

Looking beyond kinematics: 3D thermo-mechanical modelling reveals the dynamics of transform margins

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Abstract

Transform margins represent ~30% of the non-convergent margins worldwide. Their formation and evolution have ~~long-traditionally~~ been addressed through kinematic models that do not account for the mechanical behaviour of the lithosphere. In this study, we use high resolution 3D numerical thermo-mechanical modelling to simulate and investigate the evolution of the intra-continental strain localization under oblique extension. The obliquity is set through velocity boundary conditions that range from 15° (high obliquity) to 75° (low obliquity) every 15° for strong and weak lower continental crust rheologies. Numerical models show that the formation of localized strike-slip shear zones leading to transform continental margins always follows a thinning phase during which the lithosphere is thermally and mechanically weakened. For low (75°) to intermediate (45°) obliquity cases, the strike-slip faults are not parallel to the extension direction but form an angle of 20° to 40° with the plates' motion vector while for higher obliquities (30° to 15°) the strike-slip faults develop parallel to the extension direction. Numerical models also show that during the thinning of the lithosphere, the stress and strain re-orient while boundary conditions are kept constant. This evolution, due to the weakening of the lithosphere, leads to a strain localization process in three major phases: (1) strain initiates in a rigid plate where structures are sub-perpendicular to the extension direction; (2) distributed deformation with local stress field variations and formation of transtensional and strike-slip structures; (3) formation of highly localized plates boundaries stopping the intra-continental deformation. Our results call for a thorough re-evaluation of the kinematic approach to studying transform margins.

1. Introduction

Transform margins, represent ~30% of the non-convergent margins worldwide (Mercier de Lépinay et al., 2016; ~~Mé~~lody-Philippon & Corti, 2016). Transform continental margin refers to the continent-ocean transition derived from a transform plate boundary that accommodates, or has accommodated, ocean spreading (Basile, 2015; Mascle & Blarez, 1987). ~~Transform continental margins are comprised of transform faults that connect divergent margins~~ Transform continental margins are limited by ~~transform faults connected with divergent margins~~ at both ends. In contrast with continental passive margins, continental transform margins have received limited attention, probably due of their non-cylindrical nature and the steep geometry of the deformed structures that make it difficult to image them with seismic reflection methods.~~their imaging by reflection seismic.~~

39 Kinematic interpretations of transform margins are mainly based on a conceptual model (Basile, 2015;
40 Basile et al., 2013; Mascle & Blarez, 1987; Scrutton, 1979). This conceptual model was first
41 established from ~~seismic lines interpretation~~the interpretation of seismic reflection profiles along the
42 conjugate Equatorial Atlantic margins (Fig. 1) assuming inherited plate boundaries (Mascle & Blarez,
43 1987). It then became more widely used and applied to other plate-continental margins around the
44 world such as the South African margin (Parsiegla et al., 2009), the Antarctic Southern Exmouth
45 Plateau along the South Australian margin (Lorenzo & Vera, 1992), the West Greenland margin
46 (Suckro et al., 2013). This original conceptual model involves the formation of offset intra-continental
47 rift segments linked by a transform fault since the early stages of extension. As a consequence, the
48 whole rift-transform fault system evolves synchronously during continental thinning and oceanic
49 accretion. The onset of oceanic accretion marks the start of the triple junction migration along the
50 transform margin at half the spreading velocity (Basile, 2015; Gerya, 2012). The transform continental
51 margin is then considered active during the migration of the oceanic accretion axis along the
52 continental domain. Whether transform faults originate pre- or syn-rifting or even post-continental
53 break-up is still a matter of debate. However, some oceanic transform faults can form without any
54 continental inheritances as showed by the presence of many transform faults along the mid-oceanic
55 ridges due to the plate kinematics and oceanic lithosphere rheology (Langemeyer et al., 2021). More
56 recently, based on natural examples, Bellahsen et al. (2013) and Basile (2015) highlighted that
57 transform faults can form either synchronously with the syn-rift structures and may reactivate ~~d~~ or
58 cross-cut inherited structures (e.g. Equatorial Atlantic; Gulf of California, Fig. 1), or develop after the
59 oceanic spreading starts, to connect offset oceanic ridges (e.g. Woodlark basin e.g. Taylor et al., 2009).

60 This conceptual model and its offspring based on rigid plate tectonics ~~does~~ not reflect the whole intra-
61 continental deformation phase associated with progressive strain localization and structures ~~s~~ re-
62 orientation (Ammann et al., 2017; Brune, 2014; Brune & Autin, 2013; Mondy et al., 2018; Le Pourhiet
63 et al., 2017). This has first order implications on tectonic plates ~~s~~ reconstructions s and the interpretation
64 of a margin's progressive deformation history. In highly oblique systems, during the intra-continental
65 stage, the relative plate motion between two divergent segments is mostly accommodated by strain
66 partitioning along transfer fault zones (Milani & Davison, 1988). In order to better understand the
67 dynamics of such transform margins, from initiation in continental domains to maturity, it is therefore
68 ~~required-necessary~~ to account for lithosphere physical properties. Both analogue and numerical
69 modelling studies have focused on the formation and evolution of transform continental margins.
70 Different modelling approaches have been used to investigate parameters that control intra-continental
71 deformation and transform margin formation, all of them implying oblique plate motion (rift obliquity
72 controls the orientation and proportion of normal-~~and~~, strike-slip and oblique-slip faults). On the one
73 hand, this obliquity can be either imposed through initial conditions with oblique pre-existing weak
74 zones representing a structural inheritance (Agostini et al., 2009; Ammann et al., 2017; Brune et al.,
75 2012; Clifton et al., 2000; Corti, 2012; Duclaux et al., 2020; Mart & Dauteuil, 2000; Tron & Brun,
76 1991; Withjack & Jamison, 1986) or imposed en-échelon offset weak zones (Allken et al., 2012; Le
77 Calvez & Vendeville, 2002; Liao & Gerya, 2015; Le Pourhiet et al., 2017; Zwaan et al., 2016). On the
78 other hand, obliquity can be set through boundary conditions with oblique extension (e.g. Brune, 2014;
79 Brune et al., 2012; Brune & Autin, 2013; Persaud et al., 2017) or pure shear conditions (Gerya &
80 Burov, 2018; Jourdon et al., 2020; Le Pourhiet et al., 2018) relative to the domain borders.

81 Except in experiments approaching pure strike-slip conditions, models show that the onset of intra-
82 continental deformation ~~always~~ localizes on structures at half the angle of obliquity (i.e. the angle
83 between extension-perpendicular direction and rift trend) closely orthogonal to the extension direction
84 (Brune, 2014; Duclaux et al., 2020; Withjack & Jamison, 1986). Then, depending on the obliquity

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85 (defined as the angle between the plate motion direction and the average rift trend) the deformation
86 evolution differs. Resulting rifts systems are generally classified in three categories: (1) low obliquity,
87 (2) intermediate obliquity and (3) high obliquity.

88 Low obliquity systems are close to orthogonal extension. For models with oblique extension or
89 oblique weak zones it represents angles from 60° to 90° between extension direction and weak zones
90 trend. In models involving offset rifts, low obliquity is reached for offsets of 100 km and less (Allken
91 et al., 2012; Liao & Gerya, 2015; Le Pourhiet et al., 2017). In these systems, the deformation is almost
92 always orthogonal to the extension direction and the developing structures are mainly extensional.

