



1 Crustal structure of southeast Australia from teleseismic 2 receiver functions

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10 **Abstract.** In an effort to improve our understanding of southeast Australia's enigmatic tectonic evolution, we
11 analyse teleseismic earthquakes recorded by 24 temporary and 8 permanent broadband stations using the
12 receiver function method. Crustal thickness, bulk seismic velocity and internal crustal structure of the southern
13 Tasmanides – an assemblage of Palaeozoic accretionary orogens that occupy eastern Australia – are constrained
14 by our new results which point to: (1) a 39.0 ± 0.5 km thick crust, a relatively high Poisson's ratio ($0.262 \pm$
15 0.014) and a broad (>10 km) crust-mantle transition beneath the Lachlan Fold Belt. This is interpreted to
16 represent magmatic underplating of mafic materials at the base of the crust; (2) a complex crustal structure
17 beneath VanDieland, a postulated Precambrian continental fragment embedded in the southernmost
18 Tasmanides, where the crust thickens (37.5 ± 1.2 km) towards the northern tip of the microcontinent as it enters
19 south central Victoria but thins south into Bass Strait (30.5 ± 2.1 km), before once again becoming thicker
20 beneath western Tasmania (33.5 ± 1.9 km). The thinner crust beneath Bass Strait can be attributed to
21 lithospheric stretching that resulted from the break-up of Antarctica and Australia and the opening of the
22 Tasman Sea; (3) stations located in the East Tasmania Terrane and eastern Bass Strait (ETT+EB) collectively
23 indicate crust of uniform thickness (~ 33 km) and a slightly broad Moho transition that reflect a possible
24 underplating event associated with a Palaeozoic subduction system. The relative uniformity of V_p/V_s and
25 Poisson's ratio in VanDieland – suggesting uniformity in composition – could be used in support of the
26 VanDieland microcontinental model that explains the tectonic evolution of southeast Australia.

27 **Keywords:** receiver functions, crustal structure, VanDieland, Bass Strait, SE Australia

28 1 Introduction

29 The Phanerozoic Tasmanides (Collins and Vernon, 1994; Coney, 1995; Coney et al., 1990) comprise the eastern
30 one-third of the Australian continent and through the process of subduction accretion were juxtaposed against
31 the eastern flank of the Precambrian shield region of Australia beginning in the Late Neoproterozoic and Early
32 Palaeozoic (Foster and Gray, 2000; Glen, 2005; Glen et al., 2009; Moresi et al., 2014) (Fig. 1). Persistent
33 sources of debate that impede a more complete understanding of the geology of the Tasmanides include (1) the
34 geological link between Tasmania – an island state in southeast Australia – and mainland Australia, which are
35 separated by the waters of Bass Strait; and (2) the presence and locations of continental fragments from
36 Rodinian remnants that are entrained within the accretionary orogens. Furthermore, the lateral boundaries
37 between individual tectonic blocks and their crustal structure are often not well defined. To date, few constraints



38 on crustal thickness and seismic velocity structure have been available for regions such as Bass Strait.
39 Constraints on the Moho transition, crustal thickness and velocity structure beneath Bass Strait derived from
40 receiver functions (RFs) can therefore provide fresh insight into the nature and evolution of the Tasmanides.

41 Previous estimates of crustal thickness and structure beneath southeastern Australia have been obtained from
42 deep seismic reflection transects, wide-angle seismic data, topography and gravity anomalies (e.g. Collins,
43 1991; Collins et al., 2003; Drummond et al., 2006; Kennett et al., 2011). Earlier RF studies in southeast
44 Australia (Shibutani et al., 1996; Clitheroe et al., 2000; Tkalčić et al., 2011; Fontaine et al., 2013a,b) suggested
45 the presence of complex lateral velocity variations in the mid-lower crust that probably reflect the interaction of
46 igneous underplating, associated thinning of the lithosphere, recent hotspot volcanism and uplift. Furthermore,
47 the intermediate to high crustal V_p/V_s ratio of 1.70–1.78 in this region (Fontaine et al., 2013a), relative to ark135
48 continental crust where V_p/V_s is ~ 1.68 , may indicate a mafic composition that includes mafic granulite rocks,
49 granite-gneiss and biotite gneiss. Body- and surface-wave tomography (Fishwick and Rawlinson, 2012;
50 Rawlinson et al., 2015) reveal P and S wave velocity anomalies in the uppermost mantle beneath Bass Strait and
51 the Lachlan Fold Belt. Ambient noise surface wave tomography (Bodin et al., 2012b; Young et al., 2012; Pilia
52 et al., 2015b, 2016; Crowder et al., 2019) of the southern Tasmanides reveals significant crustal complexity, but
53 is unable to constrain crustal thickness or the nature of the Moho transition.

54 The goal of this paper is to provide fresh insight into the crust and Moho structure beneath the southern
55 Tasmanides using *P*-wave RFs, explain the origin of the lateral heterogeneities that are observed and explore the
56 geological relationship between the different tectonic units that constitute the southern Tasmanides, thereby
57 facilitating a better grasp of the region's tectonic history.

58 **2 Geological setting**

59 The Palaeozoic-Mesozoic Tasmanides of eastern Australia form part of one of the most extensive accretionary
60 orogens in existence and evolved from interaction between the East Gondwana margin and the Proto-Pacific
61 Ocean. The tectonic evolution of the Tasmanides is complex and large-scale reconstructions have proven
62 difficult. This is evident from the variety of models that have been suggested to explain how the region formed
63 (Foster and Gray, 2000; Spaggiari et al., 2003; Teasdale et al., 2003; Spaggiari et al., 2004; Boger and Miller,
64 2004; Glen, 2005; Cawood, 2005; Glen et al., 2009; Cayley, 2011; Gibson et al., 2011; Moresi et al., 2014; Pilia
65 et al., 2015a,b). Particular challenges arise from multiple subduction events, multiple phases of metamorphism,
66 entrainment of exotic continental blocks, the formation of large oroclinal, recent intraplate volcanism and
67 subsequent events, including the separation of Antarctica and Australia and the formation of the Tasman Sea.
68 These challenges are compounded by the presence of widespread sedimentary sequences that hinder direct
69 access to basement rocks (Fig. 1).

70 The Tasmanides consist of four orogenic belts, namely the Delamerian, Lachlan, Thomson and New England
71 Orogens. The Delamerian Orogen - located in the south - is the oldest part of the Tasmanides and has a
72 southward extension across Bass Strait from Victoria into western Tasmania, where it is commonly referred to
73 as the Tyennan Orogen (Berry et al., 2008). Between about 514 and 490 Ma, the Precambrian and Early
74 Cambrian rocks that constitute the Delamerian Orogen were subjected to contractional orogenic event along the



75 margin of East Gondwana (Foden et al., 2006). Subsequently, the Lachlan Orogen formed in the east, which
76 contains rocks that vary in age from Ordovician to Carboniferous (Glen, 2005). Gray and Foster (2004) argued
77 for a tectonic model for the Lachlan Orogen that involved interaction of a volcanic arc, oceanic microplates,
78 several turbidite thrust systems and three distinct subduction zones. Each subduction zones is linked to the
79 formation of distinct tectonic terrain: the Stawell-Bendigo zone, Tabbarebbera zone and Narooma accretionary
80 complex. The limited rock exposure in the Tasmanides as a whole has made direct observation of the Lachlan
81 Orogen difficult; this is attributed to a large swath of Mesozoic-Cenozoic sedimentary cover and more recent
82 Quaternary volcanics which obscure a large portion of the underlying Palaeozoic terrane. However, the Lachlan
83 Orogen contain belts of Cambrian rocks in Victoria and New South Wales that are similar in age to the
84 Delamerian Orogen (Gray and Foster, 2004).

85 The presence of Precambrian outcrops in Tasmania and the relative lack of similar age rocks in adjacent
86 mainland Australia has led to different models which attempted to explain the existence of Proterozoic
87 Tasmania. For instance, Li et al. (1997) suggested that western Tasmania may be a remnant of a continental
88 fragment set adrift by Rodianian break-up, whereas Calvert and Walter (2000) proposed that King Island, along
89 with western Tasmania, rifted away from the Australian craton around ~600 Ma (Fig. 1). Other researchers have
90 developed scenarios in which the island of Tasmania was present as a separate microcontinental block that was
91 positioned outboard of the eastern margin of Gondwana before re-attaching at the commencement of the
92 Palaeozoic (Berry et al., 2008).

93 A popular model that attempts to reconcile the geology observed in Tasmania and adjacent mainland Australia
94 is that of Cayley (2011). This model proposes that central Victoria and western Tasmania formed a
95 microcontinental block called “VanDieland” that fused with East Gondwana at the end of the Cambrian,
96 possibly terminating the Delamerian Orogeny. VanDieland became entangled in the subduction-accretion
97 system that built the Palaeozoic orogens that now comprise eastern Australia (Fig. 1). Delineating Precambrian
98 continental fragments within southeast Australia has proven difficult partly due to more recent sedimentary
99 cover that obscures large tracts of the Tasmanides. However, if present, they likely have distinctive structural
100 and seismic velocity characteristics.

