## The Impact of Rheological Uncertainty on Dynamic Topography Predictions

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#### 9 Abstract

Much effort is being made to extract the dynamic components of the Earth's topography driven 10 11 by density heterogeneities in the mantle. Seismically mapped density anomalies have been used as an input into mantle convection models to predict the present-day mantle flow and stresses 12 applied on the Earth's surface, resulting in dynamic topography. However, mantle convection 13 14 models give dynamic topography amplitudes generally larger by a factor of  $\sim 2$ , depending on 15 the flow wavelength, compared to dynamic topography amplitudes obtained by removing the isostatically compensated topography from the Earth's topography. In this paper, we use 3D 16 17 numerical experiments to evaluate the extent to which the dynamic topography depends on mantle rheology. We calculate the amplitude of instantaneous dynamic topography induced by 18 the motion of a small spherical density anomaly (~100 km radius) embedded into the mantle. 19 20 Our experiments show that, at relatively short wavelengths (<1,000 km), the amplitude of 21 dynamic topography, in the case of non-Newtonian mantle rheology, is reduced by a factor of  $\sim$ 2 compared to isoviscous rheology. This is explained by the formation of a low viscosity 22 23 channel beneath the lithosphere and a decrease in thickness of the mechanical lithosphere due 24 to induced local reduction in viscosity. The latter is often neglected in global mantle convection 25 models. Although our results are strictly valid for flow wavelengths less than 1,000 km, we

note that in non-Newtonian rheology all wavelengths are coupled, and the dynamic topographyat long wavelengths will be influenced.

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#### 29 **1. Introduction**

30 The Earth's mantle is continuously stirred by hot upwellings from the core-mantle boundary, and by subduction of colder plates from the surface into the deep mantle (Pekeris, 31 1935; Isacks et al., 1968; Molnar and Tapponnier, 1975; Stern, 2002). This introduces 32 33 temperature and density anomalies that stimulate mantle flow and forces dynamic uplift or 34 subsidence at the plates' surface (Gurnis et al., 2000; Braun, 2010; Moucha and Forte, 2011; Flament et al., 2013). Dynamic topography can affect the entire planet's surface with varying 35 36 magnitudes. Because it is typically a low-amplitude and long-wavelength transient signal, it is 37 often dwarfed by isostatic topography associated with variations in the thickness and density 38 of sediments, crust and mantle lithosphere.

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40 For the present day, the observational constraints on dynamic topography come from residual 41 topography measurements (Hoggard et al., 2016). Residual topography is calculated by 42 removing the isostatically compensated topography from the Earth's topography (Crough, 1983; Cazenave et al., 1989; Davies and Pribac, 1993; Steinberger, 2007, 2016). Hoggard et 43 44 al. (2016)'s comprehensive work revealed that residual topography varies between  $\pm 500$  m at very long-wavelengths (i.e.  $\sim 10,000$  km) and can increase up to  $\pm 1,000$  m at shorter 45 wavelengths (i.e. ~1,000 km). However, these residuals depend on our knowledge of the 46 47 thermal and mechanical structure of the lithosphere, and therefore may not be an accurate 48 estimation of the deeper mantle contribution to the Earth's topography. Another approach to constrain present day Earth's dynamic topography involves numerical modelling of present-49 day mantle flow using seismically mapped density anomalies as an input (Steinberger, 2007; 50

51 Moucha et al., 2008; Conrad and Husson, 2009). However, this method requires a detailed 52 knowledge of the viscosity structure in the Earth's interior (Parsons and Daly, 1983; Hager, 1984; Hager et al., 1985; Hager and Clayton, 1989), and translating seismic velocities to 53 54 physical properties (e.g. temperature) of the mantle introduces further uncertainties 55 (Cammarano et al., 2003). The problem is that dynamic topography predictions derived from 56 mantle convection models are generally larger by a factor of two (more significant at the very 57 large scales) than estimates from residual topography (Hoggard et al., 2016; Cowie and Kusznir, 2018; Davies et al., 2019; Steinberger et al., 2019). We hypothesise that this could be 58 59 related to an oversimplification of the mantle rheology. In this paper, we explore how, at 60 wavelengths less than <1,000 km, the magnitude of dynamic topography changes when we use a rheological model in which the viscosity depends on strain rate, temperature, pressure and 61 62 fluid content. We first summarize the well-established analytical solution for calculating 63 dynamic topography induced by a spherical density anomaly embedded into an isoviscous fluid (Morgan, 1965a; Molnar et al., 2015). Then, assuming isoviscous rheology, we illustrate that 64 65 the amplitude of dynamic topography depends on the viscosity structure of the Earth's interior as shown by Morgan (1965a) and Molnar et al. (2015). Finally, we use 3D coupled thermo-66 mechanical numerical experiments of the Stokes' flow to assess the dependence of dynamic 67 topography on nonlinear rheology using viscosity which depends on temperature, pressure, 68 69 strain rate and fluid content. We show that plausible non-linear rheologies can induce local 70 variations in viscosity and result in dynamic topography of lower amplitude compared to those 71 derived from models using isoviscous rheology.