93 Intermediate obliquity is reached in models involving an oblique weak zone or oblique extension for
94 angles of extension between 30° and 60° (Agostini et al., 2009; Brune, 2014; Corti, 2012; Duclaux et
95 al., 2020), while for models with offset weak zones, an offset of 100 km to 300 km is required (Le
96 Pourhiet et al., 2017). In this context, once the continental lithosphere has thinned enough, the
97 rheology of the whole system evolves and the deformation regime changes to reach transtensional
98 deformation. Large scale strike-slip structures develop to connect isolated rift basins segments and
99 accommodate the obliquity strike-slip component of deformation. However, strike-slip structures are
100 not parallel to the extension direction as transform faults are in natural systems.

101 Finally, high obliquity represents systems in which the deformation regime approaches pure strike-slip
102 conditions. These conditions can be reached for obliquities lower than 30° between the rift trend and
103 the extension direction (Agostini et al., 2009; Ammann et al., 2017; Brune, 2014) or offset between
104 rifts larger than 300 km (Le Pourhiet et al., 2017). This highly oblique deformation regime is rarely
105 simulated except in setup with periodic or open boundary conditions, due to a strong limitation in
106 models' setups associated with the use of free-slip boundary conditions on the vertical boundaries of
107 the model. Indeed, free-slip boundary conditions that are generally used for vertical boundaries
108 trending parallel to the extension direction physically prevent deformation in the direction normal to
109 the face (i.e. if free-slip is applied to a boundary of normal x , no deformation can occur in x direction
110 along this border). Therefore, models involving oblique or offset weak zones show that in high
111 obliquity contexts two independent rifts develop and never link (Le Pourhiet et al., 2017) suggesting a
112 natural propensity for segmented rifts systems rather than oblique ones. However, this context seems
113 to be the best candidate to form transform faults parallel to the extension direction segmenting two
114 spreading systems. Indeed, Ammann et al., (2017) showed that a transform fault can develop in a
115 highly oblique weak zone forming an angle of 16° with the extension direction if intense softening is
116 applied. This softening is set in their models through low viscosity magmatism, allowing the viscosity
117 in the weak zone to drop of by 4 to 6 orders of magnitude compared to the surrounding material.

118 Here we investigate numerically the effect of oblique velocity boundary conditions-extension on strain
119 partitioning and localization during early rifting and break-up in the continental lithosphere using non-
120 free slip and oblique boundary conditions and different lower crustal rheologies. We first present high
121 resolution 3D numerical thermo-mechanical models illustrating the evolution of intracontinental
122 rifting processes and strike-slip deformation leading to the formation of transform/strike-slip margins.
123 We then discuss the implication of the crustal rheology on strain localization and strike-slip
124 deformation. Finally, we compare the models' results to emblematic natural examples of transform
125 margins and propose a simplified tectonic evolution model for the formation of transform margins in
126 intermediate and highly oblique extension undergoing intermediate and highly oblique extension.

127 2. Setup for thermo-mechanical numerical modelling

128 2.1. Modelling approach and initial conditions

129 In order to model the long term deformation of the lithosphere we use pTatin3D (May et al., 2014,
130 2015), a highly scalable, massively parallel implementation of the finite element method. It employs
131 an Arbitrary Lagrangian-Eulerian (ALE) discretization together with the material point method to
132 solve the conservation of mass and momentum for an incompressible fluid coupled with energy
133 conservation.

134 The geometry of the modelled domain is 1200 km in the x direction, 600 km in the z direction and
135 250 km in the vertical y direction (Fig. 2a). Two sets of models are conducted: the first set involves ten
136 models with a resolution of 512x256x128 elements while the second set involves three high resolution
137 models of 1024x512x256 elements for a resolution about 1 km x 1 km x 1 km. The initial lithosphere
138 geometry involves four flat layers. The crust is divided into an upper crust from $y=0$ km to $y=-20$ km
139 and a lower crust from $y=-20$ km to $y=-40$ km. The upper crust is simulated with a quartz flow law
140 (Ranalli & Murphy, 1987) when viscous deformation takes place. Since the lower crust rheology is
141 known to have a first order control on strain localization (Allken et al., 2012; Brune et al., 2017; Corti,
142 2012; Jourdon et al., 2020; Le Pourhiet et al., 2017) we conducted all the experiments with two
143 different lower crust rheologies. The “weak” lower crust models involve a quartz flow law (Ranalli &
144 Murphy, 1987) while the “strong” lower crust models involve an anorthite flow law (Rybacki &
145 Dresen, 2000). The mantle is also divided into two layers, the lithosphere mantle (from $y=-40$ km to
146 $y=-120$ km) and the asthenosphere mantle (from $y=-120$ km to $y=-250$ km) that share the same
147 rheology simulated with an olivine flow law (Hirth & Kohlstedt, 2003). To simulate the brittle parts of
148 the lithosphere we use the Drucker-Prager pseudo-plastic yield criterion adapted to continuum
149 mechanics (see equation A5).

150 Table 1: parameters used for the different flow laws in the model

	Units	Quartz	Anorthite	Olivine
Reference		Ranalli and Murphy 1987	Rybacki and Dresen 2000	Hirth and Kohlstedt 2003
A	$\text{MPa}^{-n} \cdot \text{s}^{-1}$	6.3×10^{-6}	13.4637	1.1×10^5
n		2.4	3	3.5
Q	$\text{KJ} \cdot \text{mol}^{-1}$	156	345	530
V	$\text{m}^3 \cdot \text{mol}^{-1}$	0	3.8×10^{-5}	18×10^{-6}

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151
152 The initial temperature field is set with a steady-state analytical solution (Turcotte & Schubert,
153 2002)

$$154 T_{\text{init}} = T_{y=0} + \frac{-yq_m}{k} + H \frac{y_p^2}{k} \left(1 - \exp\left(\frac{-y}{y_p}\right) \right) \quad (1)$$

155 with $T_{y=0} = 0^\circ\text{C}$, an incoming mantle heat flux $q_m = 20 \text{ mW} \cdot \text{m}^{-2}$, a radiogenic heat production $H =$
156 $1.2 \times 10^{-6} \text{ W} \cdot \text{m}^{-3}$, a characteristic radiogenic layer of $y_p = 40 \text{ km}$ and a conductivity of $3.3 \text{ W} \cdot \text{m}^{-1} \cdot \text{K}^{-1}$.
157 With this analytical solution the temperature at the Moho (40 km depth, Fig. 2c) is 610°C and the
158 lithosphere-asthenosphere boundary (1300°C) lies at 120 km depth (Fig. 2c). Then, from 120 km to

159 250 km depths we prescribe a linear increase of the temperature representing an adiabatic gradient of
 160 0.5°C/km (Fig. 2c). Although this second part of the geotherm is not at steady state, the cooling by
 161 diffusivity is very slow (less than 2°C/Myr for the maximum cooling rate) and it ~~allows to~~
 162 ~~keep~~maintains reasonable conductivity values in the asthenosphere (3.3 W.m⁻¹.K⁻¹).

163 The initial radiogenic heat production is set as an exponential decay of heat production with depth
 164 according to Turcotte & Schubert (2002) as follow:

$$165 \quad H = H_0 \exp\left(\frac{-y}{y_p}\right) \quad (2)$$

166 for a surface production H₀ of 1.2x10⁻⁶ W.m⁻³.

167 In order to initiate the deformation in the central part of the model we define three weak zones that
 168 could represent tectonic inheritances in which we prescribe an initial amount of plastic strain that
 169 reduces the friction angle as:

$$170 \quad \varphi = \varphi_0 - \frac{\varepsilon_p - \varepsilon_{min}}{\varepsilon_{max} - \varepsilon_{min}} (\varphi_0 - \varphi_\infty) \quad (3)$$

171 Where φ is the friction angle, φ_0 the initial friction angle (30°), φ_∞ the minimum friction angle
 172 (5°), ε_p the plastic strain and ε_{min} and ε_{max} the minimum and maximum values of plastic strain between
 173 which the plastic strain softening is applied (respectively 0 and 1). The geometry consists in three
 174 ~~cubic~~cuboid ~~damaged~~ zones with ~~a side length of dimension~~ 200 km x 200 km x 100 km and centred
 175 at $x = \{200; 600; 1000\}$ and $z = 300$ km.