101 **3 Previous geophysical studies**

102 Imaging techniques previously employed to study crustal structure beneath the Tasmanides include: RF analysis
103 (e.g. Shibutani et al., 1996; Clitheroe et al., 2000; Chevrot and van der Hilst, 2000; Kennett et al., 2011;
104 Fontaine et al., 2013a,b), ambient noise tomography (e.g. Saygin and Kennett, 2010; Bodin et al., 2012b; Young
105 et al., 2013a,b; Pilia et al., 2015a,b; Crowder et al., 2019), studies based on potential field imaging and
106 numerical modelling (e.g. Gunn et al., 1997; Morse et al., 2009; Moresi et al., 2014; Moore et al., 2015, 2016),
107 teleseismic tomography (Rawlinson and Urvoy, 2006; Rawlinson and Kennett, 2008; Rawlinson et al., 2015,
108 2016; Bello et al., 2019b) and seismic reflection and refraction profiling (e.g. Finlayson et al., 1980; Collins,
109 1991; Direen et al., 2001; Glen et al., 2002; Finlayson et al., 2002; Drummond et al., 2006; Cayley et al., 2011;
110 Glen, 2013). The work of Clitheroe et al. (2000) used RFs to map broad-scale crustal thickness and Moho
111 character across the Australian continent. These findings confirmed the previous work of Drummond and
112 Collins (1986) and Collins (1991) who used seismic reflection and refraction transects to determine that the



113 Lachlan Fold Belt has the thickest crust (~50 km) in eastern Australia. Shibutani et al. (1996) applied a genetic
114 algorithm inversion, a non-linear global optimisation technique, to determine the lithospheric velocity structure
115 of southeast Australia from teleseismic RFs. They found that the Moho is shallow (30-36 km) and sharp within
116 the craton and deep (38-44 km) and transitional beneath the Tasmanides. They suggested that underplating or
117 intrusion of mantle material may have thickened the crust and produced a less distinct contrast across the Moho.
118 A more recent study by Fontaine et al. (2013a) employed $H\text{-}\kappa$ stacking and non-linear RF inversion to
119 investigate crustal thickness, shear wave velocity structure, as well as dipping and anisotropy of the crustal
120 layers. Their results also indicated a thick crust (~48 km) and an intermediate (2-9 km) crust-mantle transition
121 beneath the Lachlan Fold Belt zone which could be attributed to underplating beneath the crust and/or high
122 concentrations of mafic rocks in the mid-lower crust. Their results also showed a dipping Moho together with
123 crustal anisotropy in the vicinity of three seismic stations (YNG, CNB and CAN). In our new work, we have a
124 much increased data coverage of the study area (southern Tasmanides); this allows us to resolve new features,
125 and further investigate the presence of structures that have been suggested by previous studies.

126 Over the last decade, ambient noise tomography has become popular tool for studying the structure of the
127 Australian crust. Saygin and Kennett (2010) produced the first group velocity maps of the Australian continent
128 from Rayleigh wave group velocity dispersion in the period range 5.0–12.5 seconds. Limited spatial resolution
129 ($\sim 2^\circ \times 2^\circ$) in our study region means that this model is only able to represent the structure beneath Bass Strait
130 as a broad, low velocity anomaly. However, the group velocities exhibit a good correlation with known basins
131 and cratons. Subsequent studies using denser arrays covering southeast mainland Australia (Arroucau et al.,
132 2010) and northern Tasmania (Young et al., 2011) show good correlations between group/phase velocity maps
133 and sedimentary and basement terrane boundaries. In order to account for uneven data distribution, Bodin et al.
134 (2012b) used a Bayesian transdimensional inversion scheme to generate group velocity maps that span the
135 Australian continent from multi-scale ambient noise datasets. However, in our study area their model is of low
136 resolution due to the limited station coverage and hence few details on crustal structure can be inferred. Bodin et
137 al. (2012a) subsequently applied Bayesian statistics to reconstruct the Moho depth of Australia using a variety
138 of seismic datasets, which gave an approximate Moho depth of ~30 km beneath Bass Strait.

139 Potential field data have also been exploited to study the formation and structure of the Tasmanides. Gunn et al.
140 (1997) integrated potential field data (magnetic and gravity), seismic reflection data, outcrop geology and well
141 information to study the crustal structure of the Australian continent. Their study found that the occurrence of
142 tensional stress oriented NE-SW along basement structures in the Bass Basin is able to explain the formation of
143 the three major sedimentary basins that overlie dense mafic material, which in turn was formed by mantle
144 decompression processes associated with crustal stretching. From the interpretation of new aeromagnetic data,
145 Morse et al. (2009) delineated the architecture of the Bass Strait basins and their supporting basement structure.
146 Subsequent studies by Moore et al. (2015, 2016) used gravity, magnetic, seismic reflection and outcrop data to
147 support the hypothesis of a VanDieland microcontinent. Their study showed that VanDieland comprises seven
148 distinct microcontinental ribbon terranes that appear to have amalgamated by the Late Cambrian with major
149 faults and suture zones bonding these ribbon terranes together.

150 While the last few decades has seen important advances and insights made into our understanding of the



151 southern Tasmanides, there still remains limited data on the deep crustal structure beneath Bass Strait, which is
152 our region of interest. It is therefore timely that can exploit, using the RF technique, teleseismic data recorded
153 by a collection of temporary and permanent seismic stations in the region to study the structure of the crust,
154 Moho and uppermost mantle beneath mainland Australia, Bass Strait and Tasmania.

155 **4 Data**

156 A collaboration involving five organisations (University of Tasmania, Australian National University, Mineral
157 Resources Tasmania, the Geological Survey of Victoria and FROGTECH) deployed the temporary Bass seismic
158 array from May 2011 to April 2013. It consisted of 24 broadband, three-component seismic stations that
159 spanned northern Tasmania, a selection of islands in Bass Strait and southern Victoria. The instruments used
160 were 23 Güralp 40T and one Güralp 3ESP sensors coupled to Earth Data PR6-24 data loggers. The permanent
161 stations consist of eight broadband sensors managed by IRIS, GEOSCOPE and the Australian National Seismic
162 Network (ANSN). The distribution of all 32 seismic stations that are used in this study is plotted in Fig. 2.

163 Earthquakes with magnitudes $m_b > 5.5$ at epicentral distances between 30° and 90° comprise the seismic
164 sources used in this analysis (Fig. 3). This resulted in an acceptable azimuthal coverage of earthquakes between
165 the northwest and east of the array, where active convergence of the Australian and Eurasian plate coupled with
166 westward motion of the Pacific plate has produced extensive subduction zones. To the south and southwest of
167 the array, the absence of subduction zones in the required epicentral distance range means that there are
168 significantly fewer events available for analysis from these regions.

169 **5 Methods**

170 **5.1 Receiver functions**

171 The RF technique (Langston, 1979) uses earthquakes at teleseismic distances to enable estimation of Moho
172 depth and shear wave velocity structure in the neighbourhood of a seismic recorder. If this technique can be
173 applied to a network of stations with good spatial coverage, it represents an effective way of mapping lateral
174 variations in Moho depth and crustal structure. The coverage and quality of broadband data available for this
175 study provides a sound basis on which to examine the crustal structure of the southern Tasmanides.

176 A recorded teleseismic wavefield at a broadband station can be described by the convolutional model in which
177 operators that represent the source radiation pattern, path effects, crustal structure below the station and
178 instrument response are combined to describe the recorded waveform. By using deconvolution to remove the
179 effects of the source, path and response of the instrument (e.g. Langston, 1979), information on local crustal
180 structure beneath the station can be extracted from P - S -wave conversions at discontinuities in seismic
181 velocity (Owens et al., 1987; Ammon, 1991).

182 P -wave RFs were determined from teleseismic P -waveforms using FuncLab software (Eagar and Fouch, 2012;
183 Porritt and Miller, 2018), following preprocessing using the seismic analysis code (SAC) (Goldstein et al.,
184 2003). The complete set of 1765 events (Fig. 3) and 32 stations produced 21,671 preliminary RFs. These RFs
185 were manually picked using the FuncLab trace editor, and by using the clarity of the direct arrivals as an
186 acceptance criteria, a total of 9,674 RFs were retained for further analysis. The RFs were computed using an



187 iterative time-domain deconvolution scheme developed by Ligorria and Ammon, 1999 with a 2.5 s Gaussian
188 filter width. This is performed by deconvolution of the vertical component waveform from the radial and
189 transverse waveforms with a central frequency of 1 Hz. This frequency was selected on account of significant
190 source energy detected in the 1 Hz range of teleseismic P arrivals, which are sensitive to crustal-scale
191 anomalies. It also provides a favourable lateral sensitivity with respect to Fresnel zone width (~ 15 km at Moho
192 depth) when the conversions from P to S are mapped as velocity and crustal thickness variations.