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2. Dynamic topography driven by a rising sphere: Analytical and numerical
solutions

75 2.1 Analytical solution for one layer isoviscous fluid

We assume here a simple 2D model representing a very viscous spherical density anomaly embedded into a semi-infinite isoviscous fluid bounded by an upper free surface. Earliest analytical investigations revealed that, albeit counter-intuitive, the magnitude of the induced surface deflection due to the rising sphere is independent of the viscosity of the fluid. The dynamic topography is a function of the vertical total stress ( $\sigma_{zz}$ ) applied to the surface which is proportional to the size and depth of the density anomaly according to Equation 1 (Morgan, 1965a, 1965b).

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$$\sigma_{zz}(x,0) = [2g\delta\rho r^3] \frac{D^3}{(D^2 + x^2)^{5/2}}$$
 (1),

84 where *g* is the gravitational acceleration,  $\delta \rho$  is density difference between the anomaly and the 85 ambient material, *r* is radius of the sphere, and *D* is distance from the surface to the centre of 86 the anomaly (modified from Morgan 1965a, see Figure 1a). The dynamic topography *e* is given 87 by:

88 
$$e(x) = \frac{\sigma_{zz(x,0)}}{g \, \Delta \rho}$$
 at  $z = 0$  (2),

89 where  $\Delta \rho$  is the density difference between the mantle and air (or water assuming a sea-load 90 when e<0) (Morgan, 1965a; Houseman and Hegarty, 1987). In Figure 1a, we plot the dynamic 91 topography induced by a sphere of 1% density anomaly, whose centre is at 372 km depth (D=92 372 km) below the free surface. We calculate the vertical total stress and convert it to dynamic topography by using Equation 2 for different values of the radius of the sphere. The amplitude 93 94 of dynamic topography shows an accelerating increase by cubic dependence on the radius of 95 the spherical density anomaly (Fig. 1a, black solid line). For the same problem, Molnar et al., 96 (2015) provided a solution by considering a higher order term resulting in a slight difference 97 with Morgan (1965a)'s solution (see Appendix A3 in Molnar et al. (2015)) allowing to consider density anomalies of finite viscosity ( $\eta_{sphere}$ ) (Eq. 3): 98

99 
$$\sigma_{zz}(C,0) = \frac{-\delta\rho r^{3}D}{3f} \left[ \frac{3-2f}{C^{3}} + \frac{18(f-1)r^{2}}{C^{5}} + \frac{6fD^{2}}{C^{5}} - \frac{30(f-1)r^{2}D^{2}}{C^{7}} \right] (3),$$

where  $C = \sqrt{D^2 + x^2}$  and  $f = (\eta_1 + \frac{3\eta_{sphere}}{2})/(\eta_1 + \eta_{sphere})$ . One can find that f=1.5 if the 100 sphere is very viscous ( $\eta_{sphere} \gg \eta_1$ ), and f < 1.5 for any other case. In Figure 1a, we present 101 two more plots of dynamic topography where f = 1.5 for hard sphere and f = 1.25 for  $\eta_{sphere} =$ 102  $\eta_1$  by using Equation 2 and 3. Figure 1a shows that a rising deformable sphere creates higher 103 dynamic topography compared to a very viscous sphere. These show that the viscosity contrast 104 105 between the spherical anomaly and the surrounding material can affect the dynamic 106 topography. In the section that follows, we explore how dynamic topography varies when there 107 is layering in viscosity, such as presence of a strong lithosphere above the convective mantle.

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#### **2.2** The impact of layered viscosity structure on dynamic topography

110 A more generalized solution has been put forward to accommodate the presence of a 111 stronger upper layer representing a lithosphere with viscosity  $\eta_2$  above a weaker layer with viscosity  $\eta_1$  and with  $\eta_{1<}\eta_2$  representing the convective mantle (Fig. 1b). In this case, Morgan 112 113 (1965a) showed (Eq. 4) that the total normal stress induced by the density anomaly is dependent 114 on the mass anomaly per unit length ( $M_u$ , for point sources integrated along a continuous line), 115 the depth of the centre of the sphere (D), and marginally on the ratio of the viscosity of the convective mantle to the viscosity of the lithosphere ( $R = \eta_1/\eta_2$ ). The 2-layer problem is treated 116 117 in Fourier domain with the resulting total normal stress as below:

