



Postglacial strain rate - stress paradox, example of the Western Alps active faults

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Abstract. The understanding of the origins of seismicity in intraplate regions is crucial to better characterize seismic hazards. In formerly glaciated regions such as Fennoscandia North America or the Western Alps, stress perturbations from Glacial Isostatic Adjustment (GIA) have been proposed as a major cause of large earthquakes. In this study, we focus on the Western Alps case using numerical modeling of lithosphere response to the Last Glacial Maximum icecap. We show that the flexural

- 5 response to GIA induces present-day stress perturbations of ca. 1-2 MPa, associated with horizontal extension rates up to ca. 2.5×10^{-9} yr⁻¹. The latter is in good agreement with extension rates of ca. 2×10^{-9} yr⁻¹ derived from high-resolution geodetic (GNSS) data and with the overall seismicity deformation pattern. In the majority of simulations, stress perturbations induced by GIA promote fault reactivation in the internal massifs and in the foreland regions (i.e., positive Coulomb Failure Stress perturbation), but with predicted rakes systematically incompatible with those from earthquake focal mechanisms. Thus,
- 10 although GIA explains a major part of the GNSS strain rates, it tends to inhibit the observed seismicity in the Western Alps. A direct corollary of this result is that, in cases of significant GIA effect, GNSS strain rate measurements cannot be directly integrated in seismic hazard computations, but instead require detailed modeling of the GIA transient impact.

1 Postglacial strain rate - stress paradox for intracontinental regions

The origins and characteristics of seismicity in Stable Continental Regions (SCR) are an ongoing conundrum in Earth science studies (e.g., Calais et al., 2016; Talwani, 2017). Because Plate Tectonics cannot be the main source of SCR seismicity, the transient stress perturbations of Glacial Isostatic Adjustment (GIA) are commonly considered to explain the recent seismic activity and fault surface ruptures following the Last Glacial Maximum in regions such as Fennoscandia or northern North America (e.g., Hetzel and Hampel, 2005; Steffen et al., 2014; Wu and Hasegawa, 1996). In these regions, the question of the forcing mechanism and its potential rapid decay on a time scale of 103–105 yr is a central issue for understanding the hazards

20 posed by earthquakes up to magnitudes MW = 6-7.

The first-order mechanics associated with GIA-related seismicity involves loading/unloading flexure of the lithosphere, with associated stress perturbations up to a few MPa, sufficient to directly trigger earthquakes on near-failure-equilibrium fault (e.g., Johnston, 1987; Wu and Hasegawa, 1996) or to unclamp faults thus allowing the release of long-term stored tectonic stress (e.g., Craig et al., 2016). Both explanations (shear-stress increment over the failure threshold or normal-stress reduction) rely

25 on the same model (Fig. 1), wherein the initial ice loading results in downward flexure associated with a horizontal compres-





sive stress perturbation in the upper half of the elastic lithosphere beneath the load (and upward flexure / extensive stress in the forebulge regions). Following the deglaciation, the lithosphere unbending is dampened by the mantle viscosity, resulting in a gradual diminution of the compressive stress perturbation. The associated strain corresponds to a maximum shortening at the glacial peak followed by a shortening diminution during the postglacial rebound phase. As a result, the present-day surface strain rate corresponds to an extension rate while the stress perturbation remains compressive. This apparent contradiction is similar to the strain rate - stress paradox observed in subduction zone forearcs in relation with transient interseismic locking of

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the megathrust fault (Wang, 2000).

Owing to the improvements in technology and time series durations, GNSS (Global Navigation Satellite Network) data
allows measuring these small present-day extension rates coupled with vertical uplift rates in regions affected by postglacial rebound from the Last Glacial Maximum (e.g., Johansson et al., 2002; Tarayoun, 2018). Geodetic uplift rates have been classically used to constrain GIA models at global and regional scales (e.g., Mey et al., 2016; Peltier et al., 2015), whereas horizontal strain rates have been compared with seismicity deformation patterns and rates (Mazzotti et al., 2005; Rabin et al., 2018; Sue et al., 2007; Walpersdorf et al., 2018). One of the main goals of the latter comparison is the integration of GNSS velocities and strain rates in seismic hazard models, assuming that these short-term (5–20 yr) strain rates can provide information on long-term (10⁴–10⁵ yr) seismic fault activity. However, in regions of ongoing GIA, the conceptual model presented above and its apparent strain rate - stress paradox lead to strong doubts regarding the usability of GNSS strain rates for comparing with the seismicity. In the following, we test this question using elastic flexure models of the Western Alps to investigate the GIA effects on fault and seismic activity.