193 5.2 H - κ stacking

194 Having obtained reliable P -wave RFs, the H - κ stacking technique is used to estimate crustal thickness,
195 Poisson's ratio and bulk V_p/V_s . We apply the method of Zhu and Kanamori (2000) to stations where the direct
196 P_S (Moho P -to- S conversion) and its multiples are observed. This technique makes use of a grid search to
197 determine the crustal thickness (H) and V_p/V_s (κ) values that correspond to the peak amplitude of the stacked
198 phases. A clear maximum requires a contribution from both the primary phase (P_S) and the associated multiples
199 (P_pP_S and $P_pS_S + P_SP_S$). In the absence of multiples, the maximum becomes smeared out due to the inherent
200 trade-off between crustal thickness (H) and average crustal velocity properties (κ) (Ammon et al., 1990; Zhu and
201 Kanamori, 2000). The H - κ stacking algorithm reduces the aforementioned ambiguity by summing RF
202 amplitudes for P_S and its multiples P_pP_S and $P_pS_S + P_SP_S$ at arrival times corresponding to a range of H and
203 V_p/V_s values. In the H - κ domain the equation for stacking amplitude

$$s(H, K) = \sum_{j=1}^N w_1 r_j(t_1) + w_2 r_j(t_2) - w_3 r_j(t_3) \quad (1)$$

204 where $r_j(t_i); i = 1, 2, 3$ are the RF amplitude values at the expected arrival times t_1, t_2 , and t_3 of the $P_S, P_pP_S,$
205 $P_pS_S + P_SP_S$ phases respectively for the j^{th} RF, w_1, w_2, w_3 are weights based on the signal to noise ratio
206 ($w_1 + w_2 + w_3 = 1$), and N is the total number of radial RFs for the station. $s(H, \kappa)$ achieves its maximum value
207 when all three phases stack constructively, thereby producing estimates for H and V_p/V_s beneath the station. In
208 this study, the weighting factors used are $w_1 = 0.6, w_2 = 0.3$ and $w_3 = 0.1$ (Zhu and Kanamori, 2000). The H - κ
209 approach requires an estimate of the mean crustal P -wave velocity, which is used as an initial value. Based on
210 the results of a previous seismic refraction study (Drummond and Collins, 1986), we use an average crustal
211 velocity of $V_p = 6.65$ km/s to obtain our estimates of H and κ in the study area, noting that H - κ stacking results
212 are much more dependent on V_p/V_s than V_p (Zhu and Kanamori, 2000). To estimate the uncertainties in the H - κ
213 stacking results, we compute the standard deviation of the H and κ values at each station.

214 H - κ stacking can also be used to determine Poisson's ratio, which is a useful parameter for inferring the physical
215 and compositional properties of the crust (Christensen, 1996) and providing insight into fractures, fluids, and
216 partial melt (e.g. Mavko, 1980). The Poisson's ratio σ can be determined from κ using the equation

$$\sigma = \frac{1}{2} \left(1 - \frac{1}{\kappa^2 - 1} \right) \quad (2)$$

217 where $\kappa = V_p/V_s$. While simple to implement, the Zhu and Kanamori (2000) method can suffer from large



218 uncertainties due to its assumption of a simple flat-laying layer over half-space with constant crustal and upper
219 mantle properties. Consequently, there are only two search parameters (H and κ) plus *a priori* information (V_p ,
220 weightings) and it does not account for variation with backazimuth. These problems can cause non-unique and
221 inaccurate estimates, which can lead to potentially misleading interpretations; for instance a low velocity upper
222 crustal layer can appear as a very shallow Moho in an H - κ stacking search space diagram. Also, a dipping Moho
223 and/or anisotropic layers within the crust can contribute to uncertainty.

224 5.3 Nonlinear waveform inversion

225 In an effort to refine the crustal model, we invert a stack of the radial RFs by adopting the workflow described
226 by Shibutani et al. (1996). We divide the waveform data (RFs) into four 90° quadrants based on the backazimuth
227 of their incoming energy. The 1st quadrant backazimuth range is from 0° and 90° , and an equivalent range in a
228 clockwise direction defines the consecutive quadrants. The 2nd and 3rd quadrants (south-eastern and south-
229 western backazimuths) have very small numbers of RFs. Data from the 1st and 4th quadrants are of better quality,
230 with the 1st quadrant showing more coherency than the 4th quadrant, which is likely due to the orientation of
231 surrounding tectonic plate boundaries and hence the pattern of P -wave energy radiated towards Australia.
232 Kennett and Furumura (2008) showed that seismic waves arriving in Australia from the northern azimuths
233 undergo multiple scattering but low intrinsic attenuation due to heterogeneity in the lower crust and mantle; this
234 tends to produce prolonged high-frequency coda. An important assumption in our inversion is that we neglect
235 anisotropy and possible Moho dip, which we assume have a second order influence on the waveforms we use to
236 constrain 1-D models of the crust and upper mantle.

237 Visual examination of coherency in P to S conversions allows us to select a subset of RF waveforms for
238 subsequent stacking. This resulted in groups of mutually coherent waveforms after which a moveout correction
239 is then applied to remove the kinematic effect of different earthquake distances prior to stacking using a cross-
240 correlation matrix approach described in Chen et al. (2010) and Tkalčić et al. (2011). Our strict criteria give
241 reliable RFs at only 6 out of the 32 stations used for this study. An example of some stacked RFs is given in Fig.
242 4.

243 5.3.1 Neighborhood algorithm

244 We invert RFs for 1-D seismic velocity structure beneath selected seismic stations using the Neighbourhood
245 Algorithm or NA (Sambridge, 1999a,b) in order to better understand the internal structure of the crust and the
246 nature of the transition to the upper mantle. NA makes use of Voronoi cells to help construct a searchable
247 parameter space, with the aim of preferentially sampling regions of low data misfit. In the inversion process, a
248 Thomson-Haskell matrix method (Thomson, 1950 and Haskell, 1953) was used to calculate a synthetic radial
249 RF for a given 1-D (layered) structure. During the inversion, as in Shibutani et al. (1996) and Clitheroe et al.
250 (2000), each model is described by six layers: a layer of sediment, a basement layer, an upper crust, middle crust
251 and lower crust, and an underlying mantle layer, all of which feature velocity gradients and potentially, velocity
252 jumps across boundaries. The inversion involves constraining 24 parameters: V_s values at the top and bottom of
253 each layer, layer thickness and the V_p/V_s ratio in each layer (Table 1). The inclusion of V_p/V_s ratio as an



254 unknown primarily aims to accommodate the effects of a sediment layer with limited prior constraints
255 (Bannister et al., 2003). There are two important controlling parameters required by NA: (1) the number of
256 models produced per iteration (n_s); and (2) the number of neighbourhoods re-sampled per iteration (n_r). After a
257 number of trials we chose the maximum number of iterations to be 5500, with $n_s = 13$ and $n_r = 13$ for all
258 iterations. We employ a chi-squared (χ^2) metric to compute the misfit function, which is a measure of the
259 inconsistency between the true $\vartheta_i^{obs}(m)$, and predicted, $\vartheta_i^{pre}(m)$ waveforms for a given model (m):

$$\chi_v^2(m) = \frac{1}{v} \sum_{i=1}^{N_d} \left(\frac{\vartheta_i^{obs} - \vartheta_i^{pre}}{\sigma_i} \right)^2 \quad (3)$$

260 where σ_i represents the noise standard deviation determined from ϑ_i^{obs} , as explained by Gouveia and Scales
261 (1998), and v represents the number of degrees of freedom. Using the above stated parameters, the inversion
262 targets the 1-D structure that produces the best fit between the predicted and observed RF. Figure 7 and 8
263 present example results of inversions via density plots of the best 1000 data-fitting S -wave velocity models
264 produced by the NA. The optimum data-fitting model is plotted in red.

265 6 Results

266 6.1 H - κ stacking results for Moho depth and V_p/V_s (including Poisson's ratio)

267 Maps depicting crustal thicknesses and average V_p/V_s in southeast Australia are plotted from the results
268 obtained at 14 stations (Fig. 6 and 9). At the remaining stations, we could not detect any clear multiples or
269 Moho conversions in the RFs from any direction. A previous study by Chevrot and van der Hilst (2000) has
270 noted that this region is devoid of clear multiples. The crustal thickness for all analysed stations in the study
271 area varies from 30.0 ± 2.1 km (BA11) beneath King island in Bass Strait to 39.1 ± 0.5 km (CAN) beneath the
272 Lachlan Fold Belt, and the variation strongly correlates with topography. The associated V_p/V_s values range
273 from 1.65 ± 0.07 (BA11) beneath King island to 1.76 ± 0.04 (YNG) beneath the Lachlan Fold Belt. Crust of the
274 order of 30–34 km thickness occurs beneath much of VanDieland. The mountainous region of the Lachlan Fold
275 Belt has the deepest Moho at 39.1 ± 0.5 km (CAN) and a corresponding V_p/V_s value of 1.73 ± 0.02 . Crust that is
276 ~33 km thick lies beneath the East Tasmania Terrane and Eastern Bass Strait (ETT+EB). Table 2 is a summary
277 of H - κ stacking parameters for the analysed stations.

278 At ~40 km, the crustal thickness beneath the Lachlan Fold Belt is significant, but decreases southward towards
279 VanDieland (~32.5 km) and southeastward towards the East Tasmania Terrane and Eastern Bass Strait
280 (ETT+EB) (~33 km). Overall, the Moho becomes shallower from the southern tip of VanDieland (TAU)
281 towards and into Bass Strait to the north, before becoming deeper once more under the mainland part of the
282 VanDieland microcontinental block (Fig. 6a). The crustal thickness is more or less uniform beneath the Lachlan
283 Fold Belt, East Tasmania Terrane and eastern Bass Strait.