118 
$$\sigma_{zz}(x,0) = \int_0^\infty \sigma_n \cos nx \ dn \ (4),$$

119 where

120 
$$\sigma_n = \frac{M_u g e^{-n(D-d)}}{2\pi (RS_h + C_h)} \left\{ 1 + n(D-d) + nd \left[ \frac{1 - nD + n(D-d)(RC_h + S_h)/(RS_h + C_h)}{1 + nd(1 - R^2)/(RS_h + C_h)(RS_h + S_h)} \right] \right\}$$

and  $C_h = \cosh nd$ , and  $S_h = \sinh nd$  (*n* is the wave number) and *d* is the upper layer thickness (modified from Morgan 1965a). Following Morgan (1965a), Figure 1b illustrates the relative importance of *R* as well as the ratio of the thickness of the upper layer to the depth of the 124 anomaly (d/D). As long as the lithosphere is more viscous than the asthenosphere, the vertical total stress at the surface has a minor dependence on the viscosity of the lithosphere (see solid 125 126 lines with R=1 and R=0.01 in Fig. 1b). Figure 1b also shows that the magnitude of dynamic 127 topography increases as the density anomaly is brought closer to the surface (compare for R=1 the solid black line and the dashed black line). Moreover, its sensitivity on the relative viscosity 128 of the lithosphere also increases. Although an unrealistic proposition for the Earth, when the 129 130 lithosphere is less viscous than the asthenosphere, the normal stress is much reduced and is strongly dependent on the viscosity of the lithosphere (Fig. 1b). These demonstrate that 131 132 layering in viscosity can have a strong impact on the amplitude of dynamic topography (Sembroni et al., 2017). In the next section, we use the analytical solutions above to benchmark 133 a numerical model, which we will then extend to non-linear viscosity. 134

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#### **136 2.3 Numerical solutions**

For comparison with analytical solutions (Morgan, 1965a; Molnar et al., 2015), we 137 consider 3D numerical models involving 1, 2 and 3 isoviscous layers. These benchmark 138 experiments will be used as references for non-isoviscous models discussed in section 3. We 139 140 use the open-source code Underworld which solves the Stokes equation at insignificant Reynolds number (Moresi et al., 2003, 2007). The 3D computational grid represents a domain 141 142 3,840 km x 3,840 km x 576 km with a resolution of 6 km along the vertical z axis and 10 km along the x and y axes (Fig. 2). In all experiments, we include a 42 km thick continental crust 143 above the upper mantle. The density structure is sensitive to the geotherm via a coefficient of 144 145 thermal expansion and compressibility (see Table 1 for all parameters). The geotherm is 146 defined using a radiogenic heat production in the crust, a constant temperature of 20°C at the surface, and a constant temperature of 1,350°C at 150 km. We disregard the adiabatic heating 147 148 and the asthenosphere is kept at 1,350°C. We embed a positive spherical temperature anomaly 149 of +324°C at a depth of 372 km below the surface, which delivers a 1% volumetric density difference. The radius of the sphere is 96 km. In all experiments, we impose free slip velocity 150 boundary conditions at all walls, such as  $V_x$  and  $V_y$  are set to be free, but  $V_z = 0$  cm yr<sup>-1</sup> at the 151 top wall. Taking advantage of the symmetry of the experimental setup, we extract viscosity 152 and velocity fields along a 2D cross section passing through the centre of the thermal anomaly, 153 from which we derive the streamlines and vertical velocity profiles along the vertical axis at 154 155 the centre of the models. We calculate the instantaneous dynamic topography from the normal 156 stress computed at the surface.

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#### 158 2.3.1 Dynamic topography due to a rising sphere in an isoviscous fluid

In the first experiment (Fig. 3a Experiment 1), we assign the same depth-independent 159 viscosity of  $10^{21}$  Pa s to the crust, mantle and the density anomaly. The streamlines for 160 Experiment 1 (Fig. 3a) show formation of two convective cells at the sides of the sphere 161 covering the entire crust and mantle. The vertical velocity profile indicates that the thermal 162 anomaly rises with a peak velocity of  $\sim 2.4$  cm yr<sup>-1</sup>, which is faster than the 2.0 cm yr<sup>-1</sup> predicted 163 by the analytical solution (Fig. 4a). Experiment 1 predicts dynamic topography of 114 m (Fig. 164 4b) which is lower than 132 m predicted by Molnar et al. (2015)'s analytical solution. We have 165 verified that increasing the depth of our model from 576 km to 864 km increases the dynamic 166 topography from 114 m to 122 metres. Therefore, we attribute the misfit in amplitude of 167 dynamic topography to the finite space in our numerical experiments. Our numerical 168 169 experiment using isoviscous material delivers a result globally consistent with the analytical 170 solutions of Morgan (1965a) and Molnar et al. (2015).