45 2 Western Alps: Seismicity and GNSS strain rates

The Western Alps is one of the most seismically active regions in western Europe (Fig. 2a), with several damaging instrumental and historical earthquakes (e.g. Epagny-Annecy, 1996, Mw = 5; Ligurian-Imperia, 1887, Mw = 6.8-6.9; Bale, 1356, Mw = 6.5 (Larroque et al., 2012; Meghraoui et al., 2001; Thouvenot et al., 1998)) and instrumental seismicity that covers the whole Alpine arc (Mw \leq 5, Cara et al., 2015). Strain patterns derived from earthquake focal mechanisms show an overall extension direction perpendicular to the Alpine arc axis in the inner Alps, associated with strike-slip and arc-perpendicular shortening at

- 50 direction perpendicular to the Alpine arc axis in the inner Alps, associated with strike-slip and arc-perpendicular shortening at the periphery in the foreland regions (Fig. 2b; Delacou et al., 2004; Mathey et al., 2021; Sue et al., 1999). A small part of these earthquakes are associated with known structures such as the Belledonne Fault (Thouvenot et al., 2003), the Durance Fault (Cushing et al., 2008) or the Vuache Fault (Rabin et al., 2018; Thouvenot et al., 1998). In contrast, most of the normal-faulting earthquakes in the internal massifs (above the Penninic Front) are not related to known structures (e.g., Sue et al., 2003).
- 55 The present-day Alpine tectonics are primarily controlled by the counter-clockwise rotation of the Adria microplate relative to Eurasia, with a rotation pole directly east of the Western Alps near Turin, northwestern Italy (Fig. 2a; Battaglia et al., 2004; D'Agostino et al., 2008). This kinematics is incompatible with the observed seismicity and geodetic horizontal deformation patterns (Fig. 2). In addition, GNSS data show a relative horizontal motion across the Western Alps below ca. 0.3 mm.yr⁻¹



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(Masson et al., 2019), much slower than the vertical uplift rates that range between 0.5 and 2.5 mm.yr⁻¹ in the inner Western
Alps (e.g., Masson et al., 2019; Nocquet et al., 2016).

In details, the GNSS-derived horizontal strain rate field (Fig. 3) shows Alpine arc-perpendicular extension rates ca. 2×10^{-9} yr⁻¹ in the inner regions (Switzerland, France-Italy border), associated with shortening rates ca. $1^{\circ}2 \times 10^{-9}$ yr⁻¹ in the foreland and surrounding areas from the Upper Rhine Graben to the Jura and Rhone Valley (Masson et al., 2019; Nguyen et al., 2016; Walpersdorf et al., 2018). The southern Western Alps are associated with a complex mix of extension and strike-slip rates ca. $1^{\circ}2 \times 10^{-9}$ yr⁻¹. As shown by the original velocities (Fig. 3a), these signals are at the limit of GNSS detection and resolution and can only be extracted from the background noise using spatial filtering / smoothing technics. The results shown in Fig. 3 are based on a spatial Gaussian filtering with a half-width of 90 km (cf., Masson, 2019), which allows highlighting coherent strain

70 to the Alpine Icecap (cf. Fig. 3 and next section). Details of the Gaussian filtering method and additional strain rate maps at different filtering half-widths can be found in the Supplementary Material A2 to provide an overview of the strain rate patterns and their sensibility to the filtering wavelength.