284 The majority of our study region has a low-to-intermediate Poisson's ratio. Poisson's ratio is highest ($0.262 \pm$
285 0.014) in the Lachlan Fold Belt (see Table 2). In VanDieland, the Poisson's ratios generally decrease northward
286 into Bass Strait from 0.240 ± 0.019 (MOO) to 0.210 ± 0.013 (BA11) and then increase into mainland Australia



287 to 0.226 ± 0.017 (TOO). The relatively average to high values in the Lachlan Fold Belt ($0.235 \pm 0.017 - 0.262 \pm$
288 0.014) are in agreement with the presence of a mafic lower crust, as suggested by a number of other studies
289 (Drummond and Collins, 1986; Shibutani et al., 1996; Clitheroe et al., 2000; Finlayson et al., 2002). The ratios
290 in the ETT+EB (0.220 ± 0.008 (BA08) – 0.242 ± 0.005 (BA17)) agree with constraints from seismic reflection
291 and refraction studies and may indicate a felsic to intermediate (average) crustal composition (Finlayson et al.,
292 2002; Collins et al., 2003).

293 6.2 Nonlinear inversion results

294 Results of the NA inversion were successfully obtained for a selection of stations, as shown in Table 2. If the
295 Moho is defined by a gentle velocity gradient, the base of the velocity gradient is used as a proxy for the Moho
296 depth, as done in previous RF (e.g. Clitheroe et al., 2000; Fontaine et al., 2013a) and seismic refraction
297 (Collins, 1991; Collins et al., 2003) studies. We also adopt an upper mantle velocity of $V_p = 7.6$ km/s (i.e. $V_s =$
298 $4.3-4.4$ km/s for V_p/V_s ratios of 1.73-1.77 at the base of the Moho gradient) following Clitheroe et al. (2000)
299 who used this value for RF studies, and Collins et al. (2003) who used $V_p > 7.8$ km/s for their summary of both
300 seismic refraction and RF results; these V_p values are consistent with global Earth models. Therefore, we also
301 require the S -wave velocity to be > 4.4 km/s beneath the Moho. We present the S -wave velocity profiles from
302 the NA inversion for stations CAN, MOO, TOO and YNG in Figs. 7 and 8, together with observed and
303 predicted RFs. The S -wave velocity inversion results of the remaining two stations are included as
304 supplementary material (see Fig. S.10). In assigning the Moho depth, we consider three criteria to examine the
305 quality of the inversion result: (1) misfit value (χ^2); (2) the quality of the RF stack (which is based on our
306 ability to pick the direct and multiple phases); and (3) the visual fit between the synthetic and observed RF.
307 Models that fail to fit significant arrivals in the observed RF are rejected. Based on these criteria, the inversion
308 results are classified as:

- 309 • Very good: very low χ^2 (typically < 0.4), very good visual fit to direct and multiple phases.
- 310 • Good: low χ^2 (typically 0.4-0.8), direct phases clearly visible, multiple phases less clear, and a good
311 visual fit to all major identifiable phases.
- 312 • Poor: medium to high χ^2 (in the range 0.8-1.2), direct phases visible, multiple phases unclear, and
313 moderate visual fit to some identifiable phases. Looking at the character of the crust-mantle transition,
314 this study classifies the transition zone as sharp ≤ 2 km, intermediate 2-10 km or broad ≥ 10 km as
315 initially proposed by Shibutani et al. (1996) and modified by Clitheroe et al. (2000).

316 7 Discussion

317 For convenience, the seismic stations were separated into three groups (Fig. 2 and Table 2) based on tectonic
318 settings and the results obtained. Stations YNG, CAN, CNB, MILA and BA13 are located in the Lachlan Fold
319 Belt; stations BA02, BA11, TAU, MOO and TOO sit above the VanDieland microcontinental block; and
320 stations BA07, BA08 and BA17 lie in the East Tasmania Terrane and Eastern Bass Strait (ETT+EB). This
321 discussion focuses on crustal thickness and the nature of the Moho from $H-\kappa$ stacking and the nature of the crust



322 from V_p/V_s , Poisson's ratio and the 1-D S -wave velocity models.

323 7.1 Lateral variation of crustal thickness and nature of the Moho

324 The RF analysis clearly reveals the presence of lateral changes in crustal thickness that span mainland Australia
325 through Bass Strait to Tasmania. The stations located in the Palaeozoic Lachlan Fold Belt reveals a generally
326 thick crust that ranges from 36.5 ± 4.4 to 39.1 ± 0.5 km. At station CAN, there is a disparity in crustal thickness
327 obtained by the non-linear inversion method (~ 49 km) and H - κ stacking technique (39.1 ± 0.5 km). The reason
328 appears to be that the H - κ stacking analysis assumes that the crust is a single layer with a velocity jump across
329 the Moho, whereas the crust-mantle transition is actually gradual; hence it instead targets a shallower boundary
330 that is not the Moho. Therefore, the deep crustal structure obtained at YNG, CAN and CNB is part of a broad
331 velocity transition zone from crust to mantle. The crustal thickness and Moho transition zone beneath the
332 Lachlan Orogen obtained by the nonlinear inversion method is consistent with previous refraction and RF
333 studies (Shibutani et al., 1996; Clitheroe et al., 2000; Collins et al., 2003; Fontaine et al., 2013a,b). The crustal
334 thickness variations and lack of a clear Moho at the base of the Lachlan Orogen crust may be a consequence of
335 mafic magmatic underplating (e.g. Drummond and Collins, 1986; Shibutani et al., 1996; Clitheroe et al., 2000),
336 sourced from the ambient convecting mantle. This reinforces the opinion of Glen et al. (2002), who suggested
337 that the deep Moho underlying the Lachlan Orogen results from magmatic underplating that added a thick
338 Ordovician mafic layer at the base of the crust coupled with a thick sequence of Ordovician mafic rocks that can
339 be found in the mid and lower crust. Finlayson et al. (2002) and Glen et al. (2002) also inferred the presence of
340 underplating near CNB and CAN from seismic refraction data. Collins (2002) postulated that the underplating
341 might have occurred in the back-arc region of a subduction zone due to pronounced adiabatic decompression
342 melting in the asthenosphere. The seismic tomography model of Rawlinson et al. (2010, 2011) exhibits an
343 increase in P -wavespeed at 50 km depth beneath CAN, CNB and YNG and the authors suggest that magmatic
344 underplating may be the cause of the high velocity anomaly. A recent study by Davies et al. (2015) identified
345 the longest continental hotspot track in the world (over 2000 km total length), which began in north Queensland
346 at ~ 33 Ma, and propagated southward underneath the present day Lachlan Fold Belt and Bass Strait. The
347 magmatic underplating could therefore be a consequence of the passage of the continent above a mantle
348 upwelling leading to a more diffuse crust-mantle transition zone. The thickened crust and a transitional Moho
349 observed in the Lachlan Fold Belt are consistent with the proposed delamination models of Collins and Vernon
350 (1994).

351 Strong lateral changes in crustal structure and/or composition beneath VanDieland appear to be a reflection of
352 the region's complex tectonic history (Fig. 6 and 9). The thick crust (37.5 ± 1.2 km) beneath the Selwyn Block –
353 within the northern margin of VanDieland in southern Victoria – thins (to 30.5 ± 2.1 km) as it enters Bass Strait,
354 yet in southern Tasmania, at stations TAU and MOO, the crust is thicker (33.5 ± 1.9 km). This is reflected in
355 both the NA inversion and H - κ stacking depth estimates where a sharp Moho is observed beneath this region of
356 the study area (Fig. 6 and 9). The Moho depth estimates from RFs at stations TAU and MOO (~ 34 km) is
357 almost identical (~ 35 km) to that deduced by Korsch et al. (2002) from a seismic reflection profile adjacent to
358 the two seismic stations. In contrast, the Bass Strait portion of VanDieland appears to have a relatively thinner
359 crust (~ 30 km). This may indicate thinning of the lithosphere associated with lithospheric stretching and or



360 delamination that resulted from tectonic events that occur post-formation of the Tasmanides (Gaina et al., 1998).

361 Stations BA07, BA08 and BA17 (ETT+EB) collectively indicate crust of uniform thickness (~33 km, Figures
362 9a,b). Relative to western Bass Strait, the crust thickens slightly in this part of the study area, which may
363 suggest underplating associated with a Palaeozoic subduction system (e.g. Drummond and Collins, 1986; Gray
364 and Foster, 2004). Furthermore, our results support the crustal thickness estimates of Tasmania from refraction
365 and wide-angle reflection travel time tomography by Rawlinson et al. (2001). They suggested that the
366 thickening of the crust beneath central northern Tasmania is associated with the suturing of the West and East
367 Tasmania Terranes during the Middle Devonian Tabberabberan Orogeny. The Moho depths we obtained at
368 stations TAU, MOO, BA02 and BA11 which are located within their study area show significant overlap in
369 crustal thickness estimates (Fig. S10 in supplementary material).

370 In general, our understanding of crustal thicknesses variations are limited by station separation, so it is difficult
371 to determine whether smooth variations in thickness or step-like transitions explain the observations.