# 172 2.3.2 Dynamic topography on a strong lithosphere above an isoviscous 173 asthenosphere

In Experiment 2, we assign to the lithosphere a constant viscosity 100 times larger  $(10^{23})$ 174 Pa s) than that of the asthenosphere ( $10^{21}$  Pa s, Fig. 3b) between z=150 km and base of the 175 model. The convective cells become narrower by the induced viscosity contrast (Fig. 3b). The 176 streamlines are deflected across the lithosphere-asthenosphere boundary due to the large 177 viscosity contrast (Fig. 3b), and there is a sharp variation in vertical velocity at the base of the 178 lithosphere (Fig. 4a, red solid line). The maximum vertical velocity  $\sim 2.1$  cm yr<sup>-1</sup> is attained 179 near the centre of the anomaly. When compared to Experiment 1, the dynamic topography (Fig. 180 4b, red solid line) shows a significant increase from ~114 m to ~174 m. This increase is 181 182 consistent with analytical estimations showing an increase in dynamic topography when viscosity increases toward the surface (Fig. 1b, R<1). In Experiment 2a (not shown here), we 183 184 tested a different ratio of thickness of the lithosphere to the depth of the anomaly (see d/D in Equation 4) by increasing the lithospheric thickness from 150 km to 200 km, while keeping all 185 parameters identical to those of Experiment 2. As predicted by Eq. 4, Exp. 2 predicted dynamic 186 187 topography of ~191 m, being the largest among all experiments (Fig. 4b, red dashed line). Overall, and perhaps counter-intuitively, the presence of a thick viscous lithosphere enhances 188 189 the dynamic topography. Interestingly, in analogue experiments where density anomaly is 190 allowed to rise and interact with the lithosphere, the amplitude of the dynamic topography is inversely correlated with the thickness of the lithosphere (e.g. Griffiths et al. 1989; Sembroni 191 et al. 2017). 192

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#### 194 **2.3.3** The impact of low viscosity channel on the dynamic topography

195 In Experiment 3 (Fig. 3c), we introduce a third 60 km thick low viscosity layer (i.e.  $10^{19}$  Pa s) beneath the base of the lithosphere. The existence of a low viscosity layer has been 196 discussed in several studies (e.g. Craig and McKenzie, 1986, Phipps Morgan et al. 1995, 197 198 Stixrude and Lithgow-Bertelloni, 2005, and Becker, 2017). In this experiment, in order to 199 prevent large viscosity contrast that can impede the numerical convergence, the viscosity of the lithosphere and that of the asthenosphere is set to  $10^{22}$  Pa s and  $10^{21}$  Pa s, respectively. 200 When compared to Experiment 1, streamlines indicate a further decrease in size of the 201 convective cells, and more importantly, a strong horizontal divergence of the streamlines 202 203 within the low viscosity layer (Fig. 3c). The vertical velocities are also enhanced in the asthenosphere reaching up to  $\sim 2.8$  cm yr<sup>-1</sup> slightly above the centre of the anomaly (Fig. 4a, 204 205 orange solid line). When compared to Experiment 1, we observe a strong reduction in dynamic 206 topography (Fig. 4b, orange solid line) from 114 m to 88 m. This is due to the damping effect 207 of the low viscosity channel that acts as a decoupling layer, which reduces the deviatoric stress through its ability to flow. 208

Until now, the viscosities were assumed to be constant. However, results from experimental
deformation on mantle rocks strongly suggest that the viscosity is highly nonlinear (Hirth and
Kohlstedt, 2003). In what follows, we explore the influence of more realistic viscosities on
dynamic topography.

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#### **3.** The impact of nonlinear viscosity on dynamic topography

#### 215 **3.1 Viscosity structure of the Earth's interior**

Earth's mantle is not isoviscous. Geological records of relative sea level changes related to postglacial rebound, geophysical observations of density anomalies inferred from seismic velocity variations in the mantle and satellite measurements of the longest wavelength

219 components of the Earth's geoid have been used to infer the radial viscosity profile of the 220 Earth's interior (Hager et al., 1985; Forte and Mitrovica, 1996; Mitrovica and Forte, 1997; Kaufmann and Lambeck, 2000). Henceforward, beneath the lithosphere, a variation in 221 222 viscosity up to two orders of magnitude has been proposed (e.g., Kaufmann and Lambeck, 2000). Investigations of the rheological properties of crustal and mantle rocks via rock 223 deformation experiments revealed a nonlinear dependence of viscosity on applied deviatoric 224 225 stress, pressure, temperature, grain size and the presence of fluids (Post and Griggs, 1973; Chopra and Paterson, 1984; Karato, 1992; Karato and Wu, 1993; Gleason and Tullis, 1995; 226 227 Ranalli, 1995; Hirth and Kohlstedt, 2003; Korenaga and Karato, 2008). These experiments lead to the following relationship: 228

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$$\eta_{eff}(\dot{\varepsilon}, P, T) = A^{\left(\frac{-1}{n}\right)} f_{H_2 O}^{\left(\frac{-r}{n}\right)} \dot{\varepsilon}^{\left(\frac{1}{n}-1\right)} e^{\left(\frac{Q+PV}{nRT}\right)} (5).$$

where  $\dot{\epsilon}$  and *A* stands for strain rate and pre-exponential factor; *r* and *n* are exponents for water fugacity ( $f_{H_2O}$ ) and deviatoric stress, respectively; *V* and *Q* are the volume and energy of activation.