This overall deformation pattern (slow horizontal extension / extension rates coupled with relatively fast uplift rates) is at the core of the current debate on the processes responsible for the ongoing Western Alps deformation. The role of plate tectonics

rate signals at wavelength of ca. 150-200 km that we consider appropriate for comparison with ongoing GIA deformation due

- 75 being, at best, very small, alternative processes include mantle and slab-tear dynamics (Sternai et al., 2019), surface erosion (Vernant et al., 2013) and Glacial Isostatic Adjustment (Chéry et al., 2016; Mey et al., 2016). Numerical modeling shows that the isostatic response to erosion can generate the observed extensional strain pattern (Vernant et al., 2013), but the associated uplift rates are significantly smaller than the GNSS velocities (Sternai et al., 2019). On the contrary, GIA from the Last Glacial Maximum can explain the present-day uplift rates (Chéry et al., 2016; Mey et al., 2016) but a detailed comparison
- 80 with horizontal deformation is lacking. In the following section, we test the compatibility of GIA models with present-day deformation of the Western Alps

3 GIA models

In order to compare GIA effects with GNSS and seismicity observations, we model the response of the lithosphere to ice loading and unloading using a simple approach of an elastic thin plate over a viscous substratum. The elastic plate flexure wm in response to the ice load is computed with the gFlex code (Wickert, 2016) using the Kirchhoff-Love thin-plate analytic

solution (assuming small inline deformation, zero vertical shear, and plate rotation lower than 10°):

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$$w_m(x,y) = w_{0m}kei(\frac{\sqrt{x^2 + y^2}}{\alpha}) \tag{1}$$

with kei the zero-order Kelvin function, α the flexural parameter (function of the elastic plate thickness T_e and elastic parameters) and w_{0m} the maximum flexure at the center of the load (cf. Turcotte and Schubert, 2014; Wickert, 2016).





90 The ice load model at LGM is from Mey et al. (2016): ca. 600 km long by 200 km wide, locally up to 2 km thick (cf. Fig. 3). The postglacial rebound response is computed assuming an instantaneous ice melt after the Last Glacial Maximum (15000 yr BP) and a simple exponential decay associated with a linear viscosity of relaxation time τ_g (Turcotte and Schubert, 2014):

$$w_m(x, y, t) = w_m(x, y)e^{-t/\tau_g}$$
(2)

This simple 2D planar model is warranted by the relatively small spatial scale of the Alpine ice load. It comprises only 95 two parameters: The flexural parameter α , which depends mainly on the elastic plate thickness T_e , and the characteristic time τ_g . T_e controls the spatial wavelength of the area affected by subsidence, the location of the forebulge and the maximum subsidence value (a higher T_e results in a wider a subsidence area with a lower amplitude). The characteristic time τ_g controls the relaxation speed, i.e., the time to come back to the initial pre-loading state (a higher τ_g results in a longer the postglacial rebound).

- 100 In order to test the variability of GIA predictions to these two parameters, we compute models with $5 \le T_e \le 100$ km and $2000 \le \tau_g \le 20000$ yr. Assuming that GNSS uplift rates are mostly due to GIA, comparisons between observations and model predictions indicate a best-fit parameter set ca. $T_e = 10-20$ km and $\tau_g = 4500-5500$ yr (F-test statistics on residuals). Because GNSS data may be impacted by other processes (cf., above), we allow for a larger range of parameter values $5 \le T_e \le 40$ km and $3000 \le \tau_g \le 7000$ yr. These values indicate a fast and short wavelength response (low mantle velocity coupled with a
- 105 thin elastic plate), in agreement with more complex models (e.g., spatially variable plate thickness) tuned to the Western Alps (Chéry et al., 2016; Mey et al., 2016).

Stress, strain and strain rates in the elastic plate are computed from the second spatial derivative of the flexural response w(x, y, t) (eq. 2) based on the Kirchhoff-Love plate theory (no vertical shear stress, only in-plane compression / tension stress). Although the actual depth and structure of the lithosphere elastic core is unknown, standard rheological models (e.g., Burov