176 2.2. Boundary conditions

177 The boundary conditions to solve the conservation of momentum are defined with velocity vectors
 178 oblique to the boundary (Fig. 2b). On faces normal to the z-axis, we impose the same velocity on the
 179 whole face with opposite directions between face z_{min} and face z_{max} . On faces normal to the x-axis, we
 180 impose approximately periodic boundary conditions (Fig. 2b) where the velocity vectors flips 180° at
 181 the centre of the z axis. The angle of extension α is determined as the angle between the velocity
 182 vector and z, the horizontal direction normal to x (Fig. 2b). For every model, ~~s~~ we impose a velocity
 183 vector of norm $\|\vec{v}\| = 0.5$ cm/a on each face. This velocity simulates a total extension rate of 1 cm/a
 184 corresponding to an average of the varying extension rate during the evolution of a rift system. Each
 185 component of the velocity vector is therefore computed as:

$$186 \quad \vec{v} = \begin{pmatrix} v_x = \sqrt{\|\vec{v}\|^2 - v_z^2} \\ v_z = \|\vec{v}\| \cos \alpha \end{pmatrix} \quad (4)$$

187 The basal boundary condition is defined as a constant inflow to compensate the outflow as:

$$188 \quad v_y = \frac{2\|\vec{v}\|.L_x.L_y}{L_x.L_z} \quad (5)$$

189 Where L_x , L_y and L_z are the length of the domain in the corresponding direction.

190 The boundary conditions to solve the conservation of energy are null heat fluxes on vertical
 191 boundaries, $T_{y=0}=0^\circ\text{C}$ and $T_{y=bottom}=1365^\circ\text{C}$.

3. Post-processing

In order to best interpret the tectonic evolution of the oblique rift models we choose to represent the stress inferred deformation regime, the finite strain and the beta factor in map views. We also display cross-sections oriented either perpendicularly to the strike-slip structures or to the extensional ones on which the second invariant of the strain rate tensor is computed as follow:

$$\dot{\epsilon} = \frac{1}{2}(\nabla\vec{v} + \nabla\vec{v}^T) \quad (6)$$

Where $\dot{\epsilon}$ is strain rate tensor and v the velocity vector. The second invariant is then computed as:

$$\epsilon^{II} = \sqrt{\frac{1}{2}\dot{\epsilon}_{ij}\dot{\epsilon}_{ij}} \quad (7)$$

With the Einstein summation convention.

The stress inferred deformation regime is used to determine ~~whether the which is the~~ dominant instantaneous deformation regime ~~knowing as is~~ extensional, transtensional, strike-slip, transpressional ~~and-or~~ compressional. This method has been used in several studies (Brune, 2014; Brune & Autin, 2013; Buchmann & Connolly, 2007; Delvaux et al., 1997; Hergert & Heidbach, 2011; Simpson, 1997) and ~~allows better interpreting facilitates the interpretation of~~ the active tectonic structures. The detailed method is ~~well-expressed described~~ in Brune et al. 2014 ~~in-order-to-compute where~~ the regime stress ratio (RSR) ~~giving-is-computed-as~~ a scalar ranging from 0 to 3 corresponding to a continuous evolution from extension, transtension, strike-slip, transpression and compression. ~~On-In~~ Figures 3, 5, 7 we represented each of these deformation regimes with different colours. The following table 2 ~~displays-shows~~ the upper and lower bounds of each deformation regime.

Table 2: Regime Stress Ratio (RSR) values and corresponding interpretation

RSR value	Strain regime
0 – 0.75	Extension
0.75 – 1.25	Transtension
1.25 – 1.75	Strike-slip
1.75 – 2.25	Transpression
2.25 – 3.0	Compression

The maps of finite strain (Fig. 3, 5, 7) display both plastic strain and the mantle exhumation age ~~when which is indicative of the time when~~ the mantle starts to exhume. The plastic strain is computed as the cumulative deformation over time when deformation occurs under the Drucker-Prager yield criterion (eq. A6). The mantle exhumation age is designed to be compared with oceanic seafloor age or magnetic anomalies. It is computed as the time at which the particles cooled down below 800°C (Jourdon et al., 2020).

On Figures 3, 5, 7, the beta factor represents the crustal thinning as a ratio of the crust thickness at a given time over the initial crust thickness ~~as~~:

$$\beta_n = \frac{hc_{t=n}}{hc_{t=0}} \quad (8)$$

Where β_n is the beta factor at time n , $hc_{t=n}$ is the crustal thickness at time n , and $hc_{t=0}$ is the initial crustal thickness.

224 Figure 11 represents the rift obliquity with respect to the extension direction. In order to compute the
 225 rift obliquity we define two boundaries depending on the beta factor value. The boundary labelled
 226 OCT (Ocean-Continent Transition) corresponds to the highest beta factor value (i.e. the location where
 227 the crust is the thinnest before the ~~mantle starts to exhume~~exhumed mantle) and the ~~boundary lines~~
 228 labelled “necking” ~~is the beta factor equal 2 contour~~ corresponds to the contour of the beta factor value
 229 ~~equal to 2~~. Then we extract discrete points located on these contours and use the dot product between a
 230 vector defined by two points located on these contours (\vec{u}_c) and a vector defining the boundary
 231 condition velocity (\vec{v}_{β}) to compute the angle γ such as:

$$232 \quad \gamma = \cos^{-1} \left(\frac{\vec{u}_c \cdot \vec{v}_{\beta}}{\|\vec{u}_c\| \times \|\vec{v}_{\beta}\|} \right) \quad (9)$$

233 In order to highlight the first order structure orientation we then average the value of γ on rift segments
 234 of 20 km.

235 4. Numerical models results

236 In this study, we conducted ten experiments with a resolution of $\sim 2 \text{ km} \times 2 \text{ km} \times 2 \text{ km}$ per element.
 237 Five simulations with a weak lower crust, and five simulations with a strong lower crust for angles of
 238 extension $\alpha = 15^\circ, 30^\circ, 45^\circ, 60^\circ$ and 75° have been run. From these ten simulations setups three were
 239 selected and run at higher resolution ($\sim 1 \text{ km} \times 1 \text{ km} \times 1 \text{ km}$ per element). The three selected
 240 simulations are weak lower crust; $\alpha = 60^\circ$; and strong lower crust; $\alpha = 45^\circ$ and 15° . These three
 241 models better capture the detailed structures associated with evolution of offset rift basins linked by
 242 strike-slip structures and allow imaging very precisely the progressive formation and evolution of
 243 strike-slip and transform margins. Therefore, we present in details the evolution through time and
 244 space of these three models before summarising the results of all the lower resolution simulations.