233 In the case where mantle flow is driven by the temperature difference at the boundary of the convective layer or by internal heating, the dominant strain mechanism is diffusion creep 234 because low deviatoric stresses are expected in the weak convective mantle (Karato and Wu, 235 236 1993; Turcotte and Schubert, 2002). However, mantle flow in the vicinity of a moving density anomaly is likely driven by deviatoric stresses that exceed the threshold for dislocation creep. 237 238 In this case, nonlinear viscosities lead to strong local variation in viscosity. Are those local 239 variations in viscosity important for dynamic topography? To answer this question, we need 240 reasonable constraints on the rheological parameters controlling the viscosity of mantle rocks. However, the extrapolation from laboratory strain rates typically in the range of  $10^{-6}$  s<sup>-1</sup> to  $10^{-1}$ 241  $^{4}$  s<sup>-1</sup> to mantle conditions where strain rates are typically on the order of 10<sup>-13</sup> s<sup>-1</sup> results in 242 significant uncertainties on the activation volume, activation energy and stress exponent (Hirth 243

and Kohlstedt, 2003; Korenaga and Karato, 2008). In what follows, we explore how nonlinear
viscosity impacts the dynamic topography and address how the uncertainties on the activation
volume can affect dynamic topography.

In Experiments 4 and 5 (Fig. 5), the viscosity depends on temperature, pressure and strain rate as indicated by Equation 5, using published visco-plastic rheological parameters for the crust and mantle. Specifically, we use quartzite rheology for the crust (Ranalli, 1995), and test both dry and wet olivine rheologies for the mantle (Hirth and Kohlstedt, 2003). Other parameters are identical to those in Experiments 1-3. We give all the rheological and thermal parameters in Table 1. For a given olivine rheology (i.e. dry or wet) we vary the activation volume by using the minimum and maximum reported values (Hirth and Kohlstedt, 2003).

In the numerical models, the plastic (i.e. brittle) deformation is described via:

255 
$$\tau = \mu \sigma_n + C_0$$
 (6)

where  $\tau$  is the 2<sup>nd</sup> invariant of the deviatoric stress tensor, which varies with the coefficient of friction ( $\mu$ ), and depth via lithostatic pressure ( $\sigma_n$ ), as well as the cohesion ( $C_0$ ). Due to strain weakening, the cohesion and coefficient of friction decrease from  $C_0 = 10$  MPa and  $\mu_0 = 0.577$ to  $C_0 = 2$  MPa and  $\mu_1 = 0.017$  at which the maximum plastic strain ( $\epsilon_{max}$ ) is reached (i.e. 0.2, Table 1). The effective density ( $\rho$ ) of rocks is determined by the pressure and temperature using the following equation:

262  $\rho = \rho_0 [1 - \alpha (T - T_0)] [1 + \beta (P - P_0)] (7)$ 

where  $\rho_0$ ,  $T_0$ ,  $\alpha$ , and  $P_0$  signify the reference density and temperature, thermal expansion coefficient, and the compressibility respectively.

#### **3.2 Numerical results: the case of dry olivine**

In Experiments 4a and 4b, we consider dry dislocation creep for olivine (n > 1, p = 0, r)266 = 0). The reported activation volume for this rheology varies between  $6 \times 10^{-6}$  m<sup>3</sup> mol<sup>-1</sup> and 267 27x10<sup>-6</sup> m<sup>3</sup> mol<sup>-1</sup> (Hirth and Kohlstedt, 2003). In Experiment 4a (Fig. 4b), we test the lower 268 269 value. The streamlines show similar pattern with Experiment 2. Interestingly, the maximum vertical velocity peaks at 75 cm  $yr^{-1}$ , near the upper boundary of the sphere (Fig. 6a, black 270 271 dashed line). This is due to the formation of a low viscosity region above the rising sphere (Fig. 5a, Experiment 4a). This experiment gives a dynamic topography of ~149 m (Fig. 6b, black 272 dashed line). It confirms that a strong contrast in viscosity between the lithosphere and 273 274 asthenosphere enhances the dynamic topography signal. We note that the viscosity contrast is 275 attained by smoother transition between the lithosphere and asthenosphere (Fig. 7a, black dashed line). We infer the mechanical thickness of the lithosphere from the viscosity profiles 276 277 plotted in Figure 7a, along which the lithosphere-asthenosphere transition zone shows a rapid 278 decrease in viscosity (Conrad and Molnar, 1997). We observe that the effective mechanical thickness of the lithosphere is reduced to 140 km, compared to the thickness of the thermal 279 280 lithosphere (Fig. 7c).