372 **7.2 Poisson's ratio, V_p/V_s and average crustal composition**

373 Poisson's ratio, which shares an inverse squared relationship to V_p/V_s (Eq. 2) can constrain chemical
374 composition and mineralogy more robustly than P - or S -wave velocity in isolation (Christensen and Fountain,
375 1975). We observe variations in Poisson's ratio (and hence V_p/V_s) across the study region, which we equate
376 with variations in composition. Studies in mineral physics and field observations show (1) a linear increase in
377 Poisson's ratio with decreasing SiO_2 content in the continental crust and (2) partial melt is depicted by an
378 elevated Poisson's ratio (>0.30), especially if the anomaly is localised to an intra-crustal layer (Owens and
379 Zandt, 1997). In terms of V_p/V_s , a more felsic (SiO_2) composition in the lower crust is represented by a lower
380 V_p/V_s , which reflects removal of an intermediate-mafic zone by delamination, whereas a more mafic lower crust
381 is depicted by higher V_p/V_s (> 1.75) which may be due to underplated material (Pan and Niu, 2011). However,
382 lower crustal delamination can also result in decompression melting, which can yield elevated V_p/V_s (He et al.,
383 2015). We interpret the variation of observed Poisson's ratios (0.210–0.256) in the southern Tasmanides to be a
384 consequence of compositionally heterogeneous crust and localised partial melt that may likely be sourced from
385 recent intraplate volcanism (Rawlinson et al., 2017).

386 Figure 6b shows the distribution of bulk V_p/V_s across the study area. Upon comparison with our Moho depth
387 results (Fig. 6a and 9a,b), we find that areas of thick crust (Lachlan Fold Belt) do overlap with areas of higher
388 V_p/V_s ($1.70 \pm 0.04 - 1.76 \pm 0.04$). This may strengthen the argument for mafic magmatic underplating sourced
389 from an ambient convecting mantle (Glen et al., 2002). At MILA, BA13, CAN and CNB, the V_p/V_s values (1.70
390 ± 0.04 – 1.73 ± 0.06) are consistent with mafic granulite (Christensen and Fountain, 1975) which has been
391 suggested to occur in the lower crust based on a wide-angle seismic line that cross-cuts the southern region of
392 the Lachlan Orogen (Finlayson et al., 2002). At station YNG the V_p/V_s value of 1.76 ± 0.04 is consistent with
393 biotite gneisses deduced from seismic reflection experiments carried out across the Junee-Narromine Volcanic
394 Belt in the neighborhood of YNG (Direen et al., 2001).

395 The VanDieland V_p/V_s distribution is rather complex, hence we further divide this block into two separate



396 groups: (1) West Tasmania Terrane (WTT); (2) and the Selwyn block. In the WTT, stations BA02, TAU, MOO
397 (see Fig. 2 for the location) have a moderate V_p/V_s (1.69 ± 0.02 – 1.71 ± 0.04). The bulk V_p/V_s beneath BA02
398 (1.69 ± 0.02) supports a dominantly felsic crustal composition, which means that it is unlikely that the WTT has
399 a mafic lower crust. A felsic crustal composition is at odds with the crustal composition required by the lower
400 crustal flow model of Drummond and Collins (1986); Gray and Foster (2004). Our V_p/V_s measurement from the
401 permanent GSN station TAU (1.70 ± 0.08), agrees well with V_p/V_s value at BA02 which implies a similar
402 crustal composition. Station MOO adjacent to TAU exhibits a similar V_p/V_s value (1.71 ± 0.04) and together
403 this may indicate that the crust is more or less homogeneous in this region. However, the slight variation in
404 V_p/V_s values between station MOO and TAU may be associated with a slight change in bulk composition and
405 the effects of heating following juxtaposition of western and eastern Tasmania during the Middle Devonian
406 Tabberabberan Orogeny.

407 In Bass Strait and south central Victoria (underlain in part by the Selwyn Block), the abrupt variations in V_p/V_s
408 values across stations BA11 and TOO help to underscore the region's complex tectonic evolution. Very few
409 reliable H - κ stacking parameters were observed in this region: one on King Island (BA11) and the other
410 adjacent to the NVP in south central Victoria. This is attributed to low signal quality/difficulty in identifying
411 crustal multiples in this region (Chevrot and van der Hilst, 2000). The presence of a complex and
412 compositionally variable Selwyn Block beneath the stations (Cayley et al., 2002), and melt-induced heating of
413 the crust associated with the Quaternary NVP, may also be contributing factors. The V_p/V_s value at BA11 (1.65
414 ± 0.07) is the lowest in the study area which may imply a lower crustal delamination in Bass Strait, leaving a
415 dominantly felsic crust (e.g. He et al., 2015; Bello et al., 2019b).

416 Station TOO located adjacent to the NVP exhibits a relatively low V_p/V_s (1.68 ± 0.04) that implies a more felsic
417 composition, although mantle upwelling generated by the combined effects of a plume, SDU (shear driven
418 upwelling) and EDC (edge driven convection) (Rawlinson et al., 2017) would likely yield melts of a mafic
419 composition, so the low V_p/V_s may be caused by something else.

420 Despite the fact that crustal composition was possibly altered by recent deformational events that resulted from
421 the break-up between Antarctica and Australia, similar V_p/V_s measurements are generally observed from the
422 southern tip of Victoria through King Island to northwestern Tasmania. This suggests a tectonic relationship
423 between northwest Tasmania and the Selwyn block and appears to support the presence of a coherent
424 Precambrian microcontinental block (VanDieland) postulated by several studies in the preceding ~20 years
425 (Cayley et al., 2002; Cayley, 2011; Moresi et al., 2014; Pilia et al., 2015a).

426 **8 Conclusions**

427 We used H - κ stacking of teleseismic RFs to determine crustal thickness and V_p/V_s ratios; we also generate 1-D
428 S -wave velocity profiles of the crust from 1-D RF inversion in order to investigate the internal crustal velocity
429 structure beneath the southern Tasmanides. We were able to verify the presence of several crustal structures
430 imaged by previous studies (Clitheroe et al., 2000; Finlayson et al., 2002; Glen et al., 2002; Reading et al., 2011;
431 Fontaine et al., 2013a,b) where there is overlap and we have also been able to provide new estimates of crustal
432 thickness and composition. We have also been able to shed fresh light on the different tectonic blocks that



433 constitute southeast Australia. The major conclusions are as follows:

- 434 • The thick crust and broad crust-mantle transition beneath the Lachlan Fold Belt may be caused by
435 magmatic underplating of mafic materials beneath the crust, which is consistent with a relatively high
436 Poisson's ratio (0.262 ± 0.014). Thicker crust is also to be expected from the elevated topography
437 beneath the eastern Lachlan Fold Belt.

- 438 • The crustal structure is complex in VanDieland. It thins from the northern tip of the microcontinent
439 into Bass Strait, yet in southern Tasmania the crust is thicker (33.5 ± 1.9 km) compared to Bass Strait.
440 This scenario may be attributed to the break-up of Antarctica and Australia and the opening of the
441 Tasman Sea which formed three failed rift basins that contain thick piles of sedimentary rocks (Gaina
442 et al., 1998). The thinner crust beneath Bass Strait may indicate that the thinning of the lithosphere is
443 associated with processes such as delamination and/or stretching of the lithosphere during the break-up
444 of the two continents.

- 445 • Stations at ETT+EB collectively indicate crust of uniform thickness (~ 33 km) and an intermediate
446 Moho transition which possibly reflects underplating associated with a Palaeozoic subduction system.

- 447 • It is clear that the nature of velocity anomalies differ between stations on mainland Australia and
448 Tasmania. This highlights contrasting lithospheric structure across Bass Strait ($\sim 40^\circ$ S) with thin
449 lithosphere to the south and thick lithosphere to the north. This sharp transition of lithospheric
450 thickness is in agreement with previous results (Clitheroe et al., 2000) and corresponds to changes in
451 fast *S*-wave polarization directions from primarily northeast-southwest orientations in the north to
452 nearly northwest-southeast directions in the south (Heintz and Kennett, 2005; Pilia et al., 2016; Bello et
453 al., 2019a).

454 Results from this study advance our understanding of the nature and composition of different tectonic blocks
455 that constitute the geology of the southern Tasmanides. These results will also be important for helping to
456 understand the results from other comparable seismic imaging studies and the interpretation of tectonic
457 processes on a wider scale.

458 **9 Data availability**

459 Dataset available at [10.6084/m9.figshare.12233723](https://doi.org/10.6084/m9.figshare.12233723)

460

461 **10 Author contributions**

462 M.B. performed the data analysis and wrote the draft manuscript. N.R and D.C. guided the study and assisted in
463 interpretation. M.B., D.C. and N.R. discussed the results and revised the manuscript. A.R. and O.L. revised the
464 manuscript and assisted with the interpretation.

465 **11 Competing Interests:** The authors declare no competing interests.



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475 al., 2013).

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Table 1: Model parameter bounds used in the Neighbourhood Algorithm receiver function inversion. V_s^{upper} and V_s^{lower} represent the S -velocity at the top and bottom of a layer respectively. V_p/V_s represents P and S wave velocity ratio within a layer.