245 4.1. Model 1: Weak lower crust, 60° extension

246 Deformation starts to localize around 5 Myr and isolated grabens ~~individualiseform~~. These grabens are
 247 limited by extensional to transtensional en-échélon faults oriented almost perpendicularly ($\sim \text{N}110$) to
 248 the extension direction (Fig. 3a and 4A). From 15 Myr, as strain localizes more intensively in basins,
 249 the en-échélon deformation re-organizes (Fig. 3g and 4C). Newly formed strike-slip faults in shear
 250 zones oriented $\text{N}75$ link the $\text{N}110$ trending normal faults in the basins. The initial normal faults that
 251 are no more active start to rotate clockwise along the diffuse strike-slip structures (Fig. 3h and 3k). A
 252 differential thinning of the crust occurs between strike-slip fault zones and dip-slip deformation zones
 253 leading to basins ~~individualization-formation~~ (Fig. 3i). Then, strike-slip linkage occurs (Fig. 3j) to
 254 form large-scale transfer zones ($\sim 100 \text{ km}$ long; $\sim 50 \text{ km}$ width) between offset basins. The major large-
 255 scale transfer zone is localized along pre-existing damaged zone. Strike-slip shear zones display a $\text{N}60$
 256 ~~surface orientationstrike~~ and a dip of 90° (Fig. 4D and 4E, Cross section b-b') while newly formed
 257 divergent shear zones show a $\sim \text{N}95$ surface orientation. Strike-slip and divergent shear zones form an
 258 angle of 35° between each other and an angle of 30° and 65° with the extension direction. With the
 259 strike-slip strain localization, small regions with transient compressional stress regimes appear in the
 260 strike-slip to divergent transition zones accommodating the clockwise rotation (Fig. 3g and 3j). During
 261 the rifting phase, normal faults formed at the early stages of thinning are passively rotating. As they
 262 approach the strike-slip transfer zones their orientation change through time from $\text{N}110$ (at 5 Myr, Fig.
 263 3a) to $\text{N}10$ (at 30Myr, Fig. 3p) showing a clockwise rotation of $\sim 100^\circ$. Finally, when the mantle
 264 exhumes and ridge accretion takes place (Fig. 3p), the continental lithosphere ~~retrieves-resumes a rigid~~
 265 behaviour and deformation only localizes in the mantle along transfer fault zones oriented $\text{N}80$ to
 266 $\text{N}100$.

267 The final geometry of the continental margins is dominated by divergent segments that are parallel to
268 the exhumation age mantle stripes (i.e., to magnetic anomalies, Fig. 3q), while margin segments
269 located close to strike-slip faults zones are perpendicular to these mantle stripes (Fig. 3q). Offset
270 divergent basins are bounded by strike slip fault zones controlling ridge propagation. The orientation
271 of these segments highlights that the ridge propagation along strike stops until the strike-slip faults
272 zones start to accommodate mantle exhumation. As shown by the evolution of the rift through time,
273 under constant plate kinematics, the active deformation regime changes and re-orient.

274 4.2. Model 2: Strong Lower Crust, 45° extension

275 In this model, the deformation starts to localize as extensional shear zones at the edges of the initial
276 damaged zones (Fig. 5a and 6A). Inside the weak zones, active deformation zones trend perpendicular
277 (~N130) to the extension direction while at the weak zones edges deformation is oriented N110. The
278 stress field ~~evidences shows~~ weak and diffuse compression that accommodates the variation in shear
279 zones orientation ~~variations~~ between damaged zones (Fig. 5a). Areas situated between localized shear
280 zones show a diffuse strike-slip stress field (~200 km wide for a strain rate second invariant of 10^{-18} s⁻²
281]). As thinning progresses, the deformation localizes more intensively in the basins along shear zones
282 oriented N110 (Fig. 5d and 6B). Between the basins, the active deformation is localizing along N70
283 transfer zones with a sigmoidal shape. The shear zones orientation evolves from N90 at the edge of the
284 basins to N70 (Fig. 5d) where elongated lower crustal domes exhume in the transition zones between
285 basins and strike-slip shear zones (Fig. 5e). The associated stress field also display variations from
286 purely strike-slip to transtensional (Fig. 5d). At 10 Myr, the transfer zones show transtensional
287 deformation in the most localized deformation area (Fig. 5d), while at 15 Myr strike-slip deformation
288 dominates (Fig. 5g). Once pure strike-slip deformation takes place in the central part of the transfer
289 zones (from 15 Myr), strain partitioning intensifies. The transfer zones are divided in three domains,
290 (1) the most external domain dominated by pure extension, (2) a transitional domain dominated by
291 transtensional deformation and (3) the central domain dominated by pure strike-slip (Fig. 5g). These
292 three domains are visible in cross-section (Fig. 6C, cross-section a-a' and e-e') where two normal
293 shear zones located on the borders of the transfer zones accommodate the thinning of the lithosphere
294 while in the centre a vertical shear zone accommodates the horizontal displacement. From 18 Myr, a
295 ridge dynamics takes place in the basins (Fig. 5j and 6D) where the deformation is highly localized
296 along two symmetrical shear zones accommodating the oceanic spreading. The transition region
297 between basins and transfer zones displays small en-échelon shear zones with compressional stresses
298 at their tips accommodating local clockwise rotation (Fig. 5j). At 30 Myr, the continental crust in the
299 transfer zones finally breaks up and the oceanic domain display a suite of interconnected basins with
300 sigmoid shapes (Fig. 5q).

301 The final structure of the continental margins (at 30 Myr) shows a spatial repetition of three segments
302 associated respectively with divergent, transtensional and strike-slip kinematics. The divergent
303 segments are parallel to the mantle exhumation age stripes and to the main necking faults located
304 along the initial weak zones (Fig. 5q). Transitional segments, located between the divergent and the
305 strike-slip segments show exhumed lower crustal and mantle domes (Fig. 5q and 6F). The deformation
306 pattern combines strike-slip, extensional and transitory compressional structures formed during the
307 evolution of the rift system. They are related to stress field dynamics with rotation between basins that
308 are mainly divergent and transfer zones that are mainly strike-slip. Finally, the strike-slip segments
309 form the third part of the margins where the mantle exhumed domain is the narrowest. The
310 deformation pattern is relatively simple with a strike-slip shear zone at the centre and only few
311 preserved normal faults in the thinned continental domain.

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312 *4.3. Model 3: Strong Lower crust, 15° extension*

313 In this model, the deformation initiates as a wide and diffuse strike-slip region without clear individual
314 faults or shear zones, excepted along the model borders (Fig. 7a and 8A). At 10 Myr, the deformation
315 already localizes along a central vertical strike-slip shear zone oriented N90 and two surrounding
316 normal shear zones (Fig. 7d and 8B cross-section a-a'). From this stage, the deformation in the central
317 part of the model located between initial damaged weak zones evolves from strike-slip to
318 transtensional and extensional (Fig. 7g and 7j). Basins develop^{ed} in these zones accommodate the
319 maximum vertical displacement (Fig. 7l). At the same time, between and around these basins, the
320 deformation progressively localizes as transtensional to vertical strike-slip shear zones oriented N70 to
321 N90 (Fig. 7j and 8D). Then at 25 Myr the deformation partitions between large scale (~500 km long)
322 strike-slip shear zones oriented N80 and extensional shear zones in between (Fig. 7m and 8E). The
323 strike-slip motion leads to the clockwise rotation of individualized blocks. This rotation produces
324 transient compressive strain in the hinges of the blocks (Fig. 7m and 7p). While during the first
325 deformation phase (from 0 Myr to 20 Myr) the extensional deformation localized along N90 shear
326 zones, during the second phase the extensional structures located between the large scale transform
327 faults display a N105 orientation (Fig. 7m and 7p). Compared to the two previous models, the crust
328 thins slower and at 30 Myr the mantle is not exhumed yet. In addition, the maximum crustal thinning
329 occurs between the initial damaged zones between the strike-slip shear zones. However, the cross-
330 section b-b' (Fig. 8B) following the orientation of the transform faults and crossing the normal faults
331 perpendicularly shows a hyper-thinned margin over ~300 km. The high obliquity of the extension
332 velocity favours horizontal displacements over vertical ones. This results in a relative dextral motion
333 of ~200 km on each transform shear zones in 30 Myr while continental break-up has not yet occurred.