When we increase the activation volume to  $27 \times 10^{-6} \text{ m}^3 \text{ mol}^{-1}$ , the convection cells grow 281 much larger and show continuity through the lithosphere (Fig. 5a, Experiment 4b). The sphere 282 has a very low rising speed of  $\sim 0.25$  cm yr<sup>-1</sup> (Fig. 6a, black solid line). Compared to Experiment 283 4a, the dynamic topography shows a strong decrease from  $\sim 149$  m to  $\sim 105$  m (Fig. 6b, black 284 285 solid line). This is an example where the system behaves nearly as a single layer with 286 homogenous viscosity. The near absence of viscosity contrast between the lithosphere and asthenosphere explains the smaller magnitude of the dynamic topography. Moreover, the 287 288 formation of moderately low viscosity channel (Fig. 7a, black solid line) also contributes to the 289 decrease of the dynamic topography.

#### **3.3 Numerical results: the case of wet olivine**

In Experiments 5a and 5b, we consider dislocation creep of wet olivine. The reported 292 activation volume varies between  $11 \times 10^{-6}$  m<sup>3</sup> mol<sup>-1</sup> and  $33 \times 10^{-6}$  m<sup>3</sup> mol<sup>-1</sup> (Hirth and Kohlstedt, 293 294 2003). In Experiment 5a, we test the lower value. The streamlines show a pattern similar to Experiment 4a, but with slightly larger convective cells (Fig. 5b, Experiment 5a). The rising 295 velocity of the anomaly exceeds 140 cm yr<sup>-1</sup> (Fig. 6a, orange dashed line), promoted by the 296 297 low viscosity region sitting above the rising anomaly. The dynamic topography is ~110 m (Fig. 298 6b, orange dashed line). This is a bit surprising given the strong contrast in viscosity (3 orders 299 of magnitude) between the lithosphere and asthenosphere. However, Figure 7a shows that the 300 thickness of the mechanical lithosphere is reduced by about 30 km in comparison to Experiment 4a (e.g. 10 km reduction from thermal thickness) which resulted in lower dynamic 301 302 topography with similar viscosity contrast (Figure 7b,c).

In Experiment 5b, we increase the activation volume from  $11 \times 10^{-6}$  m<sup>3</sup> mol<sup>-1</sup> to  $33 \times 10^{-6}$ 303  $m^3 mol^{-1}$ . The vertical velocities show significant decrease from 140 cm yr<sup>-1</sup> to 0.34 cm yr<sup>-1</sup> 304 (Fig. 6a, orange solid line). This is due to an increase in viscosity above the rising sphere. 305 Compared to Experiment 5a, the dynamic topography decreases from ~110 m to ~90 m (Fig. 306 307 6b, orange solid line). Compared to Experiment 4b, we expect the dynamic topography to be higher due to slight increase in viscosity contrast (Fig. 7a,b). However, the increase in thickness 308 of the low viscosity channel (Fig. 7a,d) is more effective and thereby causes a greater reduction 309 310 in magnitude of the dynamic topography.

In summary, experiments using nonlinear rheology generally give lower amplitudes of dynamic topography compared to experiments using isoviscous rheology (Fig. 8). When we use dry olivine rheology for the upper mantle, the dynamic topography varies between ~105 m and ~149 m, whereas under wet conditions, the dynamic topography varies between ~90 m and ~110 m (Fig.8). These variations are due to uncertainties in the activation volume as well as
fluid content in olivine rheologies.

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- 318 4. Discussion and conclusion

319 Using coupled 3D thermo-mechanical numerical experiments, we have modelled the dynamic topography driven by a rising sphere of 1% density anomaly, having 96 km radius 320 321 and emplaced at 372 km depth. In line with analytical studies (Morgan, 1965a; Molnar et al., 322 2015), the experiments show that dynamic topography is sensitive to viscosity contrast between the lithosphere and asthenospheric mantle, and the thickness of the lithosphere (Fig. 7). Higher 323 viscosity contrasts amplify the dynamic topography (Fig. 7a,b), whereas formation of a low 324 325 viscosity channel just below the lithosphere has the opposite effect (Fig. 7a,d). The experiments 326 using nonlinear rheologies show local variations in viscosity, which contribute to the dynamic thinning of the mechanical lithosphere and causes reduction in dynamic topography. In 327 328 addition, models using high-activation volume creates a low viscosity channel above the 329 density anomaly, which contributes decreasing the dynamic topography. Using a larger viscosity range in the models  $(10^{18}Pa \cdot s \le \eta(P, T, \dot{\epsilon}) \le 10^{23}Pa \cdot s)$  resulted in ~5% 330 variation in the amplitude of dynamic topography, indicating that the effects of non-linear 331 rheology are reasonably captured in our models with smaller viscosity range  $(10^{19}Pa \cdot s \leq$ 332  $\eta(P,T,\dot{\varepsilon}) \leq 10^{22} Pa \cdot s).$ 333