Layer	Thickness (m)	V_s^{upper} (km/s)	V_s^{lower} (km/s)	V_p/V_s
Sediment	0-2	0.5-1.5	0.5-1.5	2.00-3.00
Basement	0-3	1.8-2.8	1.8-2.8	1.65-2.00
Upper crust	3-20	3.0-3.8	3.0-3.9	1.65-1.80
Middle crust	4-20	3.4-4.3	3.4-4.4	1.65-1.80
Lower crust	5-15	3.5-4.8	3.6-4.9	1.65-1.80
Mantle	5-20	4.0-5.0	4.0-5.0	1.70-1.90

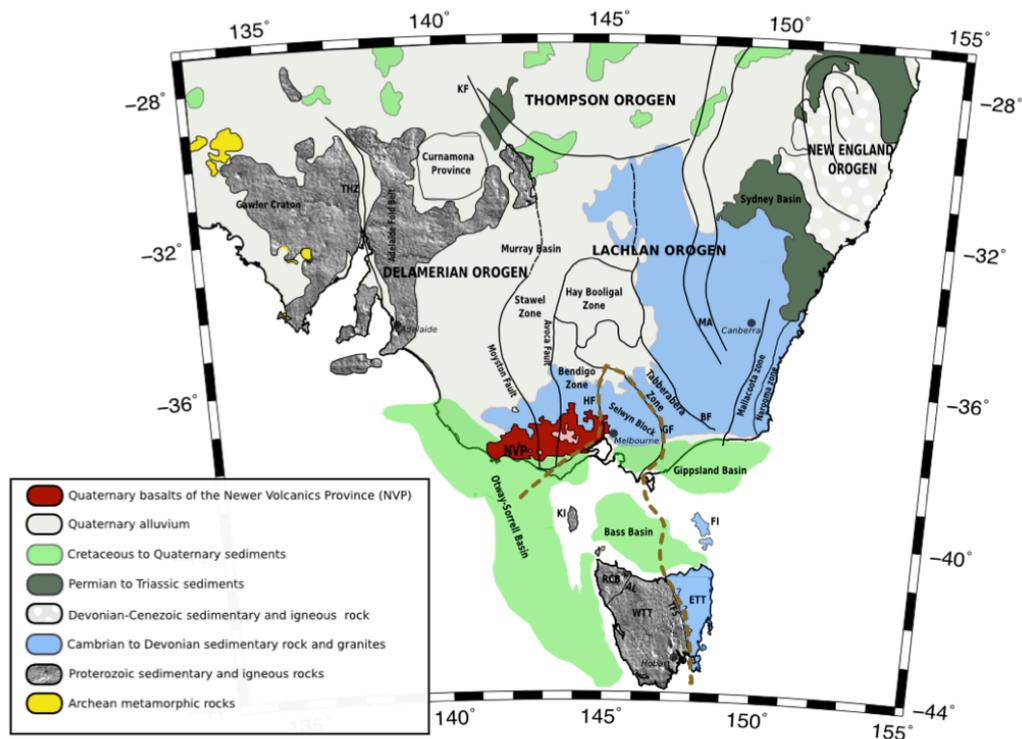
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Table 2: Moho depth, V_p/V_s , Poisson's ratio and nature of the Moho for seismic stations analysed by two different techniques used in this study.

Name	Basic station information				Results				Nature	
	No. of RFs	Lon.(°)	Lat.(°)	Moho depth grid search	Moho depth inversion	Quality inversion	Bulk V_p/V_s	Poisson's ratio (σ)		
VanDieland										
BA02	4	145.20	-40.95	31.4±2.1	-	-	1.69±0.02	0.231±0.017	-	
BA11	12	143.98	-39.64	30.5±2.1	-	-	1.65±0.07	0.210±0.013	-	
TAU	41	147.32	-42.91	33.5±1.9	33	poor	1.70±0.08	0.235±0.036	intermediate	
MOO	58	147.19	-42.44	33.0±1.2	34	good	1.71±0.04	0.240±0.019	sharp	
TOO	276	145.59	-37.57	37.5±1.2	35	good	1.68±0.04	0.226±0.017	sharp	
Lachlan Fold Belt										
YNG	178	148.40	-34.30	37.0±1.2	48	good	1.76±0.04	0.262±0.014	broad	
CAN	402	149.00	-35.32	39.1±0.5	49	very good	1.73±0.02	0.250±0.008	broad	
CNB	155	149.36	-35.32	38.5±1.1	46	good	1.70±0.04	0.235±0.017	broad	
MILA	4	149.16	-37.05	37.6±2.1	-	-	1.73±0.06	0.251±0.023	-	
BA13	6	148.83	-37.63	36.5±4.4	-	-	1.72±0.12	0.245±0.045	-	
ETT+EB										
BA07	5	148.31	-40.43	32.5±0.1	-	-	1.70±0.02	0.235±0.001	-	
BA08	13	147.97	-39.77	34.0±1.2	-	-	1.67±0.03	0.220±0.008	-	
BA17	5	146.33	-39.04	33.2±0.5	-	-	1.71±0.02	0.242±0.008	-	

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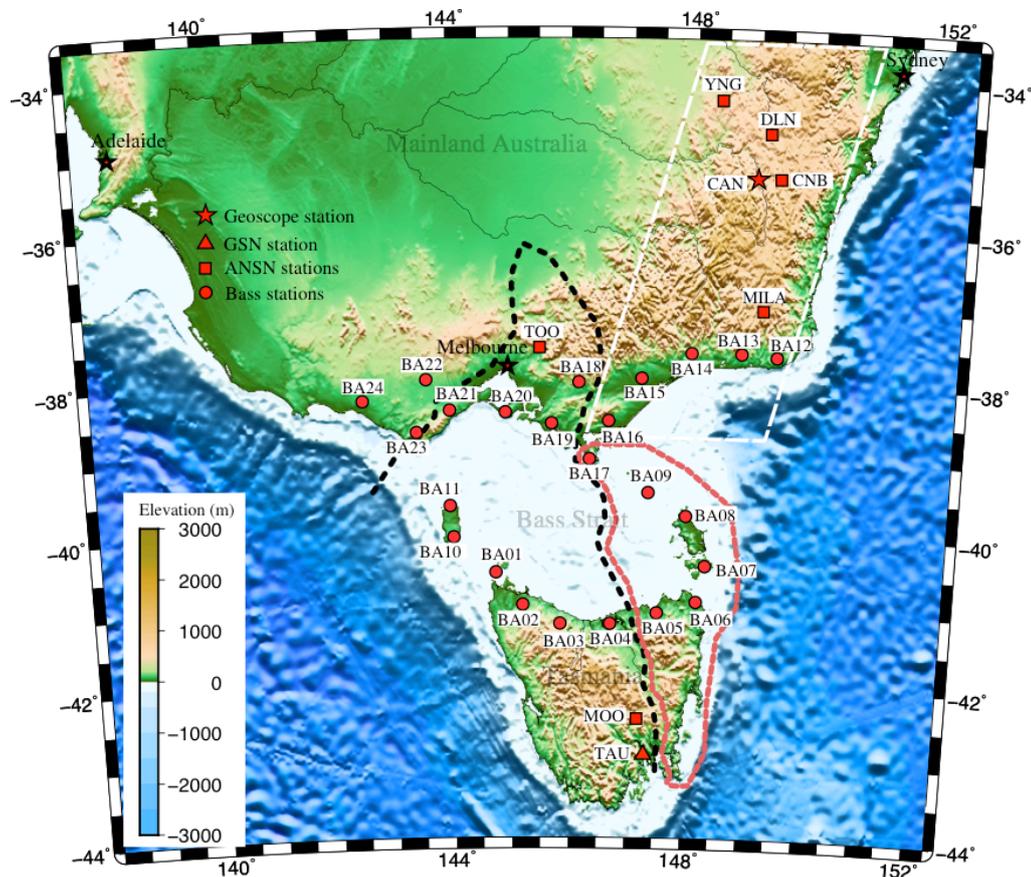
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776 **Figure 1: Regional map of southeastern Australia that shows key geological boundaries and the locations of observed**
 777 **or inferred tectonic units (Modified from Bello et al., 2019a). Thick black lines delineate structural boundaries and**
 778 **the thick brown dashed line traces out the boundary of VanDieland. HF = Heathcote Fault; GF = Governor Fault;**
 779 **BF = Bootheragandra Fault; KF = Koonenberry Fault; THZ = Torrens Hinge Zone; MA = Macquarie Arc; NVP =**
 780 **Newer Volcanics Province; KI = King Island and FI = Flinders Island in Bass Strait; ETT = East Tasmania Terrane;**
 781 **WTT = West Tasmania Terrane; TFS = Tamar Fracture System; AL = Arthur Lineament and RCB = Rocky Cape**
 782 **Block. Outcrop boundaries are sourced from Rawlinson et al. 2016.**