334 The final structure of the continental margins (at 30 Myr) shows three strike-slip dominated shear zone
335 that are parallel to the extensional direction limiting two elongated extensional segments (Fig. 7p and
336 7q).

337 *4.4. Effect of obliquity and rheology on strain localization and rift evolution*

338 Figure 9 shows the results of all 2 km x 2 km x 2 km resolution simulations at 30 Myr. The models
339 ~~results~~ show that for the same extension direction, the rheology of the crust exerts a first order control
340 on the rift evolution and margin final structure. The 75° oblique extension models are drastically
341 different for a strong (Fig. 9q and 9r) and a weak lower crust (Fig. 9s and 9t). Although ~~this model has~~
342 ~~only at~~ the small degree of obliquity, a weak lower crust leaves more freedom in the model for stress
343 rotation in the crust and favours the development of individual offset basins which are linked by
344 transfer fault zone. This transfer fault zone results from the evolution of the en-échelon distributed
345 deformation that progressively localizes as described in ~~the~~ section 4.1 (Model 1). For a strong lower
346 crust, the deformation localizes faster on fewer shear zones and basins develop with a small offset.
347 This strain localization behaviour is different for a direction of extension of 45°. For these simulations,
348 the model with a strong lower crust (Fig. 9i and 9j) develops offset basins while for a weak lower crust
349 (Fig. 9k and 9l) basins are aligned. Finally, for high obliquity ($\alpha=15^\circ$) both strong (Fig. 9a and 9b) and
350 weak lower crust (Fig. 9c and 9d) models show that the strike-slip deformation drives the evolution of
351 the rift and results in large-scale transform shear zones.

352 These results tend to demonstrate that in order to form large scale strike-slip deformation that evolves
353 into strike-slip margin segments, the early formation of offset basins is essential ~~in case with in~~
354 ~~contexts of~~ low to intermediate obliquity. However, in ~~context of important obliquity~~ ~~high obliquity~~
355 ~~cases~~, the strike-slip deformation drives the evolution of the system as soon as the deformation starts
356 to localize.

357 The modelled rift evolution shows that the deformation of the continental lithosphere takes place in
358 three stages. The first stage corresponds to the initiation of the deformation in a rigid plate. For
359 obliquity angles larger than 30° the deformation always initiates along extensional shear zones
360 oriented sub-perpendicular to the extension direction. On the contrary, for obliquity angles below 30°
361 the deformation initiates along strike slip shear zones almost parallel to the imposed velocity field
362 vectors. This behaviour corresponds to the expected strain localization in a rigid plate. However, the
363 second stage of deformation marks significant change in strain-stress regime and strain localization.
364 The timing for the initiation of this second stage may differ depending on the initial rheology of the
365 lithosphere (strong and weak crust) and the angle of extension but it is always observed. During this
366 phase, the stress field changes and the initial shear zones start to re-orient. For angles of obliquity
367 greater than 30° the strike-slip deformation takes place along transfer fault zones to link the offset
368 basins and accommodate the oblique component of the velocity field. Rotation of former faulted
369 blocks is the result of this stress field reorientation at the corner between transfer fault zones and
370 divergent segments, where lower crust exhumation may occur. While for angles of obliquity lower
371 than 30° , the initial strike-slip deformation partitions to later form extensional shear zones that
372 accommodate the vertical displacement. Mechanically, the rheology of the lithosphere evolves from a
373 rigid continuous plate to a weakening domain in which the deformation localizes and temperature
374 increases, which contributes to the weakening of the lithosphere. This deformation stage is transient
375 and evolves to the third deformation stage which corresponds to the formation of a new plate boundary
376 where the deformation is highly localized and partitioned along a continuous shear zone separating
377 again two rigid plates.

378 4.5. Lithosphere thickness evolution

379 Figure 10 shows the evolution through time of the crustal thickness and thinning rate for each model.
380 Thickness evolution curves display the crustal thickness evolution in a selected zone located in a basin
381 (i.e. where the extension is maximal), in a strike-slip transfer zone, and in the transition zone between
382 the basin and the transfer zone. At first order, the thinning of the crust is faster in low obliquity models
383 than in high obliquity models (Fig. 10). Low to intermediate oblique extension models favour the
384 formation of extensional shear zones delimiting large basins between which strike-slip transfer zones
385 develop and therefore the vertical displacements are greater than the horizontal displacements.
386 OppositelyIn contrast, high obliquity extension favours the formation of long strike-slip structures
387 between which small basins develop. In this context the horizontal motion is predominant over the
388 vertical motion and the thinning of the continental crust and lithosphere is-progresses 2 to 4 times
389 slower than under low and intermediate obliquity extension for the same plate velocity. The rheology
390 of the crust also controls the thinning rate since the deformation is more distributed in a weak crust
391 than in a strong crust, a longer time is necessary to achieve the same thinning of the crust.

392 For low to intermediate obliquity models (from $\alpha = 75^\circ$ to $\alpha = 45^\circ$) the thinning of the crust occurs in
393 different phases related to the deformation regime of the lithosphere. The first thinning phase is fast
394 (between 3 mm/yr and 4 mm/yr) and corresponds to the localization of extensional structures. Then,
395 during the second phase (stress re-orientation), while-as the strike-slip structures start to form, the
396 thinning of the crust slows down (between 1 mm/yr and 2 mm/yr). This slowing down is marked by a
397 peak in the thinning rate curves. A delay can also be observed between basins and strike-slip transfer
398 zones where achieving the same amount of thinning can take more time due to the decrease of the
399 vertical velocity component and the increase of the horizontal one in strike-slip shear zones.

400 5. Comparison with previous modelling studies

401 5.1. Strain localization

402 Modelling experiments involving oblique boundary conditions (Brune, 2014; Brune et al., 2012; this
403 study), offset weak zones (Allken et al., 2012; Le Pourhiet et al., 2017; Zwaan et al., 2016), or oblique
404 weak zones (Agostini et al., 2009; Ammann et al., 2017; Corti, 2012; Duclaux et al., 2020) show that
405 strain localization in the continental lithosphere always begins as extensional structures ~~sub-~~
406 ~~perpendicular~~approximately striking at half the angle of obliquity to the extension direction for angles
407 between extension direction and the weak zones larger than $\sim 30^\circ$. Then, as the lithosphere thins and
408 weakens due to mechanical and thermal softening, deformation patterns evolve, and strain is
409 partitioned between extensional and strike-slip segments. Nevertheless, the orientation of these strike-
410 slip segments is not parallel to the imposed plate motion direction, but to local variations of the
411 velocity field. Moreover, the orientation of the tectonic structures changes through time although the
412 global plate motion is kept constant (Brune, 2014; Duclaux et al., 2020; Jourdon et al., 2020;
413 Philippon et al., 2015; Le Pourhiet et al., 2017). For angles of obliquity lower than $\sim 30^\circ$ the models
414 with oblique boundary conditions show that strike-slip deformation dominates (Withjack & Jamison,
415 1986) at the onset of intra-continental rifting. Then, localization leads to strain partitioning between
416 pure strike-slip shear zones and extensional shear zones accommodating a small amount of vertical
417 motion and promoting crustal thinning. However, in these highly oblique cases, the vertical motion is
418 very low and the continental lithosphere thins two times slower than for the same velocity with lower
419 obliquity (Fig. 10) (e.g. Brune et al., 2018). Among the models involving cylindrical boundary
420 conditions but offset or oblique weak zones, this degree of obliquity is never reached due to the free-
421 slip boundary condition. Except in the presence of very efficient mechanical softening processes
422 (Ammann et al., 2017), two rifts develop and never link (e.g. Le Pourhiet et al., 2017). Therefore, to
423 study systems with very high obliquity, models need to take into account limitations associated with
424 the boundary conditions they use.