- 110 and Diament, 1995) and the shallow depth of earthquakes in the Western Alps (less than 15km; Cushing et al., 2008; Delacou et al., 2004) indicate that the seismogenic depth range is likely associated with the upper section of the model elastic plate. In order to consider the maximum GIA stress perturbations and strain rate signals, we consider hereafter the stress, strain and strain rate values computed at the top of the elastic plate. More complex situation with a decoupled two-layer elastic plate system would need to be tested with alternative models (e.g., finite element approach, Cattin et al., 2001), but we consider such
- 115 complexity unlikely in the context of a thin elastic plate such as the Western Alps. All the retained models predict similar GIA signals with compressive stress perturbations, shortening strain and extension strain rates in the Western Alps below the LGM icecap. Compressive horizontal stresses at the top of the elastic plate decrease from ca. 20–50 MPa at LGM to ca. 0–5 MPa after 15000 yr (present-day). The associated present-day extension strain rates are ca. $0.5^{\circ}2.5 \times 10^{-9}$ yr⁻¹. Strain rate patterns correspond to primarily NW-SE extension rates in the inner Alps, with shortening
- or strike-slip rates in the Alpine foreland and surrounding regions. These patterns are shown in Fig. 3b for the model with T_e = 20 km and τ_g = 5500 yr as an example. To first order, they are consistent with the horizontal strain rates derived from GNSS data (cf. Fig. 3b vs. 3c). Additional model predictions are shown in the Supplementary Material A3 for illustration.





More specifically, the extension rate area is centered on the LGM icecap extent, approximately 150 km wide in the Central Alps and 300 km wide in the Western Alps. At the Switzerland-Italy border and in the French Alps, modeled and GNSS strain rates are consistent both in direction (rotation from N-S to NNW-SSE) and in amplitudes. In the Switzerland-Italy border area,

- the modeled values range are about $0.9^{\circ}2.1 \times 10^{-9}$ yr⁻¹ while the GNSS data indicates $(2.5 \pm 1) \times 10^{-9}$ yr⁻¹. In the French Alps, the model rates range between 0.4 and 0.8×10^{-9} yr⁻¹ in agreement with the $(0.9 \pm 0.7) \times 10^{-9}$ yr⁻¹ given by the GNSS measurements. Based on these results, GIA accounts for a minimum of 30% and up to 100% of the GNSS extension rates. In contrast, the GIA models are unable to reproduce the GNSS $(0.8 \pm 1) \times 10^{-9}$ yr⁻¹ E-W extension rates in Italy or the
- 130 $(1.5\pm1)\times10^{-9}$ yr⁻¹ strike slip strain rates along the southern France-Italy border. This area being located south of the Adria / Eurasia rotation pole, we propose that these strain rates may be in part related to Adria micro-plate kinematics, consistent with the 0.3 0.8 mm.yr⁻¹ of E-W extension in southern Western Alps (e.g., Nocquet, 2012).

The inner Western Alps extension is surrounded by radial shortening in the Rhine Graben, Jura Mountains and Rhone Valley regions. In the Rhine graben and Jura, the GIA modeled shortening rate directions are consistent with the GNSS strain rates, but

135 the amplitudes are about three times smaller. This suggests that the shortening rates in these regions cannot be solely attributed to Alpine GIA; processes such as Scandinavian postglacial rebound (Nocquet et al., 2005) or a buoyant mantle plume located beneath Eifel volcanic area (Kreemer et al., 2020) may contribute to the shortening signal.

4 GIA stress perturbations on active faults

As expected from the conceptual flexural model (Fig. 1), the GIA stress perturbations correspond to horizontal compressive stress: uniaxial NW-SE compression in southern Switzerland, near-isotropic compression on the French Alps, and E-W uniaxial compression in the Southern Alps (French-Italian border). As previously mentioned, strain rate and stress present opposite signs and these maximum GIA compression (Fig. 4a) are located at the maximum GIA extension rate (Fig. 3c).

The impact of GIA stress perturbations on faults is estimated using the Coulomb failure criterion based on the fault azimuth and dip angle. The Coulomb Failure Stress Δ_{CFS} is computed based on the fault shear and normal stress (e.g., King et al., 145 1994):

$$\Delta_{CFS} = \tau - \mu' \sigma_n \tag{3}$$

with μ' the effective coefficient of friction (between 0.1 and 0.6), τ the shear stress and σ_n the normal stress. The fault-slip style associated with this stress perturbation is given by the rake r:

$$r = \arctan(\frac{\tau_d}{\tau_s}) \tag{4}$$

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with τ_d and τ_s the fault shear stress along dip and azimuth directions, respectively. In all models, these Coulomb Failure Stress and rake represent the effect of the GIA stress perturbations and can be interpreted as GIA favoring a specific fault style





at a given stress level if $\Delta_{CFS} < 0$, or GIA inhibiting fault motion if $\Delta_{CFS} > 0$.