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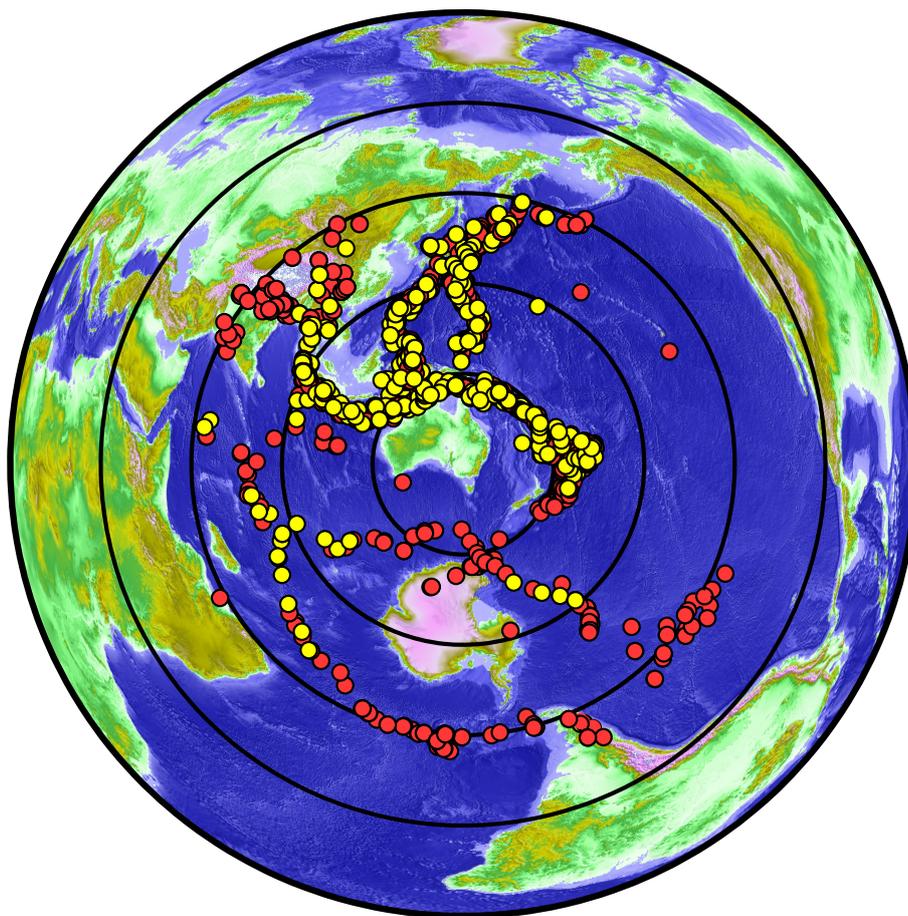
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Figure 2: Location of seismic stations used in this study superimposed on a topographic/bathymetric map of southeast Australia (Modified from Bello et al., 2019a). The boundary of VanDieland is delineated by a thick black dashed line. The boundary of the East Tasmania Terrane and Furneaux Islands is represented by a thick dashed red line, while a thick dashed white line traces out the eastern sector of the Lachlan Fold Belt. Topography/bathymetry is based on the Etopo1 dataset (Amante and Eakins, 2009).



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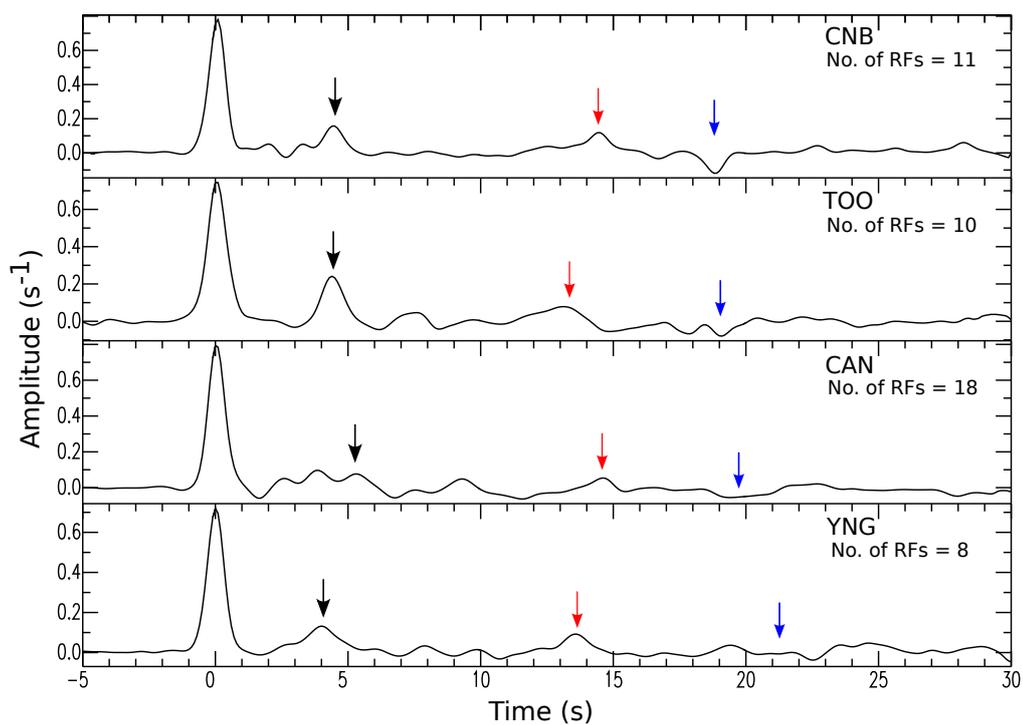
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Figure 3: Distribution of distant earthquakes (teleseisms) used in the study. The locations of events that are ultimately used for RF analysis are denoted by yellow dots. Concentric circles are plotted at 30° intervals from the centre of Bass Strait. Topography/bathymetry is based on the Etopo1 dataset (Amante and Eakins, 2009).

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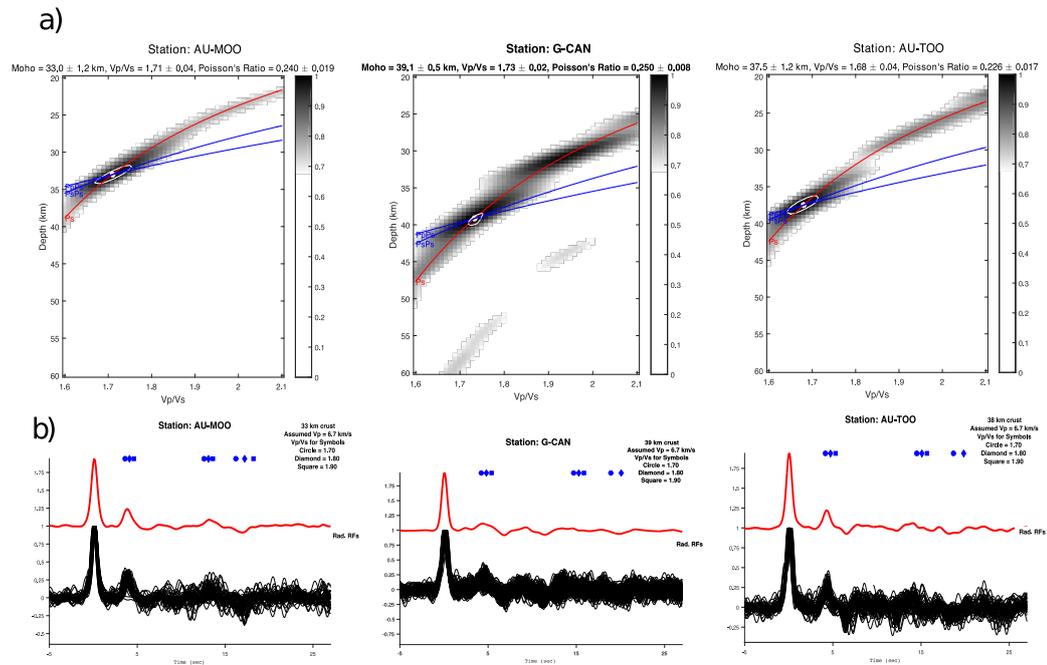
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802 **Figure 4: Stacked receiver functions from Australian National Seismic Network (ANSN) stations TOO, YNG, MOO**
803 **and GSN station TAU. Small arrows indicate arrival of the P_s (black), $PpPs$ (red) and $PpPs + PsPs$ (blue) phases from**
804 **the Moho.**

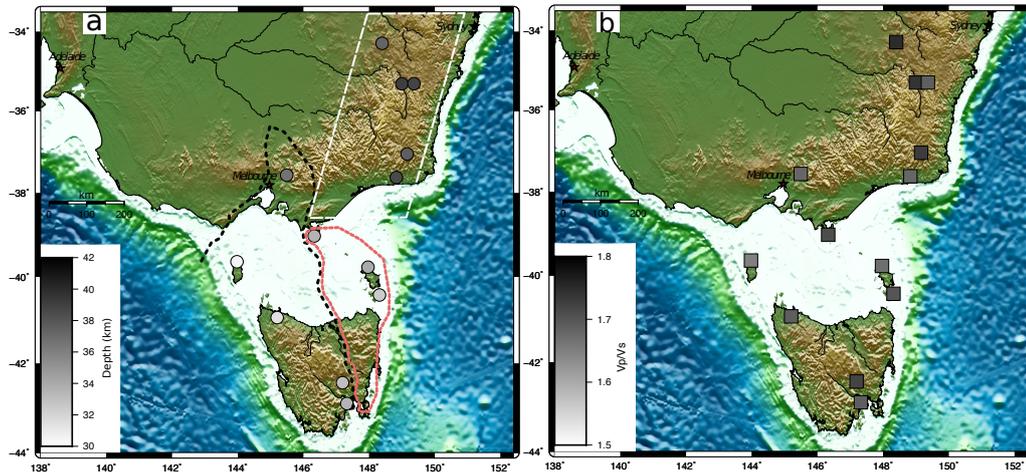
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808 **Figure 5: Results from the $H-\kappa$ stacking analysis for RFs (Zhu and Kanamori, 2000) at stations MOO, CAN and**
809 **TOO. In each case (a) Normalised amplitudes of the stack over all back-azimuths along the travel time curves**
810 **corresponding to the P_S and $P_P P_S$ phases. (b) Corresponding stacked receiver function for each station.**