425 5.2. Obliquity and offset structures

426 Brune et al., (2012)~~and~~, Brune et al., (2018) ~~and~~ ~~(Christian~~ Heine & Brune, (2014) showed that
427 oblique rifting requires less forces than cylindrical rifting during the deformation of the continental
428 lithosphere. However, transform and strike-slip margins do not represent the majority of non-
429 convergent margins (Mercier de Lépinay et al., 2016). Models suggest that the formation of offset
430 structures is essential ~~to for produce~~producing the association of strike-slip or transform segments and
431 divergent segments (e.g. Allken et al., 2012; Ammann et al., 2017; Duclaux et al., 2020; Le Pourhiet et
432 al., 2017; Zwaan et al., 2016). Although the formation of offset structures is intrinsic in models
433 involving offset or oblique weak zones and cylindrical boundary conditions, with oblique boundary
434 conditions the deformation does not necessarily develops offset basins linked by strike-slip shear
435 zones (Brune, 2014; Brune et al., 2012). Thermo-mechanical numerical models involving oblique
436 boundary conditions applied to a uniform lithosphere with one straight weak zone (Brune, 2014;
437 Brune et al., 2012) shows that the deformation localizes to progressively form a unique straight shear
438 zone and straight margins. However, the resolution of these experiments was 3 times lower (in each
439 spatial direction) than in our study, which also contributes to different strain localization patterns.
440 Models conducted in this study have the same oblique boundary conditions but present three separated
441 weak zones rather than a continuous one. These weak zones allow more freedom for structures to
442 develop inside the model and favour the localization of offset structures. For low to intermediate
443 obliquity, they favour the formation of offset basins while for high obliquity they favour the formation
444 of offset strike-slip shear zones. As shown on Figure 9, the offset between structures is essential to
445 facilitate strain partitioning and to form divergent and strike-slip segments. In models where basins

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446 | form aligned ~~to~~-with each other, only one straight transtensional shear zone develops, ~~while~~
447 | ~~where~~whereas in basins (or strike-slip structures) ~~that~~ form with an offset, the deformation partitions
448 | between divergent and strike-slip segments (Fig. 11). A first order implication of this result is that
449 | although oblique rifting may be ubiquitous (Brune et al., 2018; ~~Mé~~lody-Philippon & Corti, 2016)
450 | structural inheritance and previous geodynamic events should play an important role in the initial
451 | localization pattern of offset structures and therefore transform margins.

452 | 5.3. Transform and strike-slip margins

453 | The kinematic conceptual model currently used to interpret and reconstruct the formation of transform
454 | margins (e.g. Basile, 2015; Masclé & Blarez, 1987) has already been questioned by thermo-
455 | mechanical models (e.g. Le Pourhiet et al. 2017). Indeed, our results show that during the intra-
456 | continental oblique rifting phase, the lithosphere does not behave solely as a rigid plate but shear
457 | structures are dynamic, and the deformation pattern changes as deformation progresses. The
458 | continental lithosphere rheology evolves through time in favour of mechanical and thermal softening
459 | (Fig. 12). Therefore, especially for obliquity angle greater ~~that~~-than 30°, it is highly unlikely that
460 | transform margins initiate from already segmented ridge-transform fault-ridge system, but rather
461 | emerge from the progressive evolution of the stress field coupled with local heterogeneities in the
462 | lithosphere. Moreover, although the definition that a transform fault is a strike-slip fault forming a
463 | plate boundary parallel to the plate relative motion, analogue and numerical models suggest that
464 | except for high obliquities, the strike-slip transfer zones formed during continental extension are not
465 | necessarily parallel to the global plate motion (Fig. 11) but to the local velocity field, which contrast
466 | with oceanic transform faults that form parallel to the plates motion (Gerya, 2012, 2013). On the one
467 | hand, for intermediate to low obliquity cases (45° to 75°), the modelled margins that develop strain
468 | partitioning display divergent segments oriented between 90° (orthogonal) and 60°, and strike-slip
469 | segments oriented between 20° and 50° with respect to the imposed extension direction (Fig. 11e to
470 | 11g). These margins present the first order characteristics of transform margins. Indeed, they display
471 | offset basins, strike-slip and divergent segments and rotation of the tectonic structures in the (inner or
472 | outer corner) concave and convex transition zones between the strike-slip and the divergent margins.
473 | On the other hand, the high obliquity margins develop strike-slip faults parallel to the global relative
474 | plate motion. The rift system is no ~~more~~-longer segmented in basins and transfer shear zones but
475 | displays pull-apart basins oriented between 0° and 30° with respect to the extension direction (Fig. 11a
476 | to 11d). Highly oblique systems, also ~~present~~-have very ~~s~~low extension rates (Fig. 10), a rather cold
477 | lithosphere (1300°C isotherm at 120 km while the crust is only few kilometre thick) and small length –
478 | large width basins. Our numerical models show that even a small amount of obliquity in the extension
479 | direction can result in important obliquity of the rift structures and trend (Fig. 11) and therefore
480 | corroborate that “oblique rifting [is] the rule not the exception” (Brune et al., 2018).

481 | 6. Comparison with natural cases

482 | Figure 1 shows natural examples of transform margins formed at different obliquities and presenting
483 | very different structures. Although ~~The~~The numerical models presented in this study are not
484 | specifically designed for particular natural rifts, especially in terms of imposed velocities or tectonic
485 | inheritances. For low to intermediate obliquity rift, the extension rates in the models represent an
486 | average of the natural rifting velocity during the evolution of the system. However, for high obliquity
487 | systems like the Gulf of California, the extension rates in the models are ~5 times lower. As a
488 | consequence, the relatively cold temperature showed in the high obliquity models might be higher in
489 | natural systems and could accelerate the strain localization processes. However, they share first order
490 | similarities with natural oblique rift systems.

491 | ~~Indeed, t~~The Gulf of California shows a rift system with small basins segmented by large scale
492 strike-slip faults and a dynamics very similar to high obliquity extension models. In contrast, the
493 Equatorial Atlantic displays large oceanic basins surrounded by continental margins showing
494 alternating strike-slip transfer zones linking long divergent segments (hundreds of km). The African
495 and South American margins share clearly more similarities with intermediate oblique extension
496 models than highly oblique ones.

497 6.1. Intermediate obliquity rift systems

498 The Equatorial Atlantic margins represent an historic natural case for which the conceptual and
499 kinematic models of transform margins has been established (Basile, 2015; Mascle & Blarez, 1987).
500 The Equatorial Atlantic is part of a larger scale rifting system leading to Gondwana fragmentation and
501 individual offset basins connected by transform faults during the Mesozoic. Continental margins
502 emerging from this major extensional event display individual offset basins connected by transform
503 faults such as the Mozambique-East Antarctica margins (e.g. Thompson et al., 2019), the Central
504 Atlantic margins (e.g. Schettino & Turco, 2009) and the Equatorial Atlantic margins (e.g. Heine et al.,
505 2013). Kinematic reconstructions of the Equatorial Atlantic opening succeed to reconstruct the oceanic
506 opening phase but present gaps, overlaps and misfits of major structures and cratonic bodies for the
507 intra-continental rifting phase. These errors mainly come from the non rigid behaviour of the
508 lithosphere and the locally varying velocity field that cannot be produced in kinematic models. Indeed,
509 our models show that during the intra-continental rifting phase, the stress field, and therefore the
510 structures associated, strongly varies along the rift. However, these variations are not due to ~~plates'~~
511 changes in plate kinematics ~~s-changes~~, as the imposed velocity boundary condition is constant in our
512 models, but to a change in the rheological behaviour of the continental lithosphere. Indeed, while the
513 continental lithosphere behaves as a rigid plate when the deformation is localized along its plate
514 boundaries, the intra-plate strain localization process is characterized by the interactions between
515 brittle and ductile domains of the lithosphere. Moreover, the crustal and lithospheric thinning allows
516 advecting warm material from the exhuming mantle intensifying the non rigid behaviour of the
517 lithosphere by increasing the intensity of ductile deformation. Numerical models show that this is
518 precisely during this intra-continental rifting phase that strike-slip structures form and that rotation of
519 early structures occurs (Fig. 12e) (e.g. Duclaux et al., 2020; Neuharth et al., 2021).