Predictions of dynamic topography derived from mantle convection models are compared against residual topography which is the component of Earth's topography that is not compensated by isostasy (Flament et al., 2013; Hoggard et al., 2016). In a recent work (Cowie and Kusznir, 2018), it has been argued that dynamic topography predictions require scaling of amplitudes by ~0.75 to match the residual topography, and when density anomalies shallower than 220 km are included, the misfit requires a scaling factor of ~0.35. It is also 340 important to consider that this misfit depends on the flow wavelength and is suggested to be highest at lowest spherical harmonic degrees (2) or very long wavelengths (Steinberger, 2016). 341 342 Our numerical experiments show that amplitude of dynamic topography can be nearly halved 343 (e.g. from ~174 m in Exp. 2 to ~90 m in Exp. 5b) when we consider non-linear mantle rheology. Therefore, we propose that, at shorter wavelengths (i.e. less than 1,000 km), part of the misfit 344 between the dynamic topography extracted from mantle convection models and dynamic 345 346 topography estimated from residual topography can be attributed to the Newtonian mantle viscosity used in convection models. If the density sources are shallower, the dynamic 347 348 topography becomes more sensitive to the viscosity and density structure (Morgan, 1965a; 349 Hager and Clayton, 1989; Osei Tutu et al., 2018), and Newtonian viscosity may lead to higher misfits. 350

Our models suggest that for shallow density anomalies in the mantle, non-linear rheologies not only produce lateral variations in viscosity (Richards and Hager, 1989; Moucha et al., 2007), but also additional vertical variations in viscosity that impacts a relatively large area compared to the size of the anomaly in the mantle. We show that this impacts on the thickness of the mechanical lithosphere, and predictions of the amplitude of dynamic topography.

As shown in Figure 8, uncertainties on the activation volume result in variation in 357 dynamic topography which are higher in experiments using dry olivine rheology (i.e. 17%) 358 359 compared to experiments using wet olivine rheology (10%). The comparison between 360 numerical experiments using dry olivine (Exp. 4a) and wet olivine (Exp. 5b) indicates that the variation in dynamic topography can be as much as 25%. These variations can be lessened if 361 362 we have better constraints on the mantle rheology, which will advance the dynamic topography models as well as our understanding of the interaction between deep mantle and the Earth's 363 364 surface.

#### **366** Figures and Captions



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Figure 1. Dynamic topography driven by a spherical density anomaly of radius *r* at depth *D* embedded in a fluid whose viscosity structure is varied. (a) Variation in dynamic topography by radius of a spherical 1% density anomaly centred at 372 km depth in a single isoviscous fluid whose viscosity is  $\eta_1$ . The normal total stresses are calculated by Equation 1 taken from Morgan (1965a) (hard sphere), and Equation 3 taken from Molnar et al (2015) (hard and deforming spheres), and converted to dynamic topography by using

Equation 2. (b) The case where the fluid is no longer a single layer, but is composed of two layers with viscosities  $\eta_1$  and  $\eta_2$  for the lower and upper layers, respectively. We plot the dynamic topography for the same density anomaly in (a) using Equation 4, taken from Morgan (1965a), but with varying relative viscosities ( $R=\eta_1/\eta_2$ ). The ratio of upper layer thickness to depth to the centre of the anomaly (d/D) also affects the dynamic topography, and higher values correspond to shallow density anomalies or thicker lithosphere for constant depth (D).





Figure 2. 3D Numerical model of a spherical temperature anomaly having 96 km radius and a density of 1% less dense than the ambient mantle embedded in a depth of 372 km. The model space is 3,840 km long in *x* and *y* axes, and 576 km deep along the *z* axis. The dynamic topography is depicted as an exaggerated surface on the top of the model and is also reflected on the *x-z* plane.



Figure 3. Predicted peak amplitudes of dynamic topography for layered Earth models with isoviscous rheology. Centred at 372 km depth, the embedded spherical density anomaly (black circle) is 96 km in radius. It has a temperature anomaly of +324 °C giving 1% effective density difference with the background. The resulting streamlines are shown in a 2D cross section (*x-z* plane) along the centre of each numerical model (*y*=0 km).





Figure 4. (a) Vertical velocity profiles  $(V_y)$  along the centre, and (b) analytical solution and numerical modelling results showing dynamic topography induced by a sphere of temperature anomaly in the mantle (*r*=96 km,  $\delta \rho / \rho = 1\%$ ). The misfit between the numerical model for *R*=1 and the analytical solution is due to finite space in the numerical

400 model compared to semi-infinite space assumed in the analytical solution (Morgan401 1965a).