Figure 4b presents the computed rakes for three sets of typical faults in the Western Alps (Fig. 4a): the Vuache Fault, the Belledonne Fault, and a series of potential faults representative of normal-faulting earthquakes in the Internal Massifs above the Penninic Front (hereafter IMNF, Inner Massifs Normal Faults; Sue et al., 2003, 1999). The fault geometries are extracted from the BDFA and neotectonic databases (Grellet, 1993; Jomard et al., 2017). Due to the uncertainties on the dip angles, several values are tested (30–80°). In Figure 4b, the GIA model rakes are shown as boxplots that represent the variability in GIA model parameters (T_e and τ_g) and fault geometries (azimuth and dip). The predicted rakes compared to those derived from earthquake focal mechanisms.

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The GIA Coulomb Failure Stress perturbation depends on the fault geometry and the assumed effective friction (eq. 3). Models with standard friction ($\mu' = 0.6$) and near-vertical fault dips results in negative Δ_{CFS} in dictating that GIA tends to inhibit fault rupture in these cases. In contrast, models with low effective friction ($\mu' = 0.1$) or low fault dips result in mostly positive Δ_{CFS} between 0.1 and 2 MPa. These models are associated with fault-slip rakes corresponding to reverse faulting

- 165 (rakes r = 50-110, Fig. 4b). This faulting style is opposite to that observed in the focal mechanisms along the IMNF (Delacou et al., 2004; Mathey et al., 2021; Sue et al., 1999). For the Belledonne Fault, the GIA stress perturbation favors reverse faulting (r = 60-130) while the focal mechanisms show right-lateral strike-slip ($r = 180 \pm 20$; Thouvenot et al., 2003). The Vuache Fault orientation is strongly oblique to the GIA stress field (Fig. 4a), with the northern part of the fault located in a transition zone where the GIA stress is almost zero. Predicted rakes vary between 60 and 150 (reverse faulting), inconsistent with the
- 170 observed left-lateral faulting style (Rabin et al., 2018). In these three cases, GIA Δ_{CFS} perturbations can reach up to 1–2 MPa, a level commonly considered sufficient to trigger preloaded fault rupture (e.g., King et al., 1994; Steer et al., 2014; Stein, 1999), but the modeled rakes are systematically different from the observed ones. Thus, GIA in the Western Alps cannot explain the kinematics of the aforementioned faults.

The effect of GIA is more difficult to identify for structures parallel to the main stress direction. Along the Durance Fault, in

- 175 the southern Western Alps, the GIA extensive NE-SW stress perturbations decrease from 0.35-0.7 MPa in the area north of the fault to 0.15-0.25 MPa around the southern segment (Fig. 5a). Due to the bends in the Durance Fault trace, the range of predicted rakes is very large for this fault (Fig. 5b). Δ_{CFS} are systematically positive (with low effective friction $\mu' = 0.1$). For the northern half, GIA modeled rakes vary from 0° to 180° indicating that, depending on the fault segment orientation, the kinematics can be reverse, left-lateral, or right-lateral. For the southern half, GIA stress perturbations predict a right-lateral
- 180 strike-slip motion. The focal mechanisms along the Durance Fault system suggest mostly left-lateral displacements (Cushing et al., 2008). Thus, rupture on some segments may be promoted by the GIA stress perturbations, whereas others are clearly inhibited (Fig. 5b).