520 In the Equatorial Atlantic rift system, two offset basins (the Central Atlantic basin to the Northwest
521 and the South Atlantic basin to the Southeast) connect in the future Central Atlantic basin forming an
522 East stepping system of dextral strike-slip fault zones (e.g. Heine et al., 2013).

523 Along the Romanche transform fault (Fig. 1b), the finite deformation shows pull-apart basins with
524 various faults orientations and isolated rotated blocks (e.g. Davison et al., 2016; Mascle & Blarez,
525 1987). Numerical models especially display structures rotation at the junction between divergent
526 segments and transfer strike-slip shear zones. The rotation of tilted blocks associated with a horsetail
527 splay is also observed at the junction between transform and divergent plate boundaries in analogue
528 experiments as well (e.g. Basile & Brun, 1999).

529 Finally, the continental deformation along the Romanche Transform fault zone is not a single highly
530 localized strike-slip fault but constitutes a deformation corridor of 40 km to 70 km wide in which
531 normal, reverse, strike-slip faults, or a combination of these are present (Basile et al., 1993; Nemčok et
532 al., 2012). This wide deformation zone in which a main strike-slip structure finally localizes well
533 illustrates the progressive strain localization process as shown in numerical models.

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6.2. High obliquity rift systems

The Gulf of California represents the most compelling example of a highly oblique rift system. ~~In relation with~~ Located south of the dextral San Andreas Fault system, the Gulf of California is an active plate boundary formed in response to the relative motion between the Pacific and North America plates of ~ 5mm/a (Plattner et al., 2007). ~~At ~12 Ma, subduction beneath Baja California ceased. A major change in plate kinematics occurred and a system of highly oblique extension was established as the current plate boundary localized in the Gulf of California ~8-6 Ma. Since ~12 Ma, the cessation of the Pacific plate's subduction beneath the Baja California led to a major change in plate kinematics~~ (Atwater & Stock, 1998; DeMets & Merkouriev, 2016; Lizarralde et al., 2007; McKenzie & Morgan, 1969). ~~This event is responsible of the highly oblique extension in the Gulf of California (Lizarralde et al., 2007).~~ The structural analysis performed on faults and shear zones shows that the average angle between the rift system and the extension direction is ~20° (e.g. Bonini et al., 2019). Moreover, the general trend of normal faults strike in the continental margin shows a NNW orientation while the strike-slip faults display a NW-SE strike, indicating a ~20° difference in ~~orientation.~~ ~~In the exhumed mantle domain~~ In the deep basins of ~~of the northern Gulf of California (where the basement is likely composed of serpentinized mantle, e.g. (J. W. van Wijk et al., 2019), normal~~ oblique-slip faults strike NNE-SSW, ~~perpendicularly to the strike-slip faults~~ (Persaud et al., 2003). Several models were proposed to interpret the ~~changes in the surface deformation evolution~~ geology through time and space in the Gulf of California ~~between from ~12 Ma and to the present day.~~ These models involve two end-members, one implying a progressive change in the deformation regime firstly dominated by extension (between 12 Ma and 6 Ma) and followed by dextral shear (from 6 Ma to present) (e.g. Darin et al., 2016; Spencer & Normark, 1979; Stock & Hodges, 1989) and the other implying a coexistence of strike-slip faults and normal faults since ~12 Ma (e.g. Fletcher et al., 2007; Seiler et al., 2010).

~~The numerical models presented in this study are not specifically designed for particular natural rifts, especially in terms of imposed velocities or tectonic inheritances. However, the~~ The high obliquity numerical model (extension angle $\alpha=15^\circ$) shows striking first order similarities with the Gulf of California rift system and may bring new insights regarding the strain localization in highly oblique rifts such as the Gulf of California. For constant boundary conditions (1 cm/a, 15° obliquity) the strain localizes along normal shear zones forming a ~15° angle with the extension direction located at the boundaries of the rift system while in its central part a large scale strike slip shear zone develops. The deformation regime then evolves to transtension and forms pull-apart basins separated by strike-slip shear zones parallel to the plate motion ~~(e.g. Farangitakis et al., 2021; Persaud et al., 2017; van Wijk et al., 2017).~~ The system then reaches a stable partitioned state with large transform faults in the central part of the rift separating pull-apart basins and normal faults on the edges parallel to the rift trend. Moreover, the high obliquity favours horizontal strike-slip motion over vertical motion resulting in a dextral displacement of 200 km while break-up ~~did has still~~ not occurred ~~yet~~. In the Gulf of California the strike-slip motion since the Miocene (~12 Ma) represents ~~roughly~~ 200 km to 300 km (DeMets & Merkouriev, 2016; Stock & Hodges, 1989) ~~depending on whether the northern or central Gulf are considered, including also the Gulf of California Shear Zone in the slip budget (e.g. Bonini et al., 2019).~~

Therefore, the numerical model tends to show that the deformation could be partitioned since the onset of highly oblique continental rifting, but with a first phase of predominant extension preserved in the continental margin and predominant dextral shear in the nascent oceanic/exhumed mantle domain (Fig. 12a) and a second phase of predominant dextral deformation with pull-apart basins in between (Fig. 12b) followed by the rotation of extensional structures (Fig. 12c).

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581 **Conclusion**

582 Numerical models presented in this study show that:

- 583 - The strike-slip faults responsible for transform margins formation do not form parallel to the
- 584 plate motion except for highly oblique extension ($\alpha > 30^\circ$)
- 585 - En-échelon deformation and offset basins are required to develop strike-slip linkage shear
- 586 zones evolving to transform margin
- 587 - Localized strike-slip shear zones form after normal faults once the lithosphere is already
- 588 thermally and mechanically weakened.
- 589 - The lithosphere weakening leads to stress and strain re-orientation under same kinematic
- 590 boundary conditions

591

592 **Figures captions**

593 Figure 1: a) Simplified structural map of the Gulf of California rift system (modified from Bonini et
594 al., 2019; Ferrari et al., 2018; Fletcher et al., 2007). Large white arrows display the plate motion
595 between the North American plate and the Pacific plate from Plattner et al., (2007). b) Simplified
596 structural map of the Equatorial Atlantic rift system at 110 Ma modified from Heine et al., (2013). FZ:
597 Fault Zone. Half headed black arrows represent the shearing direction.

598 Figure 2: Numerical models setup. a) 3D spatial representation of the model domain with the 3
599 initially damaged zones. b) Schematic representation in map view of the velocity boundary conditions.
600 α is the angle between the velocity vectors and the x direction. c) Yield stress envelopes and initial
601 geotherm of strong and weak lower crust models.