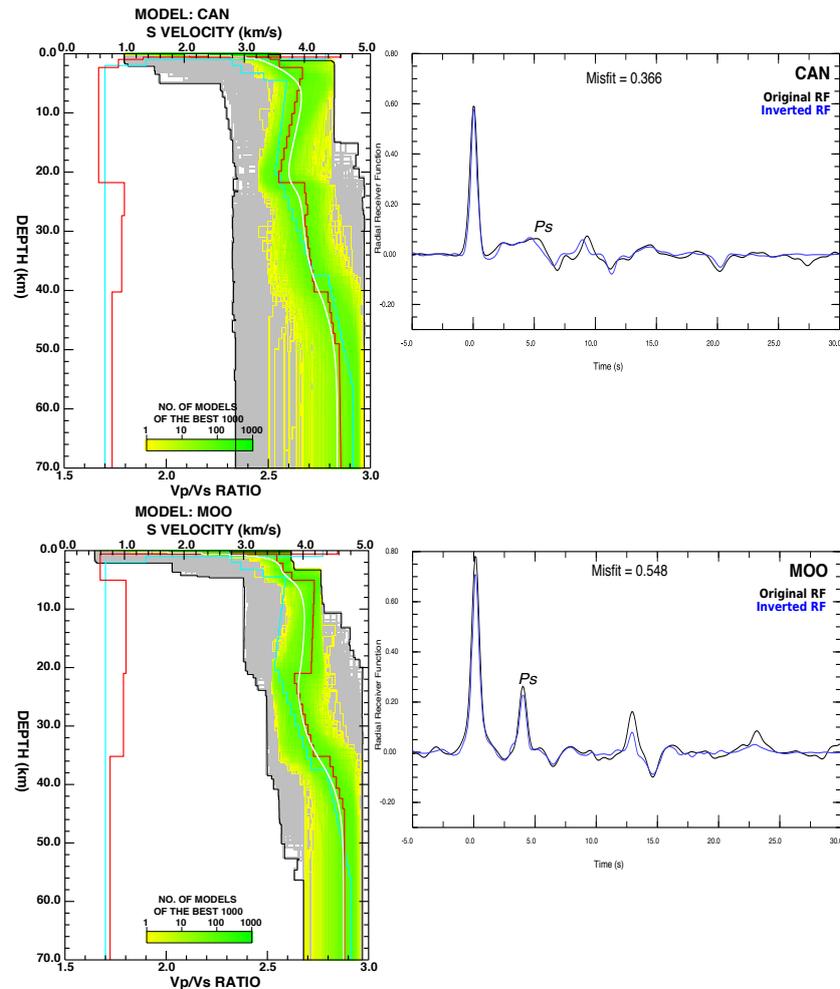
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821 **Figure 6: (a) Variations in crustal thickness and (b) V_p/V_s ratio taken from the linear ($H-\kappa$) stacking results (Table 2).**
822 **Crustal thickness varies between 30.5 ± 0.1 km and 39.1 ± 0.5 km. Thinner crust in Bass Strait can be seen flanked by**
823 **a relatively thicker crust to the north and south. V_p/V_s ratios vary from 1.65 ± 0.02 to 1.75 ± 0.02 . Thick black dashed**
824 **line denotes the boundary of VanDieland. Thick red dashed line outlines the boundary of East Tasmania Terrane**
825 **and eastern Bass Strait (ETT+EB). Thick white dashed line highlights the eastern part of the Lachlan Fold Belt.**
826 **Topography/bathymetry is based on the Etopo1 dataset (Amante and Eakins, 2009).**

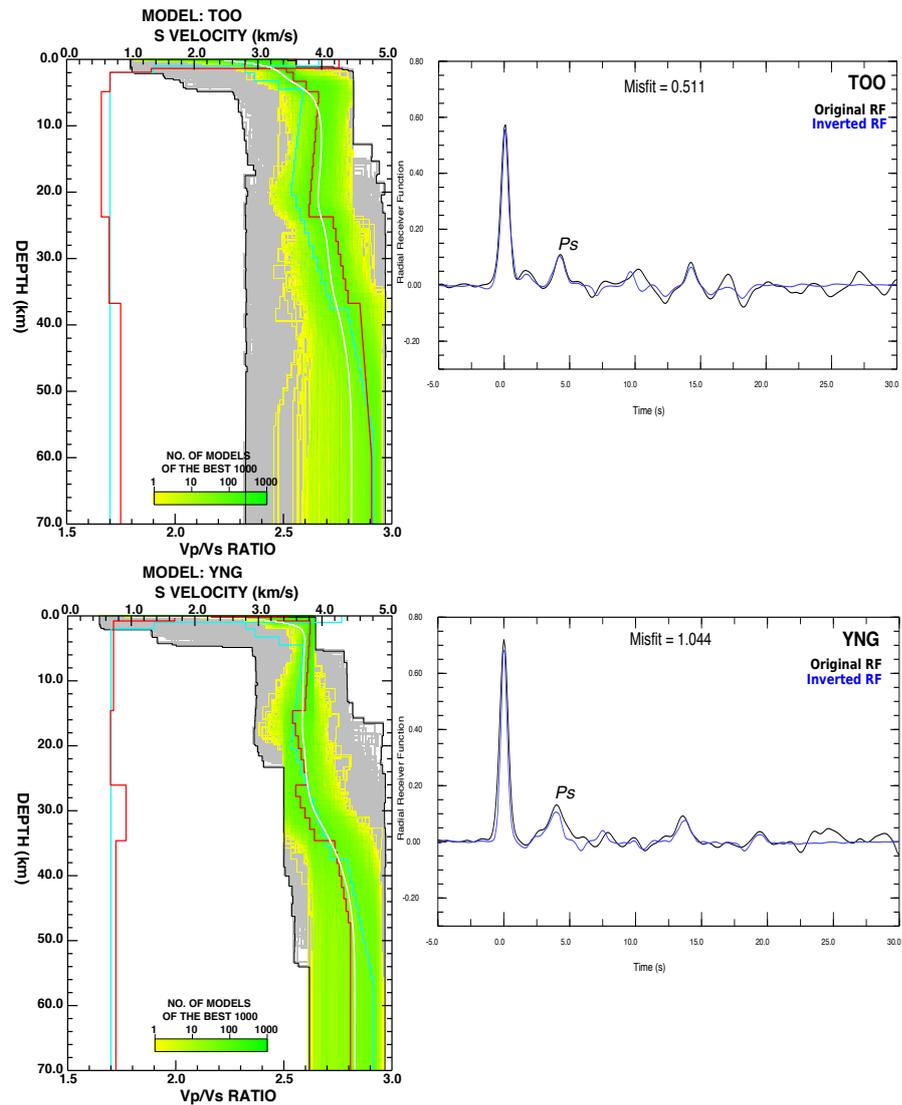
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830 Figure 7: (Left) Seismic velocity models for CAN and MOO stations obtained from the neighbourhood algorithm
831 (Sambridge 1999a). The grey area indicates all the models searched by the algorithm. The best 1000 models
832 are indicated by the yellow to green colours; the best one (smallest misfit) corresponds to the red line, both for S-wave
833 velocity and V_p/V_s ratio and the white line is the average velocity model. (Right) Waveform matches between the
834 observed stacked receiver functions (black) and predictions (blue) based on the best models.

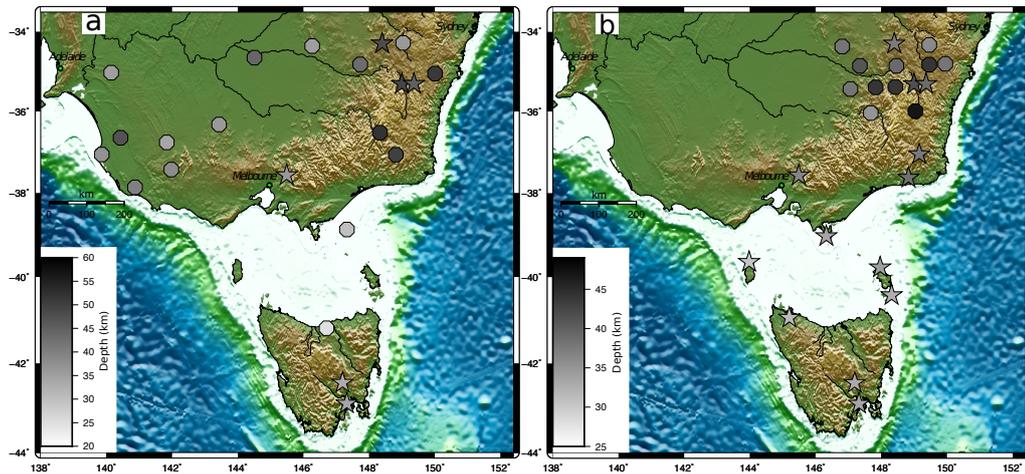
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Figure 8: (Left) Seismic velocity models for stations TOO and YNG obtained from the neighbourhood algorithm. (Right) Comparison between the observed stacked and the predicted receiver functions from the NA inversion. See Figure 7 caption for more details.



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847 **Figure 9:** (a) Map showing crustal thickness variations based on the S-wave velocity inversion results of this study
848 (stars) and previous studies (octagons) (Fontaine et al., 2013; Shubitani, 1996; Collins, 1991) and (b) comparison of
849 crustal thickness variations based on the H - κ grid search results of this study (stars) and previous results from the
850 study of Tkalčić et al. (2012) (octagons). Topography/bathymetry is based on the Etopo1 dataset (Amante and
851 Eakins, 2009).

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