GIA explains present-day Western Alps GNSS deformation but not seismicity 5

- As shown by several studies in the last decade, GNSS deformation rates in the Western Alps correspond to vertical uplift rates ca. 1–2 mm.yr⁻¹ and horizontal extension rates ca. $(1^{\circ}3) \times 10^{-9}$ yr⁻¹ (e.g., Masson et al., 2019; Walpersdorf et al., 2018). 185 These deformation rates are compatible with GIA signal from the Last Glacial Maximum provided the Western Alps behave mechanically as a thin elastic plate ($T_e = 10-35$ km) over a low viscosity mantle ($\tau_q = 4500-8000$ yr) (e.g., Chéry et al., 2016; Mey et al., 2016, cf. Fig.3). Although the actual contribution of GIA relative to other processes (e.g., slab breakoff, erosion) is debated (Sternai et al., 2019), the good agreement between simple GIA model predictions and the observed GNSS uplift rates and horizontal strain rates suggests that GIA is a major contributor to those observed deformation rates, at least in the region 190
- below the LGM icecap. The compatibility between the GNSS strain rates and the seismicity deformation style has led several authors to consider GNSS data as a constraint on seismicity budget (e.g., Sue et al., 2007; Walpersdorf et al., 2018, 2015). Yet, our analysis shows that GIA stress perturbations in the Western Alps either inhibit fault rupture ($\Delta_{CFS} < 0$) or are inconsistent with the deformation pattern highlighted by earthquake focal mechanisms (cf., Figs. 4 and 5). The overall GIA stress
- 195 perturbations correspond to horizontal compression that would favor reverse to strike-slip faulting styles, opposite to the normal faulting style observed in the region. In fact, Coulomb Failure Stress analyses show that GIA stress perturbations tend to inhibit the observed faulting style for large faults in the Western Alps (such as the Belledonne Fault).
- Our study shows an apparent strain rate stress paradox, wherein GIA can explain the observed most of GNSS strain rates but not the seismicity. This apparent paradox is easily resolved by considering that the observed (and modeled) horizontal 200 extension rates are merely a diminution over time of the compression / shortening induced at surface of the lithosphere by its downward flexure under the LGM ice load. This situation is similar to that observed in the forearcs of subduction zones where a stress orientations and styles may differ from the strain rate patterns, the latter being transient signals due to the interseismic

locking of the subduction fault (Wang, 2000).

A similar situation has been studied by Craig et al. (2016) for Fennoscandia and its early-postglacial reverse-faulting earthquakes. They argue that these reverse earthquakes occurred during a period of GIA extension strain rates, and thus were the 205 expression of compressive stress stored in the lithosphere over a long (tectonic) time. This analysis relies on the assumption that faults are sensitive to the stress rate of change since the LGM (reduction of compressive stress = extensional stress rate), when in fact the full GIA stress perturbation remains compressive throughout the whole glacial cycle (up to present-day), thus promoting reverse faulting earthquakes as proposed by previous studies (Hampel et al., 2009; Steffen et al., 2014; Wu et al., 1999).

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Coming back to the Western Alps case, the opposite style between the GIA strain rates and stress perturbations results in a particular situation. GIA is likely the cause of a large part (over 50%) of the observed geodetic strain rates, but it tends to inhibit the current seismicity and its arc-perpendicular extension. Thus, although it may be tempting to do so, GNSS strain rates cannot be used in seismicity rates or seismic hazard analyses in this context. Our results point out the necessity for an additional

215 mechanism (or several additional mechanisms) that can be the cause of the arc-perpendicular extension pattern expressed in the earthquake focal mechanisms (e.g., Holocene or Quaternary erosion, slab tear, etc.). In this situation, the long-term horizontal





extension stress pattern can be modulated by the GIA stress perturbations, with a reduction of the deformation and earthquake activity during the glacial period and an increase in activity after the glacial maximum (cf. Hampel et al., 2009; Steffen et al., 2014). The integration of GIA stress perturbations in seismicity and seismic hazard studies would thus require mechanical models and cannot be simply based on direct GNSS strain rate integration.

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Code and data availability. Maps have been made with GMT6. Figure 4b and 5b were performed with python 3.6 (Python Software Foundation), as well as models presented in the article. GPS velocities field has been processed by C. Masson using CCRS-PPP (details in Masson (2019)). Flexure is computed from gFlex code (Wickert, 2016) and glex_load code (https://github.com/juliettegroset/gflex_load.git). GPS velocities field has been processed by C. Masson using CCRS-PPP (details in Masson (2019)).

225 Appendix A

A1 Horizontal Velocity field

The velocity field (Fig. A1) is from Masson (2019). The analysis has been made on 1443 permanent stations spread on western Europe in Precise Point Positioning (PPP) from CSRS-PPP software (Kouba and Héroux, 2001). The detail of the method is described in Masson (2019).

