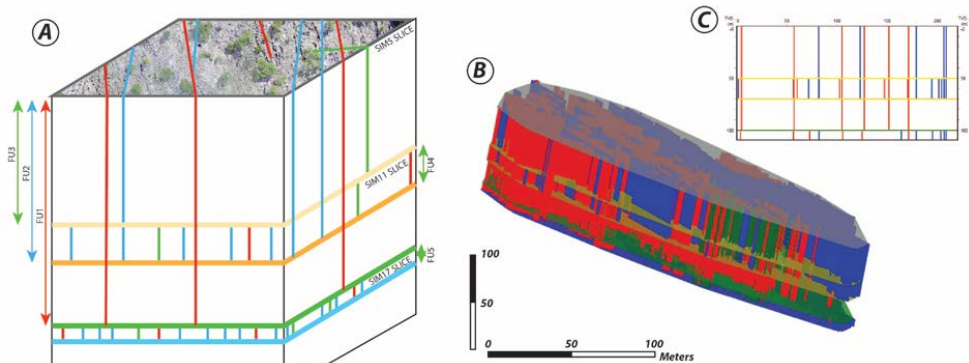


896 **Figure 14:** Mechanical and hydraulic aperture calculated in the original outcrop (AP3) and in  
 897 four selected MPS simulations





899 **Figure 15:** fracture network extrusion in 3D. The method consists of identifying the different  
900 fracture units (FU) on which the fracture height is supposed to be constant (A). This method  
901 requires one simulation per top fracture unit (SIM SLICES). (B) is a 3D DFN based on the  
902 hypothetical case (A) and realised in gOcad software. (C) is a cross section realised in the  
903 centre of the 3D model in the E-W direction.





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