602 Figure 3: Model 1, Weak lower crust, $\alpha = 60^\circ$, map views. Left column: Active strain regime, the
603 intensity of the colours depends on the intensity of the second invariant of the strain rate. The
604 background represents the topography with hill shading. The inset plot represents the strike of shear
605 zones. Central column: Plastic strain computed from equation (A5A6) in the crust and exhumation
606 ages of the mantle below 800°C isotherm. Right column: Beta factor of the crust computed with
607 equation (8).

608 Figure 4: Model 1, Weak lower crust, $\alpha = 60^\circ$. Map views and cross-sections of simulated lithologies
609 and second invariant of the strain rate tensor (equation 7).

610 Figure 5: Model 2, Strong lower crust, $\alpha = 45^\circ$, map views. Left column: Active strain regime, the
611 intensity of the colours depends on the intensity of the second invariant of the strain rate. The
612 background represents the topography with hill shading. The inset plot represents the strike of shear
613 zones. Central column: Plastic strain computed from equation (A5A6) in the crust and exhumation
614 ages of the mantle below 800°C isotherm. Right column: Beta factor of the crust computed with
615 equation (8).

616 Figure 6: Model 2, Strong lower crust, $\alpha = 45^\circ$. Map views and cross-sections of simulated lithologies
617 and second invariant of the strain rate tensor (equation 7).

618 Figure 7: Model 3, Strong lower crust, $\alpha = 15^\circ$, map views. Left column: Active strain regime, the
619 intensity of the colours depends on the intensity of the second invariant of the strain rate. The
620 background represents the topography with hill shading. The inset plot represents the strike of shear

621 | [zones](#). Central column: Plastic strain computed from equation ([A5A6](#)) in the crust and exhumation
622 | ages of the mantle below 800°C isotherm. Right column: Beta factor of the crust computed with
623 | equation (8).

624 | Figure 8: Model 3, Strong lower crust, $\alpha = 15^\circ$. Map views and cross-sections of simulated lithologies
625 | and second invariant of the strain rate tensor (equation 7).

626 | Figure 9: Map view of the 2 km x 2 km x 2 km resolution models at 30 Myrs. The two left columns
627 | display the strong lower crust models while the two right columns display the weak lower crust
628 | models. For each model the second invariant of the strain rate tensor and the plastic strain and mantle
629 | exhumation age are displayed.

630 | Figure 10: Curves of crustal thickness in a), g) basins, b), h) transition zones, c), i) transfer/strike-slip
631 | zones for strong and weak lower crust models. Curves of crustal thinning rate computed as the time
632 | derivative of crustal thickness for d), j) basins, e), k) transition zones and f), l) transfer/strike-slip
633 | zones for strong and weak lower crust models [and different obliquities](#).

634 | Figure 11: Map view of each model representing the angle of the Ocean-Continent Transition (OCT)
635 | and the necking zone with respect to the extension direction. [The background represents the
636 | topography with hill shading. Models with \$\alpha = 15^\circ\$ and \$45^\circ\$ with a strong lower crust and the model \$\alpha\$
637 | \$= 60^\circ\$ with a weak lower crust are high resolution models \(model 1, 2 and 3\).](#)

638 | Figure 12: Schematic simplified evolution of intracontinental deformation leading to the formation of
639 | strike-slip and transform margins for high and intermediate [to low](#) obliquity based on numerical
640 | models results.

641

642

643 **Appendix A**

644 To model the deformation of the lithosphere at geological timescales we use pTatin3D (May et al.,
645 2014, 2015). The code uses an Arbitrary Lagrangian-Eulerian (ALE) discretization with the material
646 point method to solve the conservation of momentum:

$$647 \quad \nabla \cdot (2\eta\dot{\boldsymbol{\varepsilon}}) - \nabla P = \rho\vec{g} \quad (\text{A1})$$

648 where η is the non-linear effective viscosity, $\dot{\boldsymbol{\varepsilon}}$ the strain rate tensor, P the pressure, ρ the density, \vec{g} the
649 gravity acceleration vector. The conservation of mass is solved for an incompressible fluid:

$$650 \quad \nabla \cdot \vec{v} = 0 \quad (\text{A2})$$

651 with \vec{v} as the velocity vector.

652 To consider the interactions between deformation and temperature, the Stokes flow is coupled with the
653 time dependent advection-diffusion energy conservation law:

$$654 \quad \frac{\partial T}{\partial t} + \vec{v} \cdot \nabla T = \nabla \cdot (\kappa \nabla T) + \frac{H}{\rho C_p} \quad (\text{A3})$$

655 where T is the temperature, \vec{v} the velocity vector of the fluid, κ the thermal diffusivity and C_p is the
656 heat capacity. The heat source H is the sum of the radiogenic heat production (eq. 2, in the main text)
657 and the shear heating heat production H_s :

$$658 \quad H_s = \frac{2\eta\dot{\boldsymbol{\varepsilon}}^2}{\rho C_p} \quad (\text{A4})$$

659 According to the Boussinesq approximation the material density may vary with pressure and
660 temperature as:

$$661 \quad \rho = \rho_0(1 - \alpha(T - T_0) + \beta(P - P_0)) \quad (\text{A5})$$

662 where ρ_0 is the initial material density, α the thermal expansion coefficient and β the compressibility.

663 To solve the Stokes flow we use Q2-P1 elements while the energy conservation is solved with
664 a Q1 discretization. The top boundary of the domain is defined with a free surface boundary condition
665 evolving dynamically with the deformation.

666 *Rheological model*

667 The mechanical behaviour of the lithosphere at geological timescales is simulated with a visco-
668 plastic rheology. The brittle parts of the lithosphere are simulated with the Drucker-Prager pseudo-
669 plastic yield criterion adapted to continuum mechanics:

$$670 \quad \eta_p = \frac{C \cos(\phi) + P \sin(\phi)}{\dot{\boldsymbol{\varepsilon}}^{\text{II}}} \quad (\text{A6})$$

671 where C is the cohesion (20 MPa), ϕ the friction coefficient, P the pressure and $\dot{\boldsymbol{\varepsilon}}^{\text{II}}$ the second invariant
672 of the strain rate tensor. To simulate the mechanical softening in brittle faults, we apply a simple linear
673 decrease of the friction angle from 30° to 5° with accumulated plastic strain from 0 to 1 (equation 3 in
674 main text). Moreover, laboratory experiments show that under high confining pressures ($> 1\text{GPa}$)
675 rocks no more behave as brittle but as plastic materials (e.g. Kameyama et al., 1999; Precigout et al.,
676 2007). To consider that change we limit the Drucker-Prager yield stress to a maximum deviatoric
677 stress of 400 MPa according to the findings in Watremez et al. (2013).

678 The ductile deformation is modelled with the Arrhenius flow law for dislocation creep:

$$679 \quad \eta_v = A^{-\frac{1}{n}} (\dot{\epsilon}^{II})^{\frac{1}{n-1}} \exp\left(\frac{Q+PV}{nRT}\right) \quad (A7)$$

680 where A, n and Q are material dependant parameters (see Table 1), R is the gas constant and V is the
681 activation volume.

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686 **Code availability**

687 Models of this study were produced with pTatin (May et al., 2014, 2015), an open source code for
688 geodynamics modelling publicly available at: <https://bitbucket.org/ptatin/ptatin3d/src/master/>.

689 **Authors contribution**

690 Anthony Jourdon designed, ran and post-processed the models, wrote the manuscript and produced the
691 figures. Charlie Kergaravat and Guillaume Duclaux contributed to results discussion and
692 interpretation, figures production and writing of the manuscript. Caroline Huguen contributed to the
693 conceptualization of the study.

694 **Competing interests**

695 Three of the authors were or are employed by the energy company TOTAL S.A. Models computing
696 was done on TOTAL's Pangea supercomputer.

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