230 A2 Gaussian filtering method

The smoothed velocity field is computed on a regular grid (0.5×0.5 degree). The velocity on each grid point is computed from velocity vectors of all GNSS stations, weighted according to their distance with a Gaussian function (Mazzotti et al., 2011). The velocity vector at each point of the grid V_q is defined by:

$$V_{gi} = \frac{\left(\sum_{n=1}^{N} \frac{G_n}{\sigma_{ni}^2} V_{ni}\right)}{\left(\sum_{n=1}^{N} \frac{G_n}{\sigma_{ni}^2}\right)}$$
(A1)

With *i* the component (North, East, Up), *N* the number of stations, V_n the velocity vector at the station *n* and σ the uncertainty of the velocity component. G_n is defined by the Gaussian function parameters r_g (the Gaussian half-width), and Δ_n the distance between stations and grid point:

$$G_n = e^{-\log(2)\frac{\Delta_n^2}{r_g^2}}$$
(A2)

The velocity Gaussian function grid is differentiated to obtain the strain rate tensor at each point. The effect of Gaussian half-width r_g on the noise in the final solution is shown in fig. A2.





A3 Additional models

The variability of tested models (depending on the elastic thickness T_e and the characteristic time τ_{ve}) is investigated in fig. A3 and A4. T_e control the spatial size of the flexure, τ_g control the present-day amplitude of the response. On fig. A4, models (a) and (d) show respectively the maximum and the minimum stress perturbation.

245 *Author contributions.* JG and SM developed the gflex_load code. JG has computed the models. JG, SM, and PV interpreted the results and wrote the article.

Competing interests. The authors declare that they have no conflict of interest.

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Figure 1. Conceptual model of Glacial Isostatic Adjustment (GIA) induced stress, strain and strain.







Figure 2. (a) Instrumental seismicity of western Europe (catalogs: SI-HEX, Cara et al. (2015); SHARE, Stucchi et al. (2013)). Predicted Adria micro-plate motion relative to Eurasia represented along the Adria border. (b) Instrumental seismicity in Western Alps (Cara et al., 2015) and interpreted seismic strain style from focal mechanisms (associated with Vuache fault (Rabin et al., 2018), Belledonne fault (Thouvenot et al., 2003) and old structures such as Penninic Front Thrust faults (Sue et al., 2003, 1999).







Figure 3. (a) Vertical velocity field from GNSS permanent networks (Masson, 2019) and (b) strain rate field extracted from Gaussian Smoothing method (half-width of 90 km); (c) Best-fit GIA model strain rate field ($T_e = 20$ km; $\tau_g = 5500$ yr). Black line is Last Glacial Maximum ice extension (Mey et al., 2016).







Figure 4. (a) Horizontal GIA stress perturbations (model with $T_e=20$ km; $\tau_g=5500$ yr) and fault sets used in the comparison. (b) GIA model rakes (boxplot) and observed rakes (black cross, from Billant et al. (2015); Delacou et al. (2004); Rabin et al. (2018); Sue et al. (1999); Thouvenot et al. (2003))







Figure 5. GIA stress perturbation. (a) Horizontal stress perturbations (model with T_e =20km; τ_g = 5500 yr) and fault used in the comparison. (b) GIA model rakes (boxplot) and observed rake along Durance fault, from south-western to north-eastern border. Observed rake are deduces with focal mechanism (Cushing et al., 2008).







Figure A1. Horizontal velocity field from permanent GNSS network (Masson, 2019). Ellipses represent unvertainties.







Figure A2. Strain rate fields extracted from Masson (2019) velocity field, with Gaussian filtering method with a half-width distance of (a) $r_g = 30$ km, (b) $r_g = 60$ km, (c) $r_g = 9$ 0km and (d) $r_g = 120$ km. Black line is Last Glacial Maximum ice extension (Mey et al., 2016).







Figure A3. GIA modeled strain rate fields (a) $T_e = 10$ km, $\tau_g = 7000$ yr (b) $T_e = 20$ km, $\tau_g = 5500$ yr (c) $T_e = 40$ km, $\tau_g = 5500$ yr (d) $T_e = 40$ km, $\tau_g = 3500$ yr.







Figure A4. GIA modeled stress fields (a) $T_e = 10$ km, $\tau_g = 7000$ yr (b) $T_e = 20$ km, $\tau_g = 5500$ yr (c) $T_e = 40$ km, $\tau_g = 5500$ yr (d) $T_e = 40$ km, $\tau_g = 3500$ yr.