Figure 5. Viscosity map and streamlines for experiments using nonlinear rheologies (dry
or wet olivine) with various activation energies. The rising sphere is shown by black or
circles.



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Figure 6. (a) Vertical velocity profiles ( $V_y$ ) along the centre and (b) dynamic topography induced by a sphere of temperature anomaly (r=96 km,  $\delta \rho / \rho = 1\%$ ) in the mantle that has nonlinear rheology depending on temperature, pressure and strain rate.



Figure 7. Factors affecting the dynamic topography. (a) Vertical viscosity profiles at the
centre of the models. Variation in dynamic topography (b) by viscosity contrast between
the lithosphere and part of the asthenosphere above the anomaly, (c) by lithospheric
thickness (d) and by thickness of low viscosity channel.



Figure 8. Predicted dynamic topographies driven by a rising sphere centred at 372 km depth with 96 km radius and 1% less dense than the ambient mantle. The various experiments differ by rheology (isoviscous vs. nonlinear) and viscous structure. For Experiments 4 and 5, we show variation in dynamic topography due to contrasting activation energy. In general, experiments with nonlinear rheologies having up to 3 orders of magnitude variation in viscosity generally predict lesser magnitude of dynamic topography compared to experiments using isoviscous rheology. Compared to dry olivine, wet olivine rheology results in lower dynamic topography. 

Parameter	Symbol	EXP 4a-b,5a-b Crust <sup>1</sup>	EXP 4a,4b Mantle <sup>2</sup>	EXP 5a,5b Mantle <sup>2</sup>
Pre-exponential factor (MPa <sup>-n</sup> s <sup>-1</sup> )	A	6.7x10 <sup>-6</sup>	1.1x10 <sup>5</sup>	1600
Activation energy (kJ mol <sup>-1</sup> )	Q	156	530	520
Power-law exponent	п	2.4	3.5	3.5
Water fugacity	f	N.A.	N.A.	1000
Water fugacity exponent	r	N.A.	N.A.	1.2
Activation volume (m <sup>3</sup> mol <sup>-1</sup> )	V	0.0	6x10 <sup>-6</sup>	11x10 <sup>-6</sup>
			or 27x10 <sup>-6</sup>	or 33x10 <sup>-6</sup>
Reference density (kg m <sup>-3</sup> )	$ ho_0$	2,700	3,370	3,370
Reference temperature (K)	Т	293.15	293.15	293.15
Initial cohesion (MPa)	<i>C</i> <sub>0</sub>	10	10	10
Cohesion after weakening (MPa)	<i>C</i> <sub>1</sub>	2	2	2
Initial coefficient of friction	$\mu_0$	0.577	0.577	0.577
Coefficient of friction after weakening	$\mu_1$	0.017	0.017	0.017
Saturation strain	$\epsilon_{max}$	0.2	0.2	0.2
Thermal diffusivity (m <sup>2</sup> s <sup>-1</sup> )	κ	$1 \times 10^{-6}$	1 x 10 <sup>-6</sup>	1 x 10 <sup>-6</sup>
Thermal expansivity (K <sup>-1</sup> )	α	3x10 <sup>-5</sup>	3 x 10 <sup>-5</sup>	3 x 10 <sup>-5</sup>
Compressibility (MPa <sup>-1</sup> )	β	$4x10^{-5}$	0	0
Heat capacity (J K <sup>-1</sup> kg <sup>-1</sup> )	$C_P$	1,000	1,000	1,000
Radiogenic heat production (W m <sup>-3</sup> )	Н	0.5x10 <sup>-6</sup>	0.2 x 10 <sup>-7</sup>	0.2 x 10 <sup>-7</sup>

431 Table 1. Thermal and rheological parameters. We use the rheological parameters from

432 (1) quartzite (Ranalli, 1995), (2) dry or wet olivine (Hirth and Kohlstedt, 2003).

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- 434
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### 436 Author contribution

437 Ö.F.B designed the experiments and wrote the manuscript. P.F.R. contributed to the analysis

438 of numerical modelling results and improved the manuscript.

440	Comi	peting	inter	·ests

441 The authors declare that they have no conflict of interest.

442

#### 443 Code and data availability

- In our experiments, we used Underworld, a free open-source code developed under theAustralian Auscope initiative.
- 446 The version of *Underworld* code we used in our study can be found at:
- 447 <u>https://github.com/OlympusMonds/EarthByte\_Underworld</u>
- 448

449 To follow an open-source philosophy and promote reproducible science, our input scripts (a

450 suite of xml input scripts) will be available directly through the EarthByte's freely accessible

451 web server as well as author's GitHub repository.